

# Motion correction of chemical exchange saturation transfer MRI series using robust principal component analysis (RPCA) and PCA

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**Background:** Chemical exchange saturation transfer (CEST) MRI requires the acquisition of multiple saturation-weighted images and can last several minutes. Misalignments among these images, which are often due to the inevitable motion of the subject, will corrupt CEST contrast maps and result in large quantification errors. Therefore, the registration of the CEST series is critical. However, registration is challenging since common intensity-based registration algorithms may fail to differentiate CEST signals from motion artifacts. Herein, we studied how different patterns of motion affect CEST quantification and proposed a cascaded two-step registration scheme by utilizing features extracted from the entire Z-spectral image series instead of direct registration to a single image.

**Methods:** The proposed approach is conducted in two stages: during the first coarse registration, the Z-spectral image series is decomposed by robust principal component analysis (RPCA) to separate CEST contrast from motion. The recomposed image series using only the low-rank component, which contains minimized motion, are averaged to generate a reference for the alignment of the image series. To further remove residual misalignments, the coarse registration is followed by a refinement stage, which uses PCA iteratively to generate motionless synthetic reference series with the first few principal components (PCs) that correspond to CEST contrast. In the end, the quality check is performed to exclude the images with unsuccessful registration.

**Results:** The proposed registration scheme (RPCA + PCA\_R) was assessed by both phantom experiments and *in vivo* data of tumor-bearing mouse brain, with simulated random rigid motion in different patterns applied to the acquired static Z-spectral image series. For comparison, previous correction schemes using an explicit image [either S<sub>0</sub> or S<sub>sat</sub>( $\Delta\omega$ )] as registration reference were also performed, named as S<sub>0</sub>R and S<sub>sat</sub>. R respectively. To illustrate the advantage of combination of RPCA and PCA, registration was also exploited using either only the RPCA-based method (RPCA\_R) or only the PCA-based one (PCA\_R). Compared with the above four methods, RPCA + PCA\_R allowed for more accurate correction of the corrupted Z-spectral images, exhibiting smaller MTR<sub>asym</sub>( $\Delta\omega$ ) error maps and lower residual Z-spectra referring to the static data. Among all the five correction methods, the corrected Z-spectral image series by RPCA + PCA\_R and the resulting MTR<sub>asym</sub>( $\Delta\omega$ ) maps achieved the highest correlation coefficients (CC) with respect to the static ones.

**Conclusions:** The registration scheme of RPCA + PCA\_R provides robust motion correction between two specific Z-spectral images and among an entire image series, through extraction of the static component from the entire Z-spectra set and inclusion of a PCA-based refinement step. Therefore, this method can help improve CEST acquisition and quantification.

**Keywords:** Chemical exchange saturation transfer (CEST); motion correction; principal component analysis (PCA); robust principal component analysis (RPCA)

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# Introduction

Chemical exchange saturation transfer (CEST) MRI is an alternative contrast mechanism that indirectly detects biomolecules by probing their exchangeable protons with a frequency-specific saturation pulse. Through multiple chemical exchanges, the saturation signal transfers to bulk water and is amplified for detection (1). CEST MRI has been shown to be able to map certain dilute metabolites such as creatine (2), glucose (3,4), salicylic acid analogs (5), and changes in microenvironment properties, like temperature (6) and pH (7-9), which are promising in a host of applications in cancers and neurological diseases (10-20).

To observe the CEST effect, a series of images of the bulk water is acquired as a function of saturation frequency offsets ( $\Delta\omega$ ), called Z-spectra data. The most-commonly used CEST quantification method is asymmetry analysis on the magnetization transfer ratio (MTR<sub>asym</sub>) (21). MTR<sub>asym</sub> takes the difference between two saturation-weighted images at opposite offsets (+/- $\Delta\omega$ ), then normalizes by S<sub>0</sub> image (without saturation pulse applied), as described below:

$$MTR_{asym} = \frac{S_{sat}(-\Delta\omega) - S_{sat}(+\Delta\omega)}{S_0} \bullet 100\%$$
[1]

To achieve higher spectral resolution and sample adequate  $\Delta\omega$ 's of interest, acquisition of Z-spectra usually lasts several minutes. The inevitable motion of subjects, however, can seriously affect CEST contrast maps and quantification, especially for voxel-by-voxel analysis. Even if individual images are motion-free, any misalignments among CEST images can easily corrupt Z-spectra and MTR<sub>asym</sub> quantification by introducing signal variations (peaks or dips) that resemble those expected from the molecules of interest (22). The MTR<sub>asym</sub> image can also easily get distorted, usually due to the motion-induced misalignments among S<sub>sat</sub>(+ $\Delta\omega$ ), S<sub>sat</sub>(- $\Delta\omega$ ), and the S<sub>0</sub> image for normalization. Therefore, the application of a proper registration algorithm is critical for CEST analysis, directly affecting image quality and quantification (12,23-32).

However, image registration for Z-spectral image series imposes two challenges. Firstly, images at different  $\Delta \omega$  inherently possess variable signal intensity via CEST contrast, compromising intensity-based registration algorithms. To register images with varying intensities, the pair-wise approach is generally used with a dissimilarity metric such as the sum of squared difference (SSD), correlation coefficient (CC), and mutual information

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(MI) (33). Still, with such conventional strategies, it is difficult to distinguish intensity changes induced by CEST contrast and motion. Secondly, the selection of a reference image for the alignment of other images is an important step in the context of CEST analysis. Several previous studies have taken S<sub>0</sub> image as the reference image (24-29). But, since the intrinsic contrast of  $S_0$  is considerably different from other saturated images, registration results are poor (32). For amide proton transfer (APT) imaging that is quantified by  $MTR_{asym}(3.5 \text{ ppm})$ , the 3D human brain data has suggested the use of a saturated image at 3.5 ppm as the registration reference can yield best quality (32). However, when different or multiple offsets are of interest, the selection of reference image(s) needs to be optimized again. Instead of a single reference image, one recent method generated a corresponding reference for each saturation image at  $\Delta \omega$ , using the low-rank approximation of the Z-spectral images, termed as LRAZ. Despite that the low-rank components containing less motion, LRAZ exploits singular value decomposition (SVD) and the level of separation between motion and CEST signal strongly depends on regularization parameters, which needs to be tuned in a heuristic manner (34). In addition to the above methods that registered CEST images post-acquisition, CEST imaging sequence can be modified by including navigators, enabling real-time corrections of motion, and shimming during acquisition (22).

