

# Group theoretic particle swarm optimization for multi-level threshold lung cancer image segmentation

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**Background:** Image segmentation is an important step during the processing of medical images. For example, for the computer aid diagnostic systems for lung cancer image analysis, the segmented regions of tumors would help doctors in early diagnosis to determine timely and appropriate treatment possibilities and thereby improve the survival rate of the patients. However, general clinical routines of manual segmentation for large number of medical images are very difficult and time consuming, which is the challenge we aim to tackle using our proposed method.

**Methods:** A novel image segmentation method with evolutionary learning technique named Group Theoretic Particle Swarm Optimization is proposed. It can tackle multi-level thresholding optimization problem during the segmentation process and rebuild the search paradigm according to the solid mathematical foundation of symmetric group from four designable aspects, which are particle encoding, solution landscape, neighborhood movement and swarm topology, respectively. The Kapur's entropy of multi-level thresholds is assessed as the objective function.

**Results:** In contrast to those conventional metaheuristics methods for lung cancer image segmentation, this newly presented method generates the best performance result among them. Experimental results show that its Kapur's entropy has the value of 9.07, which is 16% higher than the worst case. Computational time is acceptable at the cost of 173.730 seconds, average level of evaluation metrics [Kappa, Precision, Recall, F1-measure, intersection over union (IoU) and receiver operating characteristic (ROC)] is over 90%, and search process of multi-level threshold combination would finally converge in the later phase of iterations after 700. The ablation study indicates that all components are significant to the contributions of our proposed method.

**Conclusions:** Group Theoretic Particle Swarm Optimization for multi-level threshold segmentation is an efficient way to split a medical image into distinct regions and extract tumor tissues regions from the background. It maintains the balanced relationship between diversification and intensification during the search process and helps clinicians to make the diagnosis more accurately. Our proposed method processes potential medical value and clinical meanings.

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**Keywords:** Lung cancer detection; medical image segmentation; metaheuristic; evolutionary computation; group theory

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## Introduction

Image segmentation involves partitioning an image into multiple objects with meaningful structures in the homogeneous regions according to specific quantitative criteria (1-3). For medical image analysis, in order to help clinicians to make the diagnosis more accurately, the segmentation is a necessary step in advancing on which the quality of the diagnosis and analysis system depends (4,5).

There are numerous types of medical image modalities (6), for example ultrasound (US), X-ray, positron emission tomography (PET), computed tomography (CT), magnetic resonance imaging (MRI), etc. The characteristics of medical images consist of several factors, such as contrast, blur, noise, artifacts, distortion, etc. They represent main features of an image and determine its quality (7). As for lung cancers, about 30-40% of them are adenocarcinoma, which is a typical category of non-small cell lung cancer (NSCLC). The characteristic appearances of lung cancer images are the slow growth of a localized ground glass opacity and the rapid increment of a solid mass (8). And many promising technologies have been developed for detecting those appearance changes of medical image in segmentation tasks with remarkable performance, they range from traditional approaches, like thresholding, edgebased extraction, histogram-based bundling and watershed, region-based growing, to more superior methods, like active contour models, sparse representations, conditional and Markov random fields, graph cuts, deep learning-based algorithms (9-12). Although there exist many excellent methods like deep learning approaches, they still have some inevitable issues, for example, the results heavily depend on complex model structure and parameter configuration. The generalization of trained models is limited because of the huge cost of computational resources and reconstruction of deep models when dealing with heterogeneous data and objective functions during segmentation. Besides, a class of metaheuristic methods treat and reformulate the segmentation problems intrinsically as the global optimization, focusing on complicated objective functions with characteristics of noisy, non-continuous, non-convex and multi-modal information from a medical image (13). Metaheuristic is still one of the mainstreams of medical image segmentation since it has the ability to incorporate multiple criteria in objective function terms, the capacity to measure the qualities of different solutions and offer the trade-off between them by examining the quantitative metrics that a solution satisfies the specific criterion, and the availability to provide self-adaptive parameter configuration without too much background knowledge (14).

