



# Biomechanical evaluation of interbody fixation with secondary augmentation: lateral lumbar interbody fusion versus posterior lumbar interbody fusion

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**Background:** Many approaches to the lumbar spine have been developed for interbody fusion. The biomechanical profile of each interbody fusion device is determined by the anatomical approach and the type of supplemental internal fixation. Lateral lumbar interbody fusion (LLIF) was developed as a minimally invasive technique for introducing hardware with higher profiles and wider widths, compared with that for the posterior lumbar interbody fusion (PLIF) approach. However, the biomechanics of the interbody fusion construct used in the LLIF approach have not been rigorously evaluated, especially in the presence of secondary augmentation.

**Methods:** Spinal stability of 21 cadaveric lumbar specimens was compared using standard nondestructive flexibility studies [mean range of motion (ROM), lax zone (LZ), stiff zone (SZ) in flexion-extension, lateral bending, and axial rotation]. Non-paired comparisons were made among four conditions: (I) intact; (II) with unilateral interbody + bilateral pedicle screws (BPS) using the LLIF approach (referred to as the LLIF construct); (III) with bilateral interbody + BPS using the PLIF approach (referred to as the PLIF construct); and (IV) with no lumbar interbody fusion (LIF) + BPS (referred to as the no-LIF construct).

**Results:** With bilateral pedicle screw-rod fixation, stability was equivalent between PLIF and LLIF constructs in lateral bending and flexion-extension. PLIF and LLIF constructs had similar biomechanical profiles, with a trend toward less ROM in axial rotation for the LLIF construct.

**Conclusions:** LLIF and PLIF constructs had similar stabilizing effects.

**Keywords:** Lateral lumbar interbody fusion (LLIF); lumbar interbody fusion (LIF); lumbar biomechanics; pedicle screw; posterior lumbar interbody fusion (PLIF); range of motion (ROM)

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## Introduction

Interbody hardware is used to restore the intervertebral space, reconstituting the load-bearing elements of the lumbar spine to provide stability and enhance fusion potential. The principal tenets of interbody fusion include

placement of an interbody graft under direct compression, thereby restoring normal anatomical disc height, indirectly decompressing neural foramina, preserving posterior elements, and restricting motion across fusion segments (1). This frequently requires that interbody fusion be

supplemented with dorsal fixation to achieve optimal construct rigidity.

Multiple approaches exist that provide several anatomical trajectories, each with potential trade-offs determined by the extent of resection of local supportive structures and graft size. The posterior lumbar interbody fusion (PLIF) and lateral lumbar interbody fusion (LLIF) procedures use different anatomical approaches and different interbody implants to attain lumbar arthrodesis. LLIF is a method of minimally invasive lumbar interbody fusion performed with a comprehensive set of instruments.

LLIF differs from PLIF in terms of its lateral approach and the structural characteristics of the interbody implant. In LLIF, the lateral transpoas approach allows for preservation of back muscles, anterior and posterior longitudinal ligaments, and facet joints. LLIF has been shown to result in decreased tissue dissection and decreased operative time, as well as reduced postoperative pain (2). The higher profile and bilateral epiphyseal position of the interbody implant used in the LLIF approach provides strong support for disc height restoration and indirect neural foraminal decompression, and for improved correction of sagittal and coronal plane imbalance (3,4). However, the biomechanics of the interbody fusion construct used in the LLIF approach have not been rigorously compared with those of the PLIF approach in the presence of secondary augmentation.

Our objective was to directly compare the biomechanical stabilizing effect of the interbody fusion constructs used in the LLIF and PLIF approaches, both supplemented with secondary augmentation using pedicle screw-rod fixation, in flexion-extension, lateral bending, and axial rotation. Rotational range of motion (ROM) was used as the standard metric of comparison.

## Methods

We hypothesized that the LLIF approach would provide greater stability than the PLIF approach with secondary augmentation.

### *Specimen preparation*

Twenty-one human cadaveric L2–L5 specimens were studied. The mean  $\pm$  SD age of the specimens was  $55.2 \pm 13.5$  years (range, 21–73 years); there were 11 male and 10 female cadaveric specimens. Neither institutional review board approval nor consent was deemed necessary due to

the cadaveric nature of the study. By screening the medical records of the suppliers of cadaveric materials and plain film radiographs and by directly inspecting the specimens, we ensured that no specimen had any obvious pathology that might affect biomechanics, especially metastatic disease, osteophytes, disc narrowing, or joint arthrosis. Dual-energy X-ray absorptiometry scans to assess bone mineral density (BMD) were performed on the L4 vertebra of each specimen with a resulting mean of  $0.797 \pm 0.187$  g/cm<sup>2</sup>. Analysis of variance (ANOVA) was used to compare the mean age and BMD values among the three groups of specimens studied and showed no significant differences (mean age,  $P=0.38$ ; mean BMD,  $P=0.37$ ).