Previously, dynamic contrast enhancement (DCE-) MRI has developed methods for distinguishing signal intensity changes due to contrast enhancement from those corresponding to motion. A progressive principal component registration method (PPCR) gradually removes motion for both liver and breast DCE-MRI (35,36). This method is based on the iterative use of principal component analysis (PCA) to create a synthetic reference series that is free from motion but preserves contrast enhancement. However, the ability of PCA to separate motion from contrast enhancement breaks down when the image series contains a large amount of motion. Another robust data decomposition registration algorithm (RDDR) separates contrast enhancement and motion by assuming that the sparse component is attributable to contrast changes and the low-rank is attributable to motion after applying robust principal component analysis (RPCA), allowing iterative re-alignment of the liver, small bowel, and prostate DCE-MRI (37). More recently, a robust non-rigid motion correction approach was proposed for myocardial perfusion MRI, which consists of RPCA and non-rigid image registration (38). However, DCE pharmacokinetics



Figure 1 Illustration of the scheme for motion correction in CEST MRI, including a coarse registration step, a refinement registration step, and a quality check module at the end. CEST, chemical exchange saturation transfer.

and CEST Z-spectra have different features. In DCE-MRI, the contrast agent directly changes tissue relaxation and causes significant and rapid variation of the signal. In CEST experiments, especially for the endogenous CEST, the variation in CEST signal is smooth when compared to motion which results in rapid signal variation. Based on this characteristic, CEST contrast is assumed to be separated from motion by RPCA. However, it is difficult for RPCA to differentiate these two perfectly, and residual motion needs to be further considered.

Herein, we introduce a two-stage motion correction approach specifically designed for Z-spectral image series, which consists of RPCA-based coarse registration and PCA-based refinement registration, together called "RPCA + PCA\_R". Our hypothesis is that RPCA + PCA\_R allows for a robust capability in achieving accuracy registration for various motion scenarios of Z-spectral image series.

#### Methods

# Theory

# **Registration scheme**

Motion correction is conducted in a two-stage scheme (*Figure 1*). Coarse registration accounts for bulk motion, where the Z-spectral image series is decomposed by

RPCA to robustly separate CEST contrast from motion, achieving to minimize motion component in the reference image. Then, refinement registration gradually removes the remaining small misalignments by using PCA for the iterative generation of a motionless reference series. To ensure registration quality, a quality check is finally performed.

#### Stage I: coarse registration

A matrix of vectorized images M can be decomposed into a sum of the sparse component (S) and the lowrank component (L) in the context of simultaneous image alignment (39). The portion of images that cannot be described by L is allocated to the S part. Hence, L can be interpreted as correlated information among images, which is not constant but rather smooth and global changes between frames, while S captures dynamic information introduced in each subject, which is rapid with local intensity changes. Such matrix decomposition can be solved by RPCA and formulated as an optimization problem to recover L and S from the input data (40):

$$\{L^*, S^*\} = \underset{L, S}{\operatorname{argmin}} (\|L\|_* + \lambda \|S\|_1)$$
  
subject to  $M = L + S$  [2]

where  $\| \|_{*}$  denotes the nuclear norm (i.e., the sum of the

matrix singular values) and  $\|\|_{l_1}$  denotes the  $l_1$ -norm (i.e., the sum of the absolute values of the matrix). The tradeoff parameter ( $\lambda$ ) corresponds to rank of L: for high values, most information will appear in L with a large rank while S will be empty, and vice-versa. The optimal {L\*,S\*} can be efficiently computed through an augmented Lagrangian multiplier method using alternating direction approach (ADM) (41).

The information in the Z-spectral image series can be regarded as a combination of smooth CEST contrast changes and rapid motion variation. We hypothesize that RPCA decomposes the Z-spectral image series into L, corresponding to CEST contrast, and S, containing the motion. The Z-spectral image series with x×y voxels at  $N_f$  different  $\Delta \omega$  is converted to a (x-y by  $N_f$ ) Casorati matrix M and then decomposed by RPCA with suitable  $\lambda$ . Next, a series of pair-wise registrations are performed, in which the average image of the low-rank series is used as reference for the whole input series, resulting in the coarse registered series having bulk motion eliminated. Specifically, to minimize the contribution of motion in the reference image,  $\lambda$  is adjusted experimentally so that most motion is incorporated into S. Alternatively,  $\lambda$  can be chosen independent of the application and the nature of data (Candès value,  $\lambda_0$ ) (40) :

$$\lambda_0 = \frac{1}{\sqrt{\max(\mathbf{x} \times \mathbf{y}, \mathbf{N}_f)}}$$
[3]

# Stage II: refinement registration

PCA is a common method to discover and exploit linear correlation in data (42). PCA linearly transforms the correlation input into a set of uncorrelated variables by orthogonal transformation, extracting principal components (PCs). The PC with larger variance is ranked higher, containing more data information. The image series post the coarse registration of RPCA is firstly transformed to a 2D matrix M (x-y by N<sub>t</sub>), with its covariance matrix defined as:

$$C = \frac{1}{N_f - 1} M M^T$$
[4]

C is eigenvalue decomposed, and the generated eigenvectors are sorted in descending order of the corresponding eigenvalue. Orthogonal matrix U, whose columns are eigenvectors, transforms the correlation input into uncorrelated data W:

$$W = U^T M$$
<sup>[5]</sup>

where W contains PCs of the input. M can be approximately

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reconstructed using only the *d* highest ranked PCs':

$$\mathbf{M}_{\mathbf{d}} = U_{\mathbf{d}} W_{\mathbf{d}}$$
<sup>[6]</sup>

where  $U_d$  and  $W_d$  contain first *d* columns of U and W, respectively.

