

# Low-dose spectral reconstruction with global, local, and nonlocal priors based on subspace decomposition

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**Background:** Multienergy computed tomography (MECT) is a promising imaging modality for material decomposition, lesion detection, and other clinical applications. However, there is an urgent need to design efficient and accurate algorithms to solve the inverse problems related to spectral reconstruction and improve image quality, especially under low-dose and incomplete datasets. The key issue for MECT reconstruction is how to efficiently describe the interchannel and intrachannel priors in multichannel images.

**Methods:** In this model, in order to correlate the similarities of interchannel images and regularize the multichannel images, the global, local, and nonlocal priors are jointly integrated into the low-dose MECT reconstruction model. First, the subspace decomposition method first employs the global low-rankness to map the original MECT images to the low-dimensional eigenimages. Then, nonlocal self-similarity of the eigenimages is cascaded into the optimization model. Additionally, the L0 quasi-norm on gradient images is incorporated into the proposed method to further enhance the local sparsity of intrachannel images. The alternating direction method is applied to solve the optimization model in an iterative scheme.

**Results:** Simulation, preclinical, and real datasets were applied to validate the effectiveness of the proposed method. From the simulation dataset, the new method was found to reduce the root-mean-square error (RMSE) by 42.31% compared with the latest research fourth-order nonlocal tensor decomposition MECT reconstruction (FONT-SIR) method under 160 projection views. The calculation time of an iteration for the proposed method was 23.07% of the FONT-SIR method. The results of material decomposition in real mouse data further confirmed the accuracy of the proposed method for different materials.

**Conclusions:** We developed a method in which the global, local, and nonlocal priors are jointly used to develop the reconstruction model for low-dose MECT, where the global low-rankness and nonlocal prior are cascaded by subspace decomposition and block-matching, and the L0 sparsity is applied to express the local prior. The results of the experiments demonstrate that the proposed method based on subspace improves computational efficiency and has advantages in noise suppression and structure preservation over competing algorithms.

**Keywords:** Multienergy computed tomography (MECT); image reconstruction; global priors; local and nonlocal priors; subspace decomposition

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#### Introduction

Recently, multienergy computed tomography (MECT) has attracted increasing attention due to its great potential in medical imaging, especially in medicine and surgery, for its capabilities in quantitative material decomposition (1-3). Dual-energy CT (DECT) is one of the most common uses of MECT and can be implemented with dual-energy fast kilovoltage peak (kVp) switching and dual-layer sandwich detectors (4-7). However, it is limited by the use of energyintegrating detectors. The last decade has witnessed the promising development of a new type of MECT equipped with photon-counting detectors (PCDs), which have an energy separation capability in narrow energy bins (8,9). Nevertheless, image qualities are still unsatisfactory due to the low signal-to-noise ratios caused by photon pile-up, charge sharing, fluorescence effect, and photon scattering, which make the material maps suffer from severe noise (10). Therefore, developing efficient and accurate methods to improve image quality is a growing concern in the MECT field.

High-quality reconstruction from noisy and incomplete MECT measurements is a challenging problem. Regularizers encoding the image priors are typically introduced to improve reconstruction stability. For reconstruction in MECT, the popular priors can be categorized as global, local, and nonlocal. Note that the theoretically strict definitions of local and nonlocal priors are unclear. We attempt to classify them according to the ranges of the pixels for computing the regularization function for a target pixel in an image, as detailed in the Appendix 1. With the development of compressed sensing theory (11), many methods based on sparse regularization, such as L0 quasi-norm, total variation (TV) (12), wavelet (13), dictionary learning (14), and other sparse transformations, have been proposed to explore the local property in conventional CT. The sparsity-based regularization can also be used as local priors for each energy bin to reduce image noise in MECT directly. For instance, in 2012, Xu et al. reconstructed the region of interest (ROI) from MECT images by applying a TV penalty (15) to each energy channel. In 2013, Zhao et al. (16) proposed an iterative method based on tight frame (TFIR) to reconstruct higher image quality for sparse-view spectral breast CT. In 2016, Yu et al. (17) extended prior image constraint compressed sensing (PICCS) with TV regularization to spectral CT imaging (spectral PICCS) by introducing a high-quality spectral mean image to improve image quality. In 2018, Niu et al. (18) combined total generalized variation

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with a prior image to develop an iterative reconstruction for photon-counting CT, and more recently, Wang *et al.* (19) further used the image-gradient L0 quasi-norm and PICCS algorithm to design a weight adaptive method (L0-ASPICCS) for low-dose MECT in 2020.