Specimens were wrapped in plastic bags and stored at  $-20$  °C until tested. The specimens were thawed in a bath of normal saline at  $30$  °C and carefully cleaned of muscle tissue while all the ligaments, the joint capsules, and the discs were kept intact. For testing, the exposed endplate and facet articulations of L5 were reinforced with household wood screws and the screwheads and part of the vertebral body were embedded in a cylindrical metal fixture using fast-curing resin (Smooth-Cast; Smooth-On, Inc.), and attached to the base of the testing apparatus. The L2 vertebra was similarly embedded in a cylindrical metal fixture for pure moment load application.

### *Testing conditions*

Specimens were divided into three groups with similar age ( $P=0.12$ ) and bone quality ( $P=0.37$ ), then tested in four conditions: (I) intact and (II–IV) instrumented at L3–L4, as follows:

- (II) Interbody + bilateral pedicle screws (BPS) using the LLIF approach (referred to as the LLIF construct;  $n=7$ );
- (III) Bilateral interbody + BPS using the PLIF approach (referred to as the PLIF construct;  $n=7$ );
- (IV) No lumbar interbody fusion (LIF) + BPS (referred to as the no-LIF construct;  $n=7$ ).

The interbody fusion constructs used in the LLIF approach consisted of unilaterally placed polyether ether ketone (PEEK) interbody implants (CLYDESDALE Spinal System; Medtronic, Inc.), whereas the constructs in the PLIF approach used bilaterally placed CAPSTONE PEEK Spinal System implants (Medtronic, Inc.).

All the constructs were supplemented with BPS (CD HORIZON SOLERA Spinal System; Medtronic, Inc.). The pedicle screw (6.5 mm  $\times$  45–55 mm) that was used

was a multiaxial, top-loading, rigidly locking system, with a cobalt chrome screwhead and a titanium alloy (Ti-6Al-4V) shaft. A 4.75-mm diameter cobalt chrome rod was used. The interbody implants used in the LLIF and PLIF procedures varied to accommodate specific specimen anatomy height (PLIF, 10 mm; LLIF, 10–14 mm), width (PLIF, 10 mm; LLIF, 18 mm), and length (PLIF, 22–32 mm; LLIF, 50–60 mm). All implants were placed according to the manufacturer's recommendations using standard surgical techniques and instrumentation.

The LLIF surgical technique involved annulotomy and thorough discectomy, whereas the PLIF involved annulus incision to remove the disc and prepare the endplates. The appropriately sized PEEK interbody implants were inserted unilaterally in the LLIF construct and bilaterally in the PLIF construct. The interbody insertion was followed by supplemental posterior fixation using BPS, with anteroposterior fluoroscopy used to verify the correct screw trajectory.

### **Biomechanical testing**

In all conditions tested, specimens were studied using standard pure moment flexibility tests. For these tests, an apparatus was used in which a system of cables and pulleys imparted nondestructive, non-constraining torques in conjunction with a standard servohydraulic test system (MTS Systems Corp.), as we have described previously (5,6). This type of loading is distributed evenly to each motion segment, regardless of the distance from the point of loading (7,8). Maximum loads of 7.5 Nm were applied about the appropriate anatomical axes to induce the three different types of motion: flexion-extension, lateral bending, and axial rotation. Three preconditioning cycles were applied at 7.5 Nm for 60 seconds to allow for creep in each loading direction to ensure appropriate settling at the hardware-bone interface and to improve reproducibility of the results. During data collection, load was applied quasistatically in 1.5-Nm increments, with each incremental load held for 45 seconds to a maximum of 7.5 Nm (6).

Three-dimensional specimen motion in response to the applied loads during flexibility tests was determined automatically at 2 Hz using the Optotrak 3020 system (Northern Digital, Inc.). This system stereophotogrammetrically measures the three-dimensional displacement of infrared-emitting markers rigidly attached in a non-collinear arrangement to each vertebra. Custom software converts the marker coordinates to angles about

each of the anatomical axes in terms of the motion segment's own coordinate system (9). Spinal angles were calculated using a technique that provides the most appropriate results for describing three-dimensional spinal motion (10). When specimens were instrumented within each construct, fluoroscopy was used to ensure correct positioning of the hardware.