In coarse registration, it is difficult to optimize  $\lambda$  to correct for both large and small deformations simultaneously; thus, misalignments remain in the coarse registered series. However, the residual motion is slight and noise-like and assumed to appear in less significant PCs when compared with continuous CEST contrast which is more significant. Therefore, the PCA-based registration, similar to previous methods (35,36), has the ability to remove the residual motion efficiently by using a limited number of PCs that correspond to CEST contrast.

Each voxel in a coarse registered image is interpreted as a variable for the function describing the corresponding signal intensity along  $\Delta \omega$  as an observation. The coarse registered series is subject to PCA, looking for linear correlations between the voxels with regard to  $\Delta \omega$  and generating PCs. In the *i*<sup>th</sup> iteration, the first *i* PCs are used to create a synthetic motionless reference series, in a  $\Delta \omega$ -by- $\Delta \omega$  manner. Importantly, only the reference series is updated and refined in iterations, while the source images are always represented by the coarse registered series. This process is repeated until the *d*'s highest ranked PCs are included.

## Quality check

Since motion-free Z-spectral signals are continuous and smooth in theory, we use the CC between the corrected saturation-weighted image and the average image at its two neighboring offsets to assess registration quality, defined as follows:

$$CC = \frac{\sum_{i=1}^{x} \sum_{j=1}^{y} \left[ P(i,j) \cdot \overline{P} \right] \left[ Q(i,j) \cdot \overline{Q} \right]}{\sqrt{\sum_{i=1}^{x} \sum_{j=1}^{y} \left[ P(i,j) \cdot \overline{P} \right]^{2} \sum_{i=1}^{x} \sum_{j=1}^{y} \left[ Q(i,j) \cdot \overline{Q} \right]^{2}}}$$
[7]

where x and y are the dimensions of the image.  $\overline{P}$  and  $\overline{Q}$  denote the average intensities of the two comparison images, respectively. The closer the value of CC is to 1, the more similar the two images are, with the alert being raised when CC <0.9.

## **Registration details**

In principle, any registration technique can be used in the



**Figure 2** Phantom CEST MRI data after applying rigid motion of different patterns. (A) Profile of the phantom, in which the tubes are filled with different concentrations of salicylic acid (SA) solution dissolved in 0.01 M phosphate-buffered saline (PBS) at pH 6.8 (top row) and pH 7.4 (down row) corresponding to the MTR<sub>asym</sub>(9.25 ppm) map of the original data. (B,C) MTR<sub>asym</sub>(9.25 ppm) maps of the phantom data corrupted by applying shifts (x-direction and y-direction) and rotations (xy-plane) with 0 mean, different SD in normally distributed pseudo-random numbers to each Z-spectral image, and the corresponding differences from the original data. (D) The normalized root mean square error (NRMSE) of Z-spectral image series corrupted by motion in various patterns to the original data. CEST, chemical exchange saturation transfer; MTR<sub>asym</sub>, asymmetry analysis on the magnetization transfer ratio.

proposed motion correction scheme. Herein, pair-wise rigid registration with SSD-based dissimilarity metric is exploited. For each stage, we used a MATLAB (MathWorks, Natick, MA, USA) custom function. An optimizer, based on built-in-function fminsearch, looks for the optimal solution that minimizes the dissimilarity metric. A multiresolution strategy is used, in which the large deformations are corrected first, and finer deformations are corrected at higher levels. The number of resolution levels is set to 3. Bicubic interpolation is used to interpolate the images among rigid transformation.

# Experiments

#### Phantom study

The phantom was prepared using NMR tubes of 1 mm in diameter. Salicylic Acid (SA) solutions were dissolved in 0.01M phosphate-buffered saline (PBS) at 6 concentrations (1.56, 3.12, 6.25, 12.5, 25, and 50 mM), producing a range

of CEST contrast. *Figure 2* illustrates the profile of the phantom, which includes 2 groups of samples at pH 6.8 and pH 7.4.

All experiments were performed on a Bruker 11.7 T vertical MRI scanner with a 15 mm birdcage for both excitation and signal detection. CEST MRI images were acquired using a continuous-wave (CW) saturation pulse, followed by a single-sliced rapid acquisition with relaxation enhancement (RARE) sequence (RARE factor =32). A total of 89 saturated images, which were the Z-spectral image series, were collected from -11 to 11 ppm [0.25 ppm step,  $t_{sat} = 3,000$  ms,  $B_{1,sat} = 5.9 \ \mu\text{T}$ , repetition time (TR)/ echo time (TE) =6,000 ms/4.5 ms]. The total scanning time for the Z-spectral image series was 18 min. The  $S_0$ image was collected at 40 ppm. A group of images was acquired by sweeping  $\Delta \omega$  from -1 to 1 ppm (0.05 ppm step)  $(t_{sat} = 500 \text{ ms}, B_{1,sat} = 0.28 \mu\text{T}, \text{ and TR/TE} = 2,500 \text{ ms/}4.5 \text{ ms})$ to generate the B0 map using WASSR (43), resulting in 3 min and 25 s of scanning. The other imaging parameters

were as follows: field of view (FOV)  $=1.7 \times 1.4 \text{ cm}^2$ , acquisition matrix size  $=128 \times 64$ , slice thickness =1 mm.