Global low-rankness naturally exists in the MECT images due to the strong correlations of the interchannel. To improve the image quality, the local prior and global low-rankness can be modeled in the MECT reconstruction. More precisely, in 2014, Li *et al.* (20) established a tensor form reconstruction model containing prior rank, intensity, and sparsity (tPRISM) for MECT, which is an extension of PRISM (21). Semerci *et al.* (22) used the tensor nuclear norm-based iterative reconstruction method to efficiently measure the similarity of MECT images in the spectral domain. In 2015, Rigie and La Rivière (23) further applied the total nuclear variation to reconstruct MECT images with a convex penalty on common edge positions and a shared gradient direction among different channels.

Over the past decade, the idea of nonlocal self-similarity among image patches has been developed as another powerful tool. It has been fully exploited in nonlocal means, block-matching and 3D filtering (BM3D) in image denoising, image recovery, and deblurring (24-26). The research on nonlocal self-similarity also shows promising potential in MECT imaging. In 2015, Kim et al. (27) constructed 3-dimensional patches using selfsimilarity in the multichannel and carried out sparse-view MECT reconstruction with a low-rank penalty. Moreover, in 2016, as an improved version of dictionary learning, tensor dictionary learning (TDL) was proposed for MECT reconstruction to guarantee effective tissue structure preservation and noise suppression (28). In 2018, Wu et al. (29) combined the L0 quasi-norm with TDL (L0TDL) for low-dose MECT reconstruction, particularly in the sparse view; Niu et al. (30) also use a nonlocal method with low-rank regularization to improve the image quality of MECT. Wu et al. (31) further developed a nonlocal lowrank method based on cube tensor factorization (NLCTF) to obtain better image quality in MECT. More recently, in 2019, Xia et al. (32) proposed a method, called aided by self-similarity in image-spectral tensors (ASSIST), in which each tensor was decomposed into a low-rank component and a sparse component for MECT reconstruction. Hu et al. (33) developed a spectral image similarity-based tensor with an enhanced sparsity reconstruction (SISTER) method by extracting similar blocks that adopted alternating least square-based Candecomp/Parafac (ALS-CP)

**Table 1** Summary of a few representative MECT reconstructionmethods with different priors

Mathada	Type of prior				
Methods	Global	Local	Nonlocal		
TFIR (16)		$\checkmark$			
L0-ASPICCS (19)		$\checkmark$			
tPRISM (20)	$\checkmark$	$\checkmark$			
Semerci et al. (22)	$\checkmark$	$\checkmark$			
L0TDL (29)		$\checkmark$	$\checkmark$		
NLCTF (31)	$\checkmark$		$\checkmark$		
ASSIST (32)			$\checkmark$		
SISTER (33)		$\checkmark$	$\checkmark$		
WATITF (35)	$\checkmark$	$\checkmark$	$\checkmark$		
Zhang <i>et al.</i> (36)		$\checkmark$	$\checkmark$		
FONT-SIR (37)			$\checkmark$		
The proposed	$\checkmark$	$\checkmark$	$\checkmark$		

MECT, multienergy computed tomography; TFIR, tight frame iterative reconstruction; L0-ASPICCS, L0 norm-based adaptive spectral prior image constrained compressed sensing; tPRISM, tensor prior rank, intensity, and sparsity model; L0TDL, L0 norm-based tensor dictionary learning; NLCTF, nonlocal lowrank cube-based tensor factorization method; ASSIST, aided by self-similarity in image-spectral tensors; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction.

decomposition (34) to improve the MECT image quality. In 2020, Wu *et al.* (35) used weight-adaptive TV with spectral tensor factorization in nonlocal prior (WATITF) to improve the image quality of small animal imaging. Zhang *et al.* (36) combined the CP decomposition with intrinsic tensor sparsity regularization to exploit the nonlocal similarity and expressed spatial sparsity through TV regularization for a PCD-based MECT reconstruction. Chen *et al.* (37) further proposed a fourth-order nonlocal tensor decomposition model (FONT-SIR) for MECT reconstruction in 2021.

*Table 1* is list of some representative methods, including the various priors mentioned above. The methods described tend to adopt different types of priors. The listed methods have achieved relatively better performance than have those of the traditional analytical and typical iterative methods using purely local priors. However, their image qualities for various clinical application are still not adequate, and their use of local and nonlocal priors typically requires high computation complexity.