Three parameters were generated from the quasistatic load deformation data: angular ROM, zone of ligamentous laxity or lax zone (LZ), and zone of ligamentous stretching or stiff zone (SZ). The LZ and SZ are components of the ROM and represent the low-stiffness and high-stiffness portions of the typically biphasic load-deformation curve, respectively (10,11). The LZ is similar to Panjabi's neutral zone but is more reproducible and refers to the zone in which there is minimal ligamentous resistance, whereas the neutral zone is the zone in which there is only frictional joint resistance (7,8). Larger values of LZ, SZ, or ROM indicate greater instability.

### **Analysis**

The location at which LZ crossed to SZ was calculated by extrapolating the load deformation slope at data points corresponding to 4.5 Nm, 6.0 Nm, and 7.5 Nm to zero load using the method of least squares. Data were normalized such that each specimen served as its own control. Normalized values of LZ, SZ, and ROM were statistically analyzed using a one-way ANOVA, followed by Holm-Sidak tests, to determine whether outcome measures were significantly different among the various conditions of instrumentation. The level for statistical significance was set at  $P < 0.05$ .

### **Results**

No fractures were observed in specimens. No screws or rods demonstrated signs of fracture, loosening, or breakage in all conditions tested.

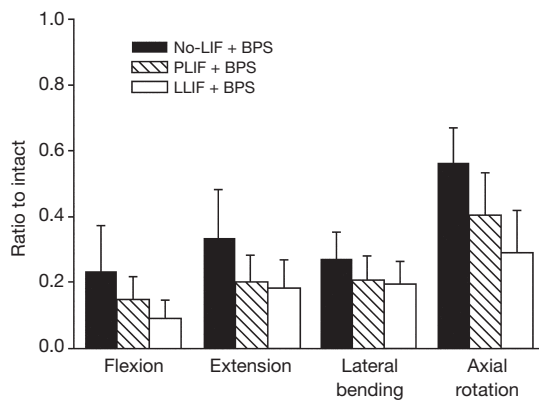
#### ***Instrumented constructs versus intact***

Compared to the intact condition, all three configurations of instrumentation greatly decreased the mobility in all directions of motion (*Table 1*). The mean reductions in mobility with LLIF + BPS were 91% in flexion ( $P < 0.001$ ), 82% in extension ( $P < 0.001$ ), 81% in lateral bending ( $P < 0.001$ ), and 71% in axial rotation ( $P < 0.001$ ). The corresponding reductions with PLIF + BPS were 86% flexion

**Table 1** Raw angular motion in degrees for the intact condition and for all three instrumented conditions at L3–L4 (non-normalized ROM)\*

Raw angular motion	Intact	No-LIF + BPS	PLIF + BPS	LLIF + BPS
Flexion	4.33±1.38	0.72±0.34	0.60±0.29	0.42±0.34
Extension	4.07±1.43	0.86±0.28	0.81±0.15	0.85±0.46
Lateral bending	5.31±1.51	1.50±0.63	0.90±0.13	1.04±0.41
Axial rotation	2.52±1.20	0.87±0.30	1.04±0.13	0.71±0.35

\* , values are mean ± SD. BPS, bilateral pedicle screws; LIF, lumbar interbody fusion; LLIF, lateral lumbar interbody fusion; No-LIF, no lumbar interbody fusion; PLIF, posterior lumbar interbody fusion; ROM, range of motion.



**Figure 1** Graph showing mean normalized range of motion (ROM) (i.e., ROM as a ratio to the intact condition) at L3–L4 during each loading mode and in each instrumented condition studied. Error bars show standard deviation of the ROM. BPS, bilateral pedicle screws; LLIF, lateral lumbar interbody fusion; No-LIF, no lumbar interbody fusion; PLIF, posterior lumbar interbody fusion. Used with permission from Barrow Neurological Institute, Phoenix, Arizona.

( $P < 0.001$ ), 80% extension ( $P < 0.001$ ), 80% lateral bending ( $P < 0.001$ ), and 60% axial rotation ( $P < 0.005$ ). For no-LIF + BPS compared to intact, mobility was decreased by 77% in flexion ( $P < 0.001$ ), 67% in extension ( $P < 0.001$ ), 73% in lateral bending ( $P < 0.001$ ), and 44% in axial rotation ( $P < 0.002$ ).