#### In vivo study

All animal experiments were performed in accordance with the Johns Hopkins University Animal Care and Use Committee guidelines. A SCID/NCR mouse was xenografted intracranially to the striatum of the brain with 100,000 human glioblastoma cancer cells derived from patients (44,45). MR imaging was performed 6 weeks post-injection with the mouse anesthetized using 0.5-2% isoflurane prior to imaging. MR images were acquired with the RARE readout on a Bruker 11.7T horizontal MRI scanner, using a 23 mm birdcage transmit-receiver coil. The in vivo experiments used the same RARE sequence as that for the phantom study, but it was slightly modified given the different relaxation characteristics and offset frequencies of interest. A total of 49 Z-spectral images with  $\Delta \omega$  incremented from -6 to 6 ppm (0.25 ppm step) were collected using  $t_{sat} = 2,500$  ms,  $B_{1,sat} = 2.4 \mu T$ , TR/TE =5,500 ms/11.1 ms, resulting in 9 min and 10 s of scanning. The S<sub>0</sub> image at 40 ppm was collected. B0 inhomogeneity was corrected using WASSR (43), which were saturation images with a weak saturation pulse  $(B_{1,sat} = 0.5 \ \mu T, t_{sat} = 500 \text{ ms})$  sweeping from -1 to 1 ppm (0.1 ppm step) (TR/TE =2,000 ms/10.8 ms). The other imaging parameters were as follows: RARE factor =16, FOV = $1.7 \times 1.4$  cm<sup>2</sup>, acquisition matrix size = $96 \times 64$ , slice thickness =1.2 mm.

## Simulated motion

The statically acquired Z-spectral image series were seen as original data. To verify RPCA + PCA R, each image was corrupted by random shifts and rotations to simulate rigid motion for tubes of phantom and in vivo mouse head. Motion under three patterns was applied to phantom data: normally distributed pseudo-random numbers with 0 mean and SD for shifts in x-direction and y-direction of 0.2 or 0.5 pixel, 0 mean and SD for rotation in the xy-plane of 0.1° or 0.3°, and combinations of different shifts and rotations. In vivo data was corrupted by motion under the other 3 patterns: 0 mean and 0.5 or 1 pixel SD for shifts, and 0.5° or 1° SD for rotations as well as their different combinations in normally distributed pseudo-random numbers. To assess the robustness of registration methods, the simulation of each motion pattern was repeated 10 times to obtain various motion scenarios between the image series.

# Image processing

The original Z-spectral image series, as well as WASSR images, were first aligned using the proposed registration method, followed by the regular CEST processing flow which consists of the voxel-wised correction for B0 inhomogeneity, calculation of the  $MTR_{asym}(\Delta \omega)$  map, and the ROI-based Z-spectra analysis. For comparison, previous registration strategies using an explicit image as the reference of registration were also performed, termed as  $S_0$  R (using  $S_0$ image) (24) or S<sub>sat</sub>\_R which used saturated image  $S_{sat}(\Delta \omega)$  ( $\Delta \omega$ =+9.25 ppm for phantom and +3.5 ppm for in vivo) (32). In addition, to illustrate the advantage of combination of RPCA and PCA, registration was also exploited using either only RPCA-based method (RPCA\_R) or only the PCA-based one (PCA\_R). All the exploit correction schemes used the same registration core technique as described earlier in the session of 'Registration details'.

All data processing was performed using customwritten scripts in Matlab 2016a. All statistical analyses were performed with Prism8 (GraphPad Software) with P<0.05 considered as statistically significant.

## Evaluation of registration performance

To fully evaluate the changes of the entire Z-spectral image series due to motion, and after correction, we expanded the whole series to form a 2D offset-cut map, with the x-dimension representing the (selected) voxels of the S<sub>sat</sub> image at a specific  $\Delta \omega$  and the y-dimension depicting the Z-spectrum of a specific voxel. The offset-cut map was then normalized by the average image of the whole series. The registration accuracy was quantitatively assessed using CC between the normalized offset-cut map of the data corrupted by motion (or after correction) and that of the original data. Furthermore, the CC for the MTR<sub>asym</sub>( $\Delta \omega$ ) map was calculated to assess the registration effects between S<sub>sat</sub>(+/- $\Delta \omega$ ) images.

We also quantitatively compared Z-spectra and the  $MTR_{asym}(\Delta \omega)$  of particular regions of interest (ROIs), which were calculated from the original data, the motioncorrupted data, and the corrected data, using different methods in each data set. The residual Z-spectra referring to the original data, were also plotted to describe the deviation. For the phantom, the ROI was defined at the 25 mM pH 6.8 tube as shown in *Figure 3*. For the *in vivo* experiments, the ROI of tumor was defined by a 4 pixel ×5 pixel box at the tumor core, and a mirrored ROI of





**Figure 3** Visual registration results of the phantom data, corrupted by simulated motion (0.5 pixel SD for shifts and 0.3° SD for rotations). (A-F)  $MTR_{asym}(9.25 \text{ ppm})$  maps and the corresponding error maps for the motion-corrupted data, and for those corrected by different registration methods, including use of S<sub>0</sub> as reference for registration, use of saturated image S<sub>sat</sub>(+9.25 ppm) as reference, RPCA-based registration, PCA-based registration, and our method of combining RPCA and PCA, termed as S<sub>0</sub>\_R, S<sub>sat</sub>\_R, RPCA\_R, PCA\_R, and RPCA + PCA\_R, respectively. ROI was plotted at the 25 mM tube with pH 6.8 in (A). RPCA, robust principal component analysis; ROI, region of interest; MTR<sub>asym</sub>, asymmetry analysis on the magnetization transfer ratio.