We propose a reconstruction model that exploits the complementary merits of the global, local, and nonlocal priors to improve the image quality with lower computational complexity. High correlations exist in different channels of MECT images, which means that the full MECT images can be expressed or represented by a low-rank subspace (38,39). In this paper, the global and nonlocal regularizations are proposed based on the low-rank subspace decomposition. The most advantageous property of subspace decomposition is that the main features (e.g., detail structures in the image) can be effectively extracted and enhanced, while the global random noise can be suppressed. This method can also improve computational efficiency since the subspace decomposition transfers the global data into a low-rank subspace. In our work, the global low-rankness and nonlocal self-similarity of interchannel images are cascaded through subspace decomposition and nonlocal block-matching. Furthermore, the local spatial sparsity of intrachannel images is also integrated into the model to maintain structure while suppressing noise. The alternating direction method is used to solve the model iteratively.

#### **Methods**

#### MECT reconstruction with different priors in parallel

Lowercase letters and boldface lowercase letters (e.g., a and  $\alpha$ ) are used to denote scalars and vectors, respectively. Matrices and tensors are denoted as capital letters, and calligraphic letters (e.g., A and  $\mathcal{X}$ ).  $\|\cdot\|_0$ ,  $\|\cdot\|_2$  are used to represent the L0 quasi-norm and L2 norm of a vector, respectively.  $\|\cdot\|_F$  is defined as the Frobenius norm of a matrix. Let  $X = [\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_s]' \in \mathbb{R}^{S \times N_p}$  represent MECT images of all S channels, where the row  $\mathbf{x}_s, s = 1, 2, ..., S$  of X is the vectorized single-channel CT image with  $N_p$  pixels.  $x \in \mathbb{R}^{S \times \sqrt{N_p} \times \sqrt{N_p}}$  denotes the 2-dimensional MECT images of all S channels.

Ignoring the detector response and other effects, the forward projection model is considered the following discretized linear system at S narrow energy windows in MECT:

$$A\boldsymbol{x}_s + \boldsymbol{e}_s = \boldsymbol{b}_s, \quad s = 1, 2, \dots, S$$
<sup>[1]</sup>

where  $A \in \mathbb{R}^{M \times N_p}$  is the system matrix,  $\boldsymbol{b}_s \in \mathbb{R}^M (M = U_y \times N_{views})$ stands for the vectorized projections,  $U_y$  and  $N_{views}$  are the number of detector units and projection views, respectively.  $e_s \in \mathbb{R}^M$  is the noise in the measured projection. For a given system geometry, the task of image reconstruction for MECT is to find  $x_s$  according to the system geometry and observation  $b_s$ . However, the reconstruction is ill-posed due to the serious noise in low-dose MECT. It is thus necessary to introduce some priors to build regularization terms to improve the stability of solving the inverse problems.

In order to obtain high-quality reconstruction images, the prior knowledge of the image itself should be introduced to build a regularization model. In this work, we first propose to combine the local and nonlocal regularizations for the low-dose MECT reconstruction problem. The local term is built by the L0 quasi-norm of image gradients and the nonlocal term is established by the block-matching frame-based regularizations, expressed as follows:

$$\min_{\boldsymbol{x}_{s}} \frac{1}{2} \sum_{s=1}^{S} \left\| A\boldsymbol{x}_{s} - \boldsymbol{b}_{s} \right\|_{2}^{2} + \lambda \sum_{s=1}^{S} \left\| \nabla \boldsymbol{x}_{s} \right\|_{0} + \beta R(X)$$

$$s.t. \quad \boldsymbol{x}_{s} \ge 0$$

$$[2]$$

where *X* is the group of all-channel CT images, *R* (*X*) represents the regularization term on MECT images based on blocking-matched frames, and  $\|\nabla \mathbf{x}_s\|_0$  denotes the regularization term on single-channel gradient image.  $\lambda$ ,  $\beta$  are the nonnegative parameters to balance the data fidelity and regularization term.