For multi-level threshold technologies in medical image segmentation, a method where the non-parametric multilevel variance that is maximized between classes during segmentation procedure is developed by Otsu (15), and after that, Kapur et al. (16) improve branch of method by introducing entropy and probability distribution of the image histogram into it. The Ant Colony Optimization (ACO) can boost the performance of optimal solution compared to the traditional one with Otsu-based multilevel image thresholding (17). Objective functions such as Otsu, Kapur and Tsallis entropy are fed into the efficient Krill Herd Algorithm (KHA) to search for the best values of threshold and it can prevent the drawbacks of single target function (18). Similar to this, an efficient Cuckoo Search Algorithm (CSA) is proposed for segmentation problem with multiple objectives functions (19). Partitioned-Cooperative Quantum-behaved Particle Swarm Optimization (SCQPSO) for auxiliary swarm and the search space is designed to achieve rapid convergence by shifting the mode of particle update (20). Chaotic Salp Swarm Algorithm (CSSA) is embedded into the combined model as the core to optimize the feature matrix obtained from two-dimensional (2D) curvelet transformation for segmentation (21). Multi-Leader Whale Optimization Algorithm (MLWOA) aims to overcome the drawbacks of traditional WOA during the segmentation process (22).

Despite good amount of works achieved by those researchers, we are still facing some critical shortcomings other than stagnation at local optimum or slow convergence. One of them is that most of the improvements enhance either the diversification (exploration) or intensification (exploitation)



Figure 1 Four-layered hierarchical partitioning of the solution space.

during the search, which will influence the performance of search algorithms and the qualities of optimal solutions. This also motivates us to propose a new method based on new mathematical foundation, aiming to enhance the balance between them and facilitate the overall efficiency of search.

The purpose of this article is to introduce a novel metaheuristic approach named Group Theoretic Particle Swarm Optimization (GT-PSO) (23), for multi-level threshold optimization in medical image segmentation. With the basic concepts of symmetric group, the search space would be decomposed exhaustively and exclusively, and the process can continue under the guidance of function composition-based operators and equilibrium evolution of both local and global search. Finally, it will reach the goal of finding the optimal combination of multi-level threshold. The main contributions of this article are summarized as follows: the search paradigm is rebuilt on the solid foundation of group theory, and hierarchical decomposition is carried out to generate corresponding operators and evolution strategies for guiding the search procedure. The rest of this article is organized as follows: the "Methods" section describes the details about GT-PSO methodology; the "Results" section presents the experimental results; the "Discussion" section analyzes the performances and discusses the properties of the proposed method; the "Conclusions" section concludes the paper. We present the following article in accordance with the TRIPOD reporting checklist (available at https://gims.amegroups.com/article/

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#### **Methods**

#### Particle encoding

The mapping function is designed for encoding the particles in the form of permutation with cycles of symmetric group of degree n, which is also the dimension of the objective function:

$$p = \left(p(x_1)p(x_2)\cdots\right)\cdots\left(\cdots p(x_{n-1})p(x_n)\right)$$
[1]

The encoded vector in each particle is regarded as a potential candidate of the solution.

#### Solution landscape

In terms of symmetric group theory, four-layered hierarchical method is applied to decompose the solution space into various partitions at different levels, which are conjugacy class, cyclic form, orbital plane and orbit, respectively (*Figure 1*).

Conjugacy class is the first order partition of hierarchy with the structure of numerous cyclic factors denoted by the factor form:

$$cnj = 1^{k_1} 2^{k_2} \cdots i^{k_i} \cdots n^{k_n}, \forall i \in [1, n], k_i \in [0, n]$$

$$\sum_{i=1}^n ik_i = n$$
[2]

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Figure 2 Neighborhood movement guided by four hierarchical operators in the solution space.

Cyclic form is the second order partition of hierarchy based on the permutation of cyclic factors denoted by the cyclic form:

$$cyc = (x_1 \ x_2 \cdots) \cdots (\cdots x_{n-1} x_n)$$
<sup>[3]</sup>

Orbital plane is the third order partition of hierarchy where the elements in partition set X are same under two group actions of  $g_1$  and  $g_2$ :

$$obp = \{X_k\}, iff X_i(g_1) = X_i(g_2), \forall i \in [1,k]$$

$$[4]$$

Orbit is the fourth order partition of hierarchy as the collection of all elements by group action g from a given group G:

$$obt = \{gx \mid g \in G\}, \forall x \in X$$

$$[5]$$

Notice that four-layered hierarchy is the complete partitioning of the solution landscape, every partition is unique and exclusive to each other.

# Neighborhood movement

The movement of a particle happens when the specific group action is used on the incumbent solution to change the permutation of original particle. Four types of operators are created based on four-layered hierarchical partitions. Movement details are illustrated in *Figure 2* following the corresponding explanation below.

Conjugator operator shifts the particle to another conjugacy class, as shown with blue arrow (*Figure 2*). It is an inter conjugacy class operator of exploration.