**LLIF construct versus no-LIF construct**

On the basis of our analysis of normalized values of motion (Figure 1, Table 2), LLIF + BPS was significantly more stable than no-LIF + BPS during flexion ( $P = 0.047$ ), extension ( $P = 0.049$ ), and axial rotation ( $P = 0.001$ ), but not during lateral bending ( $P = 0.13$ ). There were no significant differences between LLIF + BPS and no-LIF + BPS in terms of normalized SZ ( $P > 0.06$ ). The normalized LZ with LLIF + BPS was significantly less than with no-LIF

**Table 2** Comparison of P values for LZ, SZ, and ROM among LLIF, PLIF, and no-LIF (normalized data)\*

Comparison	LZ	SZ	ROM
<b>LLIF + BPS vs. no-LIF + BPS</b>			
Flexion	0.24	0.11	<i>0.047</i>
Extension	NA	0.46	<i>0.049</i>
Lateral bending	0.22	0.52	0.13
Axial rotation	<i>0.02</i>	0.06	<i>0.001</i>
<b>LLIF + BPS vs. PLIF + BPS</b>			
Flexion	0.24	0.11	0.31
Extension	NA	0.46	0.70
Lateral bending	0.22	0.52	0.13
Axial rotation	0.17	<i>0.01</i>	0.10
<b>PLIF + BPS vs. no-LIF + BPS</b>			
Flexion	0.24	0.11	0.23
Extension	NA	0.46	0.07
Lateral bending	0.22	0.52	0.13
Axial rotation	0.17	0.34	<i>0.04</i>

\* , by analysis of variance or Holm-Šidák test; italicized P values are significant. BPS, bilateral pedicle screws; LIF, lumbar interbody fusion; LLIF, lateral lumbar interbody fusion; LZ, lax zone; NA, not applicable; no-LIF, no lumbar interbody fusion; PLIF, posterior lumbar interbody fusion; ROM, range of motion; SZ, stiff zone.

+ BPS during axial rotation ( $P = 0.02$ ), with no significant differences in flexion and lateral bending ( $P \geq 0.22$ ).

**PLIF construct versus no-LIF construct**

The PLIF construct was significantly more stable than the no-LIF construct during axial rotation ( $P = 0.04$ ), with

no significant differences in flexion ( $P=0.23$ ), extension ( $P=0.07$ ), and lateral bending ( $P=0.13$ ). There were no significant differences between PLIF + BPS and no-LIF + BPS in LZ or SZ data ( $P\geq 0.11$ ).

### *LLIF construct versus PLIF construct*

The PLIF + BPS construct allowed similar normalized ROM to LLIF + BPS during flexion ( $P=0.31$ ), extension ( $P=0.70$ ), lateral bending ( $P=0.13$ ), and axial rotation ( $P=0.10$ ) (Figure 1). Normalized values of LZ and SZ were comparable ( $P\geq 0.11$ ) for LLIF and PLIF constructs, with the exception of significantly larger SZ ROM in axial rotation in the PLIF construct ( $P=0.01$ ).

## Discussion

Biomechanical studies have demonstrated the benefit of larger profile interbody implants in interbody fusion (12). Lateral approaches [e.g., LLIF, extreme lateral interbody fusion (XLIF)] enable insertion of a larger interbody device, without sacrificing posterior elements and with theoretically improved stability compared to that of smaller interbody implants [e.g., PLIF, transforaminal interbody fusion (TLIF)] inserted via dorsal approaches (4). Studies have shown that stand-alone fusion constructs are not sufficiently stable without supplemental fixation, with many authors recommending additional posterior fixation to enhance stability (13-16). Although comparisons of stability of stand-alone constructs have been made between PLIF and LLIF (1,17), no prior studies have compared their relative stability when augmented with BPS. The purpose of the present study was to compare the biomechanical stability of interbody fusion constructs using the LLIF + BPS and PLIF + BPS approaches in the presence of supplemental dorsal fixation.

Our study demonstrates a similar biomechanical profile for the LLIF + BPS construct in providing immediate post-implantation stability relative to the PLIF + BPS construct, with somewhat greater effectiveness in limiting axial rotation with LLIF + BPS. Relative to the no-LIF + BPS construct, the LLIF + BPS construct demonstrated consistently smaller ROM in all modes of testing except lateral bending; comparatively, the PLIF + BPS construct demonstrated smaller ROM in axial rotation, with no differences in flexion, extension, or lateral bending.