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normal tissue at the contralateral hemisphere (marked on *Figure 4*).

Other qualitative assessments through direct visualization of different kinds of maps are detailed below:

- The offset-cut maps, which display both the oscillation of Z-spectra for a particular voxel and the signals for (selected) voxels on a particular S<sub>sat</sub>(Δω) image.
- The MTR<sub>asym</sub>(Δω) maps, which exhibit the intensity and distribution of CEST contrast.
- The error maps, which depict the difference of MTR<sub>asym</sub>(Δω) maps from original data.

## **Results**

#### Phantom study

The performance of RPCA + PCA\_R was first verified on a phantom. Firstly, we compared how different motion patterns affected the CEST contrast. The spatial distribution of SA tubes is shown in Figure 2A. The motion-corrupted MTR<sub>asym</sub>(9.25 ppm) maps displayed substantial errors, particularly at the edge of the tubes (Figure 2B,C). The form and degree of deformation affected the corruption of Z-spectral images, in which shift had a greater impact on motion corruption, and combined with rotation would worsen it (Figure 2D). Among the simulated patterns, the worst-case motion pattern was created by a combination of the maximum shift (0.5 pixel SD) and rotation (0.3° SD), resulting in the largest normalized root mean square error (NRMSE) to the original data (0.31). For this worst case, the saturation-weighted images were clearly misaligned (Figure S1), while the L components after RPCA decomposition contained less motion, and the S components had more obvious motion. Herein, the value of  $\lambda$  was set experimentally to generate a low rank of L (rank, 4-6) to minimize the motion component in the reference image. In refinement registration, PCA was repeated 2 or 3 times empirically; details of the parametric registration model for phantom studies are provided in Figure S2.

*Figure 3* depicts the visual registration results of the phantom data corrupted by the simulated motion with the above-mentioned worst pattern. As seen in *Figure 3A*, the MTR<sub>asym</sub> analysis was corrupted completely by motion, and S<sub>0</sub>\_R, S<sub>sat</sub>\_R, RPCA\_R, and PCA\_R removed part of the motion artifacts. However, residual misalignments still existed, causing MTR<sub>asym</sub>(9.25 ppm) maps to exhibit a distinct deviation from the original data (*Figure 3B,C,D,E*). Among all the methods, RPCA + PCA\_R performed the

best, reproducing the  $MTR_{asym}(9.25 \text{ ppm})$  map with only a slight difference from the original one (*Figure 3F*).

We further performed a quantitative assessment of these methods. The motion-corrupted dataset used in Figure 5A and B was same as that in Figure 3. Compared with the original data, the motion-corrupted Z-spectrum contained false peaks and dips, which might have been affected by the different patterns of motion including the directions. The motion-induced oscillations were corrected at different levels by the 5 methods. The residual curve of the Z-spectrum suggested that RPCA + PCA R produced the most similar and smooth Z-spectrum with reference to the original one, by excluding most of the wiggles (Figure 5A). Figure 5B summarizes the measured  $MTR_{asym}(9.25 \text{ ppm})$ for multiple tubes, and the corrected values display a more linear relationship for the concentration over the range of 1.5 to 25 mM (pH 7.4) (46) when comparing to the motion-corrupted one. More specifically, the relationship regained by RPCA + PCA\_R was closer to the original one. Figure 5C,D display the statistics of the CC between the  $MTR_{asym}(9.25 \text{ ppm})$  maps of the data corrupted by motion (or with correction) and that of the original data, in addition to the CC for the whole Z-spectral image series in 10 repeated simulations (with the same motion pattern as that in Figure 3). All methods increased CC for both; however, CC for RPCA + PCA\_R showed the most significant rise with small SD [0.90 for the MTR<sub>asym</sub>(9.25 ppm) map and 0.60 for the whole series].

## In vivo study

RPCA + PCA\_R was then tested in a mouse tumor-bearing brain model. As seen in *Figure 6*, the saturation-weighted images were markedly misaligned due to motion (M: 1<sup>st</sup> row). Post-RPCA decomposition, the low-rank components appeared static (L: 2<sup>nd</sup> row), while the S components had obvious motion (S: 3<sup>rd</sup> row).

Figure 7 displays the detailed manner of parameterizing the registration model for the same motion-corrupted *in vivo* data as that in *Figure 6*. The rank of L was plotted as a function of  $\lambda$ , indicating that a smaller  $\lambda$  corresponded to a lower rank of L (*Figure 7A*). To reduce the contribution of the motion in the reference image,  $\lambda$  was selected as a smaller value that distributed most motion component in S but kept some contrast in L. As seen in *Figure 7B,C,D*, the recomposed L with rank =3 or 4 provides distinction of Z-spectra between tumor and normal tissue, while with maintaining a relatively small motion component. When

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**Figure 4** Visual registration results of the *in vivo* data corrupted by simulated large motion (1 pixel SD for shifts and 1° SD for rotations). (A) From top to bottom: the offset-cut maps for selected voxels indicated by the black dashed line, the  $MTR_{asym}(3.5 \text{ ppm})$  map, and the error map with respect to that of the original static data. (B-G) same as (A), but for the motion-corrupted one, and for those corrected by  $S_{0}$ \_R,  $S_{sat}$ \_R [using  $S_{sat}(+3.5 \text{ ppm})$  as the reference image], RPCA\_R, PCA\_R, and RPCA + PCA\_R, respectively. ROIs of tumor and normal tissue are plotted in (B). RPCA, robust principal component analysis; ROI, region of interest;  $MTR_{asym}$ , asymmetry analysis on the magnetization transfer ratio.