Cycler operator moves the particle across different cyclic forms, as shown with red arrows (*Figure 2*). It is an intra conjugacy class and inter cyclic form operator of exploration.

Planer operator changes the particle from one orbital plane to another, as shown with green arrows (*Figure 2*). It is an intra cyclic form and inter orbital plane operator of exploitation.

Orbiter operator searches the particle along the orbit one by one, as shown with yellow arrows (*Figure 2*). It is an intra orbital plane and inter orbit operator of exploitation.

Four operators cooperate with each other to move neighborhoods heuristically in the hierarchical partitioned solution space (*Figure 2*).

#### Swarm topology

Let  $\nabla$  denote the operator based on various group actions by group multiplication  $\otimes$ , then the swarm evolutionary process is formulated as:

$$\nabla = (r_1 \nabla_{cnj}) \otimes (r_2 \nabla_{cyc}) \otimes (r_3 \nabla_{obp}) \otimes (r_4 \nabla_{obt})$$
[6]



**Figure 3** Flowchart of GT-PSO. GT-PSO, Group Theoretic Particle Swarm Optimization; Y, yes; N, no; P<sub>best</sub>, personal best; G<sub>best</sub>, global best.

$$v_{k+1}^{i} = \nabla \otimes v_{k}^{i} + r_{5} \left( p_{k}^{i} - x_{k}^{i} \right) + r_{6} \left( p_{k}^{g} - x_{k}^{i} \right)$$
[7]

$$x_{k+1}^{i} = x_{k}^{i} + v_{k+1}^{i}$$
[8]

where *r* is the random number, *i* is the particle index, *k* is the iteration count,  $P_k^i$  is the local best fitness of *i*<sup>tb</sup> particle after *k* iterations and  $P_k^g$  is the global best fitness of the entire swarm after *k* iterations. GT-PSO would initialize the entire swarm randomly with a particular number of particles whose representations are variable length encoding, and it will assess the fitness score by setting those best values of all particles. And then it can decompose the solution space hierarchically and generate the corresponding operators. They run concurrently to move the neighborhoods of particles in the solution space, and the self-adaptive evolutionary strategy is guaranteed

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by parameter configuration to make the updates of velocity and position. The whole search would be stopped when stopping conditions are satisfied, which can be configured to for example, when the maximum iteration number is reached, or the minimum error rate is achieved. The detailed flowchart of GT-PSO is demonstrated in (*Figure 3*).

# **Objective function**

The popular measurement of Kapur's entropy is evaluated as the objective function of medical image segmentation formulated as:

$$H(\theta_1, \theta_1, \cdots \theta_m) = H_0 + H_1 + \cdots + H_m$$
[9]

where:

$$H_{0} = -\sum_{i=0}^{\theta_{i}-1} \frac{p_{i}}{\omega_{0}} \ln \frac{p_{i}}{\omega_{0}}, \omega_{0} = \sum_{i=0}^{\theta_{i}-1} p_{i}$$
[10]

$$H_1 = -\sum_{i=\theta_1}^{\theta_2-1} \frac{p_i}{\omega_1} \ln \frac{p_i}{\omega_1}, \quad \omega_1 = \sum_{i=\theta_1}^{\theta_2-1} p_i$$
<sup>[11]</sup>

$$H_m = -\sum_{i=\theta_m}^{L-1} \frac{p_i}{\omega_m} \ln \frac{p_i}{\omega_m}, \omega_m = \sum_{i=\theta_m}^{L-1} p_i$$
[12]

$$p_{j} = \frac{h_{j}}{\sum_{j=0}^{L-1} h_{j}}$$
[13]

*j* is the grayscale index, *L* is the upper bound of grayscale,  $b_j$  is the number of pixels and  $p_j$  is the probability distribution of  $j^{ib}$  grayscale. *i* is the segmentation class index,  $\theta_i$  is the  $i^{ib}$  threshold,  $w_i$  is the cumulative probability and  $H_i$  is the entropy of  $i^{ib}$  segmentation class. The optimization task of segmentation is to maximize  $H(\theta_1, \theta_1, \dots, \theta_m)$ . The notations of GT-PSO components are listed in (*Table 1*).

#### Parameter configuration

The proposed GT-PSO is compared to Tabu Search (TS), Genetic Algorithm (GA), Particle Swarm Optimization (PSO) and Differential Evolution (DE). The parameter configuration for every method is presented in (*Table 2*).

The study was conducted in accordance with the Declaration of Helsinki (as revised in 2013). This study was approved by our institutional review board. Informed consent was waived.