In order to decouple the variable X, 2 auxiliary variables,  $u_s$  and Y, are introduced to reformulate the above problem [2] as follows:

$$\min_{\boldsymbol{x}_{s}} \quad \frac{1}{2} \sum_{s=1}^{S} \left\| A\boldsymbol{x}_{s} - \boldsymbol{b}_{s} \right\|_{2}^{2} + \lambda \sum_{s=1}^{S} \left\| \nabla \boldsymbol{u}_{s} \right\|_{0} + \beta R(\boldsymbol{Y})$$

$$(3)$$

$$s.t. \quad \boldsymbol{x}_{s} = \boldsymbol{u}_{s}, \ \boldsymbol{X} = \boldsymbol{Y}, \ \boldsymbol{x}_{s} \ge 0$$

Its corresponding augmented Lagrangian function is the following:

$$\frac{1}{2}\sum_{s=1}^{S}\left\|A\boldsymbol{x}_{s}-\boldsymbol{b}_{s}\right\|_{2}^{2}+\lambda\sum_{s=1}^{S}\left\|\nabla\boldsymbol{u}_{s}\right\|_{0}+\beta R(Y)+\frac{\lambda_{1}}{2}\sum_{s=1}^{S}\left\|\boldsymbol{x}_{s}-\boldsymbol{u}_{s}+\frac{\Lambda_{1}}{\lambda_{1}}\right\|_{2}^{2}+\frac{\lambda_{2}}{2}\left\|\boldsymbol{X}-\boldsymbol{Y}+\frac{\Lambda_{2}}{\lambda_{2}}\right\|_{2}^{2},$$

where  $\Lambda_1$  and  $\Lambda_2$  are the Lagrange multipliers, and  $\lambda_1$  and  $\lambda_2$  are the nonnegative parameters.

In this paper, the alternating direction method of multipliers (ADMM) is used to solve the problem [3]. The process is detailed in Algorithm 1, and it is used as a comparison algorithm in the experiments section. It should be noted that, for the subproblem Y, it is actually carried out the nonlocal block-matching denoising process on input

data  $Y_{input} = X^l + \frac{\Lambda_2^{l-1}}{\lambda_2}$ . Due to the effectiveness of suppressing noise, the BM3D algorithm under 3D block-matching frames is selected as a plug-and-play (PnP) module in the reconstruction process (25,40). The algorithm is termed the multienergy BM3D (ME-BM3D) method in this work.

Algorithm 1. ME-BM3D method Input: parameters  $\lambda$ ,  $\lambda_1$ ,  $\lambda_2$ ,  $\beta$ ,  $l_{max}$ , projection data  $\boldsymbol{b}$ . 1. Initialization:  $\boldsymbol{x}^0 = 0$ ,  $\boldsymbol{y}^0 = 0$ ,  $\boldsymbol{u}^0 = 0$   $\Lambda_1^0 = \Lambda_2^0 = 0$  l = 0. 2. While not converged or  $l \le l_{max}$ 3.  $\boldsymbol{x}' \in \operatorname{argmin}_{\boldsymbol{x}_s} \left\{ \frac{1}{2} \sum_{s=1}^{s} ||A\boldsymbol{x}_s - \boldsymbol{b}_s||_2^2 + \frac{\lambda_1}{2} \sum_{s=1}^{s} ||\boldsymbol{x}_s - \boldsymbol{u}_s^{l-1} + \frac{\Lambda_1^{l-1}}{\lambda_1}||_2^2 + \frac{\lambda_2}{2} ||\boldsymbol{x} - \boldsymbol{Y}^{l-1} + \frac{\Lambda_2^{l-1}}{\lambda_2}||_2^2 \right\}$ 4.  $\boldsymbol{u}' \in \operatorname{argmin}_{\boldsymbol{u}_s} \left\{ \lambda \sum_{s=1}^{s} ||\nabla \boldsymbol{u}_s||_0 + \frac{\lambda_1}{2} \sum_{s=1}^{s} ||\boldsymbol{x}_s^l - \boldsymbol{u}_s + \frac{\Lambda_1^{l-1}}{\lambda_1}||_2^2 \right\},$ 5.  $\boldsymbol{Y}^l \in \operatorname{argmin}_{\boldsymbol{Y}} \left\{ \beta R(\boldsymbol{Y}) + \frac{\lambda_2}{2} ||\boldsymbol{X}^l - \boldsymbol{Y} + \frac{\Lambda_2^{l-1}}{\lambda_2}||_2^2 \right\},$ 6.  $\Lambda_1^l = \Lambda_1^{l-1} + \lambda_1 \left( \boldsymbol{x}^l - \boldsymbol{u}^l \right), \quad \Lambda_2^l = \Lambda_2^{l-1} + \lambda_2 \left( \boldsymbol{X}^l - \boldsymbol{Y}^l \right)$ 7. End while Output:  $\mathcal{X}$ 

Although the ME-BM3D method takes into account the prior knowledge of the spatial and spectral domain to improve the reconstruction quality, it is solved channelwise in practice, resulting in an increased computational time. Therefore, we further considered the similarity of each channel to design a method based on subspace representation to accelerate MECT reconstruction. Furthermore, it is worth mentioning that the solving methods of  $\mathcal{X}$  and  $\mathcal{U}$ subproblems in the ME-BM3D method are consistent with the proposed subspace decomposition-based method introduced in the next subsection.