**Figure 5** Quantitative assessment of the RPCA + PCA registration method for motion-corrupted phantom data, in comparison with the 4 other registration methods including  $S_{0}$ \_R,  $S_{sat}$ \_R, RPCA\_R, and PCA\_R. (A) Z-spectra of ROI (as defined in *Figure 3A*) and the residual curves referring to the original data. (B) The relationship between the MTR<sub>aym</sub>(9.25 ppm) and the concentration of SA over the range from 1.5 mM to 25 mM (pH 7.4). The motion-corrupted data used in (A,B) was the same as in *Figure 3*. (C) The correlation coefficient (CC) of corrected MTR<sub>aym</sub>(9.25 ppm) maps with that of the original static data for 10 repeated simulations with the same motion pattern as that in *Figure 3* (mean ± standard deviation). (D) Simulations are the same as (C), but have plotted CC of the corrected whole Z-spectral image series with respect to the original static data. The significance between different registration results and motion-corrupted data: \*\*\*P<0.001, \*\*\*\*P<0.0001. RPCA, robust principal component analysis; ROI, region of interest; CC, correlation coefficient; MTR<sub>asym</sub>, asymmetry analysis on the magnetization transfer ratio.

the rank >4, L demonstrates obvious motion with the offsetcut map displaying changed voxel locations among images at various  $\Delta \omega$ . Since the coarse registered series could be expressed as a linear combination of its first 3 principal eigenvalue images, the number of iterations using PCA was determined to be 3 (*Figure 7E*,*F*). The choices of  $\lambda$  for various motion patterns are shown in *Table S1*.

Figure 4 shows the registration results for *in vivo* data corrupted by the simulated large motion (1 pixel SD for shifts and 1° SD for rotations). The  $1^{st}$  row shows the offset-cut maps which expand the Z-spectra of voxels on the black dashed line in *Figure 4A* into a 2D map. The

original data without misalignments among the Z-spectral images obtained an  $MTR_{asym}(3.5 \text{ ppm})$  map with higher signal intensities in tumor and lower ones in normal tissue (*Figure 4A*). Due to the applied motion, the offset-cut map displays wiggles indicating location of voxels changed significantly among Z-spectral images, resulting in an  $MTR_{asym}(3.5 \text{ ppm})$  map with a bright-dark pattern in normal tissue and changes of tumor shape and position (*Figure 4B*). S<sub>0</sub>\_R, S<sub>sat</sub>\_R, RPCA\_R, and PCA\_R reduced misalignments; however, the offset-cut maps still exhibit jitters, while the  $MTR_{asym}(3.5 \text{ ppm})$  error maps show visible signal variation and deformation of tumor (*Figure 4C*, D, E, F). RPCA +



**Figure 6** Decomposition of Z-spectral image series using RPCA, for *in vivo* CEST MRI data of mouse tumor-bearing brain. (A) Z-spectral image series corrupted by simulated rigid motion, M. (B) low-rank component, L. (C) sparse component, S. A horizontal line (yellow) illustrates the different positions of the mouse head among Z-spectral images. As can be seen, after decomposition, S images exhibit obvious motion while L images appear static. RPCA, robust principal component analysis; CEST, chemical exchange saturation transfer.

PCA\_R eliminated the motion-induced interference, recovered the spatial location of voxels, and regained the analytical  $MTR_{asym}(3.5 \text{ ppm})$  map (*Figure 4G*).

# Discussion

Figure 8 quantitatively summarizes the registration performance for the in vivo data. For the data corrupted by the simulated large motion, the Z-spectra of the tumor show that RPCA + PCA\_R improved the corrupted Z-spectrum (the corrupted data was same as Figure 4) with only a slight difference from the original data, while other methods rendered obvious discrimination (Figure 8A). In 10 repeated simulations with the large motion pattern, the statistical results demonstrate that RPCA + PCA R obtained the highest CC between the corrected  $MTR_{asym}(3.5 \text{ ppm})$  map and that of the original data, among all the exploited methods (Figure 8B). This is also the case for the CC of the corrected whole Z-spectral image series (*Figure 8C*). The  $MTR_{asym}(3.5 \text{ ppm})$  values for both tumor and normal tissue obtained by RPCA + PCA\_R were closest to the original data with the smallest SD among the 10 repeated simulations. For PCA\_R, the MTR<sub>asym</sub>(3.5 ppm) of normal tissue was also very close to the original data but with larger SD (Table 1). In small motion patterns, RPCA + PCA\_R corrected the artificially added motion and achieved a similar registration performance as the bigger one (Figure 8D,E). Registration results can also be seen in Figure S3.

In this study we proposed a novel registration scheme for the correction of misaligned images acquired during a CEST MRI scan, which first exploited RPCA decomposition for coarse registration, followed by a PCAbased refinement step, and a quality check module at the end. Compared with the 4 other methods, our RPCA + PCA R allowed for more accurate correction of the Z-spectral images, with smaller  $MTR_{asym}(\Delta \omega)$  error maps and lower residual Z-spectra referring to the original data (Figures 3,5 for phantom and Figures 4,8 for in vivo). Among all the 5 exploited methods, the corrected Z-spectral image series by RPCA + PCA\_R and the resulting  $MTR_{asym}(\Delta\omega)$ maps exhibit the highest CCs to the original ones. In particular, RPCA + PCA\_R provided a robust correction under both large and small motion patterns of in vivo data in multiple repeats (Figure 8). Additionally, quality check module certified that the motion-corrected by RPCA + PCA\_R was valid (Figure S4). The residual Z-spectra and  $MTR_{asym}(\Delta \omega)$  error maps after RPCA + PCA\_R slightly deviated from the original data. This was mainly due to the interpolation during transformation of registration, which means the motion can in principle be corrected to a great amount, but slight discrimination might still arise.