#### Results

As a case study of the effect of the proposed GT-PSO, the

Table 1 Notations of GT-PSO components

Notation	Remark
p	Particle encoding
X	Permutation set
g	Group action
$\otimes$	Group multiplication
cnj	Conjugacy class
сус	Cyclic form
obp	Orbital plane
obt	Orbit
$\nabla$	Operator

GT-PSO, Group Theoretic Particle Swarm Optimization.

Table 2 Parameter values of compared methods

Method	Parameter	Value
TS	Tabu list	20, 30
GA	Mut rate	0.3, 0.4
	Tour rate	0.1, 0.2
DE	Cross prob	0.2, 0.4
	Low bound	0.2, 0.3
	High bound	0.7, 0.8
PSO	Inertial weight	0.8, 1.2
	Acc coeff	1.2, 1.5
GT-PSO	Random 1&2	0.5, 0.8
	Random 3&4	0.2, 0.5
	Acc coeff	1.2, 1.5
	Pop size	20, 30

DE, Differential Evolution; GT-PSO, Group Theoretic Particle Swarm Optimization; GA, Genetic Algorithm; TS, Tabu Search; Mut, mutation; prob, probability; Acc coeff, acceleration coefficients; Pop, population.

dataset of lung cancer MRI has been considered as the tested images. The illustrated result is based on the image #311 (*Figure 4A*) extracted from the dataset archive of Iraq-Oncology Teaching Hospital/National Center for Cancer Diseases (IQ-OTH/NCCD), which contains 110 cases of 1,190 images. The detail description of data archive is shown in (*Table 3*).

During the segmentation process, the GT-PSO has

identified three distinct classes of image with two levels of thresholds that just reside in the trough between two crests of grayscale distribution, and the illustration of final histogram of segmentation is shown in (Figure 4B), The optimized thresholds  $\theta_1$  and  $\theta_2$  obtained by GT-PSO in grayscale distribution are 118 and 182 respectively. The contour of sick region is detected and segmented from the background tissues in the right part of (*Figure 4C*). PSO is chosen as the baseline model compared to GT-PSO on the same image #311 (Figure 4D) because GT-PSO is the enhanced version of PSO based on group theory foundation. The optimized thresholds  $\theta_1$  and  $\theta_2$  obtained by PSO in grayscale distribution are 87 and 206 respectively (Figure 4E), and in contrast to the visualization of GT-PSO, the contour of sick region extracted by PSO has more noises and dark dots from the background (Figure 4F), causing the blurred quality of segmentation result. After 1,000 iterations of the search of multi-level threshold with variable numbers of feasible threshold combinations in each particle (Figure 5).

The numerical metrics of experimental results generated by those compared methods (TS, GA, DE, PSO and GT-PSO) are tabulate in (*Table 4*). The Kapur's entropy is the same as pixel accuracy for segmentation evaluation.

As shown in (*Figure 5*), GT-PSO outperforms all the other compared methods on the tested image archives. The behavior of GT-PSO increases gradually in the early and middle of the search and gets converged in the last one third of the iterations around 700. Although its raising speed is not as fast as PSO and GA before the number of iterations about 300, GT-PSO still performs the best during the rest of the search process. And it is followed by the outcome of DE, which has the second-best performance of all compared methods. PSO and GA come to the next two rankings where TS shows the worst output among them.

The result of comparison of fitness values with Kapur's entropy and time consumptions of all compared methods are displayed in (*Table 4*). It also proves the illustrated results (*Figure 5*) simultaneously, where GT-PSO generates the superior Kapur's entropy of 9.07 at the acceptable time cost of 173.730 seconds. Without the consideration of running time, its achievement is 3% higher than DE and 16% higher than TS almost. As the time cost is concerned, GT-PSO still has balanced performance between fitness value and time consumption compared to others. Its average level of other evaluation metrics of Kappa, Precision, Recall, F1-measure, intersection over union (IoU) and area under the curve (AUC) is over 90%.

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**Figure 4** The tested image (A), histogram with multi-level thresholds (B) by GT-PSO, segmentation result by GT-PSO (C), and the same tested image (D), histogram with multi-level thresholds (E) by PSO, segmentation result by PSO (F). GT-PSO, Group Theoretic Particle Swarm Optimization.

Table 3 Image descriptions of IQ-OTH/NCCD				
Image	Number			
Train	800			
Validate	200			
Test	190			
Cross-validation	10-fold			

IQ-OTH, Iraq-Oncology Teaching Hospital; NCCD, National Center for Cancer Diseases.