Prior studies have shown the stabilizing benefit of supplemental fixation across all interbody devices (13-16).

Laws *et al.* (18) demonstrated decreased ROM in flexion-extension and lateral bending, with increased stiffness approaching 350% in flexion and 220% in extension with the use of BPS along with an interbody implant in the LLIF approach. Fogel *et al.* (19) reported significant reductions in ROM in all loading modes with pedicle screw fixation after lateral interbody placement. Similarly, a comparative *in vitro* cadaveric study found that bilateral pedicle screw fixation dramatically improved stiffness in both the TLIF and the PLIF constructs; however, the PLIF construct demonstrated greater reductions, particularly in lateral bending. Despite the prevalence of pedicle screw fixation, a recent report by our group described comparable biomechanical stiffness of cortical screws and pedicle screws in both TLIF and LLIF constructs (6).

The stabilizing effect of posterior fixation may reduce biomechanical differences between interbody implants. Laws *et al.* (18) showed equivalent improvement in segmental stability, both with and without supplemental fixation, using the LLIF and the anterior lumbar interbody fusion (ALIF) approaches. Although the fusion construct had somewhat greater reduction in ROM with the LLIF than with the ALIF approach in all modes of testing without supplemental fixation, these results were not statistically significant. In comparison, Cappuccino *et al.* (1) reported minimal differences in biomechanical stability between the interbody fusion construct using the XLIF, ALIF, and TLIF constructs with supplemental bilateral posterior fixation. However, Pimenta *et al.* (17) found significant differences between fusion constructs supplemented with BPS using TLIF and XLIF approaches with larger interbody implants (26 mm, anterior-posterior width); and, with standard 18-mm implants, the XLIF construct demonstrated a significant reduction only in axial rotation. In our current study, no significant differences were observed between LLIF and PLIF constructs with BPS in ROM across all motion types; however, a comparison of interbody type (e.g., LLIF or PLIF) with no-LIF demonstrated a differential effect, with greater stabilization with LLIF + BPS *vs.* no-LIF + BPS than with PLIF + BPS *vs.* no-LIF + BPS.

Although the facet joint provides axial rotational resistance in the intact lumbar spine, studies have demonstrated that the partial bilateral facetectomy necessary for the PLIF approach does not significantly affect axial stability in a BPS-augmented setting (20). In our study, we observed a significant difference in SZ between LLIF + BPS and PLIF + BPS in axial rotation, suggesting that the larger footprint and lateral placement of the interbody implant

used in the LLIF construct may provide better stability than the smaller and anteroposteriorly placed bilateral PLIF device. Therefore, rather than providing facet joint preservation, the larger footprint of the laterally inserted interbody implant in the LLIF approach may contribute to improved stability, in part due to disc space distraction and greater tension on retained ligaments.

Limitations of our study design include the inherent constraints of an *in vitro* cadaveric model. Such model systems evaluate only the immediate stability of segmental fixation and cannot easily be extrapolated to construct longevity or fusion success. Additionally, the small sample size of the current study may affect the results and limit the generalizability of our findings, particularly given the increased average donor age, heterogeneity of underlying disease processes, and variable bone quality. Further study is needed to clarify our understanding of this model system and to contextualize our findings in clinical practice.

## Conclusions

This cadaveric biomechanical study directly compared the immediate postoperative stability between interbody fusion constructs using the LLIF and PLIF approaches in the presence of BPS. For most loading parameters, the LLIF construct demonstrated equivalence to the PLIF construct. Our data indicate that the interbody fusion construct using LLIF with dorsal supplemental fixation is a biomechanically equivalent alternative to conventional dorsal approaches to LIF.

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## Footnote

*Conflicts of Interest:* SW Chang receives royalties from Globus Medical, Inc., royalties from Biomet, Inc., consulting fees from LDR Holding Corp., and educational grants from Medtronic, Inc. V Singh is an employee of Medtronic, Inc. NR Crawford is an employee of Globus Medical, Inc. The other authors have no conflicts of interest to declare.

*Ethical Statement:* The authors warrant that this research conformed to the ethical principles of the Declaration of Helsinki. Neither institutional review board approval nor consent was deemed necessary due to the cadaveric nature of the study.

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