## Cascaded global and nonlocal priors based on subspace decomposition and block-matching

#### Subspace decomposition

Due to the high correlations between different channels of MECT images, we assume that the images X can be approximated by the k dimensional subspace, where  $S \geq k$ ; that is,

$$X = EZ$$
<sup>[4]</sup>

where the columns of  $E = [e_1, e_2, ..., e_k] \in \mathbb{R}^{S \times k}$  are the basis of



Figure 1 The flowchart of the proposed algorithm. The input MECT images are processed through the spectral low-rank, nonlocal blockmatching denoising and sparsity regularization of intrachannel to generate the output as the new iteration. MECT, multienergy computed tomography.

subspace  $S_k$ .  $Z \in \mathbb{R}^{k \times N_p}$  are the coefficients of X under the basis E. Without loss of generality, we simply assume that E is orthogonal; that is,  $E^T E = I_k$ , where  $I_k$  is an identity matrix of dimension k. Different methods can be followed to infer a subspace matrix E from the MECT images, such as the hyperspectral signal identification by minimum error (Hysime) method (41) or singular value decomposition.

Since *E* is orthogonal,  $Z \in \mathbb{R}^{k \times N_p}$  can be obtained by projecting MECT images *X* through subspace *E*, meaning that  $Z=E^T X$ . Each row of *Z* is denoted a vectorized image, and hereafter referred to as eigenimages. According to the literature (38,42), the eigenimages can be denoised with nonlocal patch-based methods due to the nonlocal selfsimilarity of each eigenimage and the correlation between the eigenimages.

### Regularization combing with global, local, and nonlocal priors

Images of MECT are highly self-similar. Furthermore, it can be assumed that every single energy image exists in the *k*-dimensional subspace  $S_k$ , where  $S \ge k$ . Thus, the mathematical model of the MECT reconstruction can be formulated as follows:

$$\min_{\boldsymbol{x}_{s}, \boldsymbol{Z}, \boldsymbol{E}} \frac{1}{2} \sum_{s=1}^{S} \left\| A\boldsymbol{x}_{s} - \boldsymbol{b}_{s} \right\|_{2}^{2} + \lambda \sum_{s=1}^{S} \left\| \nabla \boldsymbol{x}_{s} \right\|_{0} + \beta R(\boldsymbol{Z}) + \frac{\rho}{2} \left\| \boldsymbol{X} - \boldsymbol{E} \boldsymbol{Z} \right\|_{F}^{2}$$

$$[5]$$

$$s.t. \quad \boldsymbol{E}^{T} \boldsymbol{E} = I_{t} \quad \boldsymbol{x} > 0$$

The Frobenius norm term represents the difference between subspace decomposition *EZ* and MECT images *X*. *R* (*Z*) represents the regularization term on eigenimages, and  $\lambda$ ,  $\beta$ ,  $\rho$  are the nonnegative parameters to balance the data fidelity and regularization terms.

The flowchart of the algorithm according to the reconstruction model is presented in *Figure 1*. Specifically, model [5] contains the global, local, and nonlocal priors in parallel. Firstly, the subspace decomposition is applied to map the high-dimensional MECT images into a low-dimensional space by using the spectral low-rankness, which corresponds to the fourth term of the objective function in model [5]. Then, the nonlocal similarities are further exploited on each eigenimage by similar block-matching, which is expressed as  $\beta R$  (Z). This step cascades the global low-rankness and the nonlocal priors of interchannel images. Secondly, the denoised eigenimages are aggregated into high-dimensional image space. Finally, the local spatial sparsity is described by L0 quasi-norm regularization, which applies sparsity to a single-channel gradient image.