As shown in (*Figure 6*), the ablation study of GT-PSO is implemented via removing two categories of components gradually from the entire algorithm. GT-PSO is an enhanced method of conventional PSO rebuilt on group theory foundation, and there are four kinds of operators: *cnj*, *cyc*, *obp* and *obt*, where the previous two belong to the category of diversification and the latter two are intensified operators. GT-PSO outperforms the other three without any one module or both, its Kapur's entropy is 9.07 while



**Figure 5** Fitness curves with Kapur's entropy of compared methods. GT-PSO, Group Theoretic Particle Swarm Optimization; DE, Differential Evolution; TS, Tabu Search; GA, Genetic Algorithm.

the value for worst case is only 7.51, and the gap between them is more than 20%. For detailed results of evaluation metrics please refer to (*Table 5*).

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I able 4         Fitness values with Kapur's entropy and multiple metrics of compared methods									
Method	Kapur's entropy	Kappa	Precision	Recall	F1-measure	loU	AUC	Time (s)	
TS	7.799	0.651	0.855	0.848	0.847	0.718	0.834	90.120	
GA	8.257	0.778	0.864	0.859	0.859	0.794	0.877	158.250	
DE	8.801	0.860	0.917	0.917	0.917	0.866	0.940	151.920	
PSO	8.568	0.821	0.893	0.892	0.892	0.832	0.916	142.830	
GT-PSO	9.069	0.898	0.945	0.945	0.945	0.902	0.957	173.730	

Table 4 Fitness values with Kapur's entropy and multiple metrics of compared methods

DE, Differential Evolution; GT-PSO, Group Theoretic Particle Swarm Optimization; GA, Genetic Algorithm; TS, Tabu Search; IoU, intersection over union; AUC, area under the curve.



Figure 6 Fitness curves with Kapur's entropy of ablation study of GT-PSO. GT-PSO, Group Theoretic Particle Swarm Optimization; w/o, without; inten, intensification; diver, diversification.

#### Discussion

As we know, the multi-level threshold image segmentation can be regarded as the problem of combinatorial optimization of various thresholds within the range of grayscale boundary to some certain extent. Meanwhile GT-PSO is originally designed for combinatorial optimization based on symmetric group definitions and concepts, thus it is also suitable for similar type of image segmentation tasks. This is the main reason why GT-PSO outperforms all the other comparison methods in our experiment (Table 4). Another reason of this superior achievement of GT-PSO is that the comparison methods are practical for solving continuous optimization problems with appropriate real number encoding, while the multi-level thresholding is actually considered as discrete optimization problem. GT-PSO can provide more suitable encoding and updating approaches with the mathematical foundation

of symmetric group. During the early procedure of GT-PSO, since the conjugacy class and cyclic form operators dominate the search according to the parameter setting in (Table 2), it gets a relatively slow slope when iteration number increases, which indicates that the search is in the exploration stage and the solution diversities are maintained in order to reach more regions in the solution landscape. Furthermore, the orbital plane and orbit operators act as the major components of particle movements and intensify the search to converge in the exploitation stage. Meanwhile, the intermedia results displayed in (Figure 6) has the best numerical evidence for that, and both modules of diversification and intensification are necessary to the efforts of GT-PSO. The shape of GT-PSO curve in (Figure 5) demonstrates the self-adaptive strategy of swarm evolution of balanced optimization between exploration and exploitation.

For the rest of the comparison methods, DE and GA belong to the same class due to their evolutionary essences of selection, crossover, mutation, etc. Same for PSO and GT-PSO which both belongs to swarm intelligence optimization algorithm, and as result their curves share similar shapes and trends. In addition, TS is the single and non-population-based metaheuristic algorithm belonging to an independent branch besides the two classes previously mentioned, and its performance heavily relies on the local search ability controlled by tabu list memory, so it would suffer the stagnation at local optimum and the premature convergence during the search process.