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Figure 7 Analysis of the decomposition results of motion-corrupted *in vivo* data (same as *Figure 6*). (A) Rank of L as a function of the trade-off parameter ( $\lambda$ ).  $\lambda_0$  corresponds image for a specific  $\Delta \omega$  and y dimension depicting the Z-spectrum of a specific voxel. The voxels are those indicated by the yellow dashed line in Figure 6. (D) Z-spectra of to the Candès value. (B,C) The offset-cut maps for original data and low-rank series of the motion-corrupted data, with x dimension representing selected voxels in Sat tumor and contralateral normal tissue for original data and low-rank series of the motion-corrupted data. (E) Normalized eigenvalues of the covariance matrix for the coarse registered series. (F) An example image shows that the coarse registered series can be presented as a linear combination of 3 images with highest principal eigenvalues.



**Figure 8** Quantitative assessment of the RPCA + PCA registration method for motion-corrupted *in vivo* tumor-bearing mouse brain, by comparison with the 4 other registration methods including  $S_{0}$ \_R,  $S_{sat}$ \_R, RPCA\_R, and PCA\_R. (A) Z-spectra of tumor (ROI defined in *Figure 4B*) and the residuals curves referring to the original data (The large motion-corrupted data was same as *Figure 4*). (B) Correlation coefficients (CCs) between the corrected MTR<sub>asym</sub>(3.5 ppm) map and the original static one, in comparison with those calculated from non-corrected motion-corrupted data, for 10 repeated simulations with the same large motion pattern as that in *Figure 4* (mean ± standard deviation). (C) Simulations are the same as (B), but are plotted CC of the corrected whole Z-spectral image series with respect to the original static data. (D) CCs between the RPCA + PCA\_R corrected MTR<sub>asym</sub>(3.5 ppm) map and the original static one, in comparison with those calculated from non-corrected motion-corrupted data, for 10 repeated simulations with small motion of different patterns. (E) Same as (D), but CC values are for the whole Z-spectral image series. The significance between different registration results and motion-corrupted data: \*P<0.05, \*\*\*P<0.001, \*\*\*\*P<0.001. RPCA, robust principal component analysis; ROI, region of interest; MTR<sub>asym</sub>, asymmetry analysis on the magnetization transfer ratio.

for rotations in normany distributed pseudo-random numbers, and the corrected ones using different registration methods in 10 simulations								
Variable	Original	Corrupted	S <sub>0</sub> _R	S <sub>sat</sub> _R	PCA_R	RPCA_R	RPCA + PCA_R	
MTR <sub>asym</sub> _tumor (%)								
Mean	1.60	2.97	1.35	1.14	1.43	1.44	1.50	
SD	-	0.60	0.18	0.18	0.09	0.17	0.05	
MTR <sub>asym</sub> _normal (%)								
Mean	-3.11	-4.51	-3.21	-3.20	-3.08	-3.02	-3.17	
SD	_	2.43	0.40	0.23	0.20	0.26	0.03	

**Table 1** Statistics of MTR<sub>asym</sub>(3.5 ppm) for the original *in vivo* data, the data corrupted by motion with 0 mean and 1 pixel SD for shifts and 1° SD for rotations in normally distributed pseudo-random numbers, and the corrected ones using different registration methods in 10 simulations

RPCA, robust principal component analysis; MTR<sub>asym</sub>, asymmetry analysis on the magnetization transfer ratio.

In contrast to previous methods that used an explicit registration reference image, either  $S_0$  (24-29) or a specific saturated image  $S_{sat}(\Delta \omega)$  (32), RPCA + PCA\_R extracted the relative static low-rank component from the entire Z-spectral image series and used their averaged image as the registration reference. Results suggest that S<sub>0</sub>\_R showed the worst registration between  $S_{sat}(+/-\Delta\omega)$  images, which might be because S<sub>0</sub> image intensities and contrast are different from saturated ones (32). Despite a better performance in correcting  $S_{sat}(+/-\Delta\omega)$  images than that of  $S_{0}R$ , among all the 5 methods, S<sub>sat</sub>\_R exhibited the lowest CC between the corrected whole image series and the original static data. This indicates that the selection of a single saturated image as a registration reference is less robust, and may result in poor registration for images of other offsets in the CEST dataset.

The idea of decomposition of Z-spectral image series for separating CEST contrast from motion is similar to the previous LRAZ method (34). However, LRAZ registered each image to its corresponding low-rank one, with the quality of registration strongly depending on the choice of regularization parameters. RPCA-based registration had a similar principle but used the averaging of L as a reference, which enabled the improvement of robustness. PCAbased registration also corrected motion by attributing motion to less significant PCs. Both only RPCA- (RPCA\_ R)- and only PCA- (PCA\_R)-based methods performed well in compensating for misalignments among entire image series in the phantom (Figure 3). This is presumably because motion-induced signal changes were smaller and faster compared with CEST contrast, and the separation was easier. However, neither RPCA\_R nor PCA\_R was unable to completely correct motion in vivo, or for the S<sub>sat</sub>(+/-9.25 ppm) images in the phantom study. RPCA\_ R did not work well since  $\lambda$  was difficult to determine for accurately separating the CEST contrast from motion. As seen in *Figure 7C*,*D*, the recomposed L using a small  $\lambda$  still contained undifferentiated motion. For PCA R, the larger motion was likely to appear in the first PCs, resulting in a synthetic image series with motion. Hence, to improve the robustness and effectiveness of registration, we chose a combination of RPCA and PCA, with PCA\_R further correcting the residual motion after the coarse registration by RPCA R.