#### Details of the solving scheme

For convenience, a third-order tensor  $\mathcal{X}$  is set to represent all channels of CT images. The  $\mathcal{X}$  subproblem can be solved through the following optimization:

$$\min_{x} \quad \frac{1}{2} \sum_{s=1}^{S} \|A\boldsymbol{x}_{s} - \boldsymbol{b}_{s}\|_{2}^{2} + \lambda \sum_{s=1}^{S} \|\nabla \boldsymbol{x}_{s}\|_{0} + \frac{\rho}{2} \|X - E^{l-1}Z^{l-1}\|_{F}^{2}$$

$$s.t. \quad \boldsymbol{x}_{s} \ge 0$$

$$[6]$$

Then, by introducing an auxiliary variable  $u_s$  to replace  $x_s$ , problem [6] can be further written into the following constrained form:

$$\min_{x,u} \frac{1}{2} \sum_{s=1}^{S} \|A\boldsymbol{x}_{s} - \boldsymbol{b}_{s}\|_{2}^{2} + \lambda \sum_{s=1}^{S} \|\nabla \boldsymbol{u}_{s}\|_{0} + \frac{\rho}{2} \|X - E^{l-1}Z^{l-1}\|_{F}^{2}$$
*s.t.*  $\boldsymbol{x}_{s} = \boldsymbol{u}_{s}, \boldsymbol{x}_{s} \ge 0$ 

$$(7)$$

Based on the augmented Lagrangian function, problem [7] can be rewritten as follows:

$$\min_{\boldsymbol{x},\boldsymbol{u},\boldsymbol{v}} \frac{1}{2} \sum_{s=1}^{S} \|A\boldsymbol{x}_{s} - \boldsymbol{b}_{s}\|_{2}^{2} + \lambda \sum_{s=1}^{S} \|\nabla \boldsymbol{u}_{s}\|_{0} + \frac{\rho}{2} \|X - E^{l-1}Z^{l-1}\|_{F}^{2} + \frac{\eta}{2} \sum_{s=1}^{S} \|\boldsymbol{x}_{s} - \boldsymbol{u}_{s} - \boldsymbol{v}_{s}\|_{2}^{2}$$

$$s.t. \quad \boldsymbol{x}_{s} \ge 0$$

$$[8]$$

where  $v_s$  is the *s*-th channel Lagrangian multiplier of  $v \in R^{\sqrt{N_p} \times \sqrt{N_p} \times S}$ , and  $\eta$  is the nonnegative penalty parameter. Therefore, problem [8] can be solved via ADMM in the inner loop

$$\underset{x}{\operatorname{argmin}} \quad \frac{1}{2} \sum_{s=1}^{S} \left\| A \mathbf{x}_{s} - b_{s} \right\|_{2}^{2} + \frac{\rho}{2} \left\| X - E^{l-1} Z^{l-1} \right\|_{F}^{2} + \frac{\eta}{2} \sum_{s=1}^{S} \left\| \mathbf{x}_{s} - \mathbf{u}_{s}^{j} - \mathbf{v}_{s}^{j} \right\|_{2}^{2}$$

$$(9)$$

$$\underset{u}{\operatorname{argmin}} \quad \lambda \sum_{s=1}^{S} \left\| \nabla \boldsymbol{u}_{s} \right\|_{0} + \frac{\eta}{2} \sum_{s=1}^{S} \left\| \boldsymbol{x}_{s}^{j+1} - \boldsymbol{u}_{s} - \boldsymbol{v}_{s}^{j} \right\|_{2}^{2}$$
[10]

$$v^{j+1} = v^j + u^{j+1} - x^{j+1}$$
[11]

where superscript *j*, *l* represent the iteration of the inner and outer loop, respectively. We rearrange *X*, *Z* in the second term of Eq. [9] along the energy channel as  $x_s$  and  $z_s$ , and then problem  $x_s$  can be solved using the separate quadratic surrogate method, which is expressed as follows:

$$\mathbf{x}_{s}^{j+1} = \mathbf{x}_{s}^{j} - \frac{\mathbf{c}_{s}^{j}}{A^{T} A \mathbf{l} + \rho + \eta}$$
[12]

where  $c_s^j = A^T (Ax_s^j - b_s) + \rho(x_s^j - E^{l-1}z_s^{l-1}) + \eta(x_s^j - u_s^j - v_s^j)$ . The long division stands for pixelwise operation. Meanwhile, the ordered-subset simultaneous algebraic reconstruction technique (OS-SART) (43) is used to accelerate the implementation for  $x_s$ . Problem [10] is solved by an approximation algorithm described previously (29). Then, the final output  $x_s^{j_{max}}(s=1,2,...,S)$  in the inner loop appears as the *l*-th iteration  $X^l$  of the outer loop. The algorithm of solving  $\mathcal{X}$  subproblem is summarized in Algorithm 2.

Algorithm 2. ADMM for solving ${\mathcal X}$ subproblem				
Input: parameters $\rho$ , $\eta$ , $\lambda$ , $j_{max}$ , projection data <b>b</b> .				
1. Initialization: $x^0 = u^0 = v^0 = 0$ , $j = 0$