Compared to GA, PSO seems to have better outcome because of its easier update mechanism and less parameter configuration. And DE shows a slower converging rate in the early phase compared to GA, probably caused by the mutant information of differential vectors of

10010 0 1 101000 1	There is a finite so which have a second s							
Method	Kapur's entropy	Kappa	Precision	Recall	F1-measure	loU	AUC	Time (s)
GT-PSO	9.073	0.796	0.916	0.907	0.907	0.870	0.976	184.560
w/o diver	8.253	0.614	0.837	0.825	0.820	0.757	0.914	136.950
w/o inten	8.621	0.738	0.866	0.861	0.859	0.821	0.919	150.770
w/o both	7.509	0.541	0.800	0.751	0.713	0.692	0.822	103.520

Table 5 Fitness values with Kapur's entropy and multiple metrics of ablation study of GT-PSO

AUC, area under the curve; GT-PSO, Group Theoretic Particle Swarm Optimization; diver, diversification; inten, intensification; IoU, intersection over union; w/o, without.

parents of DE, whereas the mutation of GA is directly based on fitness values of parents. So, in the beginning of the search, the vast majority of search information is focused on diversification and the differential values are relatively high, and it leads to the slower converging rate of DE. There is also a fatal problem for DE: it is very sensitive to the noisy raw data, and it would affect the behavior to some degrees. Despite the slower converging rate and random nature of search, DE would eventually outperform GA during the progressively growing iteration process.

The analysis of time complexity of GT-PSO is conducted as follows. Assuming that the dimension of objective function is *n* and its evaluating cost is *cof*, the swarm population is *p* and the maximum iteration number is k. In the initialization phase the time complexity of GT-PSO (Figure 3) is  $T_{ini} + T_{eva} + T_{set} = O[p * (n + cof)], \text{ and time complexity of each}$ operator is  $T_{cnj} = T_{cyc} = T_{obp} = T_{obt} = O(p * n)$  since each of them is the linear rearrangement of threshold combination. Then in a single iteration phase the time complexity of GT-PSO should be  $T_{out} + T_{eva} + T_{und} = O[p*(n+cof)]$ , therefore the total time complexity would be O[k \* p \* (n + cof)]. In image segmentation, the objective function is to assess the Kapur's entropy with the polynomial time complexity of  $O(n^2)$  at least, which is directly proportional to the size of the input image. Finally, the time complexity of GT-PSO for image segmentation is  $O(k * p * n^2)$ .

We would like to discuss and analyze the superiorities of our proposed method along with its shortcomings and challenges to come in the following list.

#### **Contributions**

Proposed method partitions the space completely and

approach global optimum accordingly;

- Proposed method statistically guarantees to find an optimal solution through mathematical proof;
- Proposed method is flexible to restrictive properties of the model and parameters, and versatile for practical discrete optimizations.

#### Challenges

- Proposed method does not yet guarantee completely to find the real global optimum solution during the search;
- Proposed method could possibly cost over-acceptable computational time when the objective function is extremely complex.

Optimization is one of the fundamental technologies for computer vision and machine learning tasks in general, and for these techniques in medical use. As a new search paradigm, we believe GT-PSO has decent potential and practical value for various medical applications. For example, in organ segmentation task, it can be applied for the process of feature selection, feature fusion, attenuation correction and intensity normalization in data preprocessing step. And in data augmentation step, it would reduce over-fitting and increase samples by optimizing distortion, elastic deformation and noise contamination. The optimizer of back-propagation in deep learning can be replaced by GT-PSO, as well as model structure optimization. The nature of hierarchy of GT-PSO would lead to the parallel search for multi-objective detection in organ segmentation.

#### Conclusions

A novel multi-level threshold image segmentation method using symmetric group theory-based metaheuristic is proposed to solve the combinatorial optimization problem of multiple grayscale thresholds of medical images. GT-PSO would generate a new search paradigm and improve the efficiency from four designable aspects: particle encoding, solution landscape, neighborhood movement and swarm topology. A case study of lung cancer CT image archive is conducted to demonstrate the performance of our proposed GT-PSO comparing to other metaheuristics algorithms. The ablation study is fulfilled to check the intermedia efforts of two major components of GT-PSO. Overall, the experimental results show that GT-PSO achieves the best performance and keep the equilibrium between exploitation and exploration, therefore we believe it has decent potential for interdisciplinary applications of clinical medicine and artificial intelligence.

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## Footnote

*Reporting Checklist:* The authors have completed the TRIPOD reporting checklist. Available at https://qims.amegroups.com/article/view/10.21037/qims-22-295/rc

*Conflicts of Interest:* All authors have completed the ICMJE uniform disclosure form (available at https://qims. amegroups.com/article/view/10.21037/qims-22-295/coif). The authors have no conflicts of interest to declare.

*Ethical Statement:* The authors are accountable for all aspects of the work in ensuring that questions related to the accuracy or integrity of any part of the work are appropriately investigated and resolved. The study was conducted in accordance with the Declaration of Helsinki (as revised in 2013). This study was approved by our institutional review board. Informed consent was waived.

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