Despite coarse registration not requiring a complete differentiation motion and CEST contrast,  $\lambda$  cannot be selected arbitrarily (*Figure S5*). An excessively small  $\lambda$  will lead to less information in L and generate a sparse reference

image that differs significantly from the saturated ones, causing the failure of coarse registration as in S<sub>0</sub>\_R. While a too large  $\lambda$  introduces too much motion into L, coarse registration will be less effective. Herein, to provide a motionless reference image for coarse registration,  $\lambda$  was adjusted experimentally to keep the most motion in S but some CEST contrast in L with sufficient information to distinguish different tissues. The optimization of  $\lambda$  will be further investigated, which may use the lineshape of the Z-spectrum obtained from a quantitative model as a constraint for RPCA to guide the information to be retained in the L or S components.

However, the hypothesis of coarse registration that CEST contrast appears in L while motion in S may be limited, specifically when continuous and periodical motion occurs. This limitation can be exploited in dynamic CEST MRI, where contrast enhancement seems to be rapid in comparison to motion. RPCA + PCA\_R represents a scheme for the image series registration, which means that pair-wise registration in RPCA + PCA\_R is exchangeable. Any other optimization algorithms, like group-wise registration (47-49), can be introduced to improve the performance of RPCA + PCA\_R. Equally, any non-rigid registration methods can replace the rigid algorithm used in this study.

Realistic *in vivo* motion was not studied in this paper. Indeed, it is important to test our method by mimicking real motion scenarios. For example, some of the previous studies examined skeletal muscles under exercise with obvious motion involved but with relatively simple anatomy (34), while others used brain data with minor and random motion (32,50). As an initial study, we employed the wellstudied brain tumor model with simulated random motion. Additionally, we included both large and small motion in different patterns with multiple repeats to prove the robustness and effectiveness of RPCA + PCA\_R. We will further test the method in multiple realistic motion scenarios including brain and body imaging.

CEST MRI is still at the early stage that precedes widespread clinical application. Most existing preclinical data are acquired at high field, as well as a large portion of data on human subjects, used 2D single-slice sequences. Particularly, when multiple offsets on Z-spectra are of interest, 2D data are acquired first to shorten the scan time and to simplify the analysis. Therefore, in this study we focused on correcting the misalignments among 2D CEST images caused by in-plane rigid motion, similar to recent works by other groups (22,34). However, in cases where an

image moves out of the imaging plane, our current method using 2D data may not work as well. Nevertheless, those images with unsuccessful correction will be captured by the quality check module (*Figure 1*), raising alerts for a manual check. Additionally, motion correction using RPCA and that using PCA has been successfully applied to a 3D dataset in DCE-MRI (36,37). Therefore, we are optimistic that our method can also be applicable for 3D CEST data, which will be the focus of our next work.

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# Footnote

*Conflicts of Interest*: The authors have no conflicts of interest to declare.

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Figure S1 Decomposition of Z-spectral image series from phantom acquisition (artificially corrupted by simulated rigid motion) with RPCA. (A) motion-corrupted Z-spectral image series, M. (B) low-rank component, L. (C) sparse component, S. A horizontal line (yellow) illustrates the different positions of tubes among Z-spectral images. As can be seen, after decomposition, S images exhibit obvious motions while L images appear static. RPCA, robust principal component analysis.



Figure S2 Analysis of the decomposition results of motion-corrupted phantom data (same as *Figure S1*). (A) Rank of L as a function of the trade-off parameter ( $\lambda$ ). (B,C) The offset-cut maps for original data and low-rank series of the motion-corrupted data. The voxels are those indicated by the yellow dashed line in *Figure S1*. (D) Z-spectra of the tubes with 3.1 and 50 mM SA (pH 7.4) for original data and low-rank series of the motion-corrupted data. (E) Normalized eigenvalues of the covariance matrix for the coarse registered series. (F) An example image shows that the coarse registered series can be presented as a linear combination of 2 images with highest principal eigenvalues.

**Table S1** The selected rank of low-rank component, corresponding to trade-off parameter ( $\lambda$ ), for different motion patterns of phantom and *in vivo* data

Motion patterns	Phantom	Rank of L	In vivo	Rank of L
Shift only	0.2 pixel	6	0.5 pixel	5
	0.5 pixel	4	1 pixel	3
Rotation only	0.1°	6	0.5°	5
	0.3°	4	<b>1</b> °	3
Shift + rotation	0.2 pixel + 0.1°	4	0.5 pixel + 0.5°	3
	0.2 pixel + 0.3°	4	0.5 pixel + 1°	3
	0.5 pixel + 0.1°	4	1 pixel + 0.5°	3
	0.5 pixel + 0.3°	4	1 pixel + 1°	3



**Figure S3** Registration results of the *in vivo* data corrupted by simulated small motion in normally distributed pseudo-random numbers with 0 mean and 0.5 pixel SD for shifts and 0.5° SD for rotations. (A,B) Offset-cut maps (the selected voxels indicated by the black dashed line), MTR<sub>asym</sub>(3.5 ppm) maps and the corresponding error maps for the corrupted data, and the corrected one by RPCA + PCA\_R, respectively. (C) Z-spectra of tumor and the residual curves referring to the original data. ROI of tumor was plotted in (A). RPCA, robust principal component analysis; ROI, region of interest; MTR<sub>asym</sub>, asymmetry analysis on the magnetization transfer ratio.



Figure S4 Graphs of CC in quality control for phantom and in vivo, respectively. CC, correlation coefficient.



**Figure S5** Subtraction between average image of the original data and that of low-rank series with different ranks for motion-corrupted *in vivo* data (same as *Figure 6*). (A) Rank =1; (B) rank =3; (C) rank =25 (corresponds to  $\lambda_0$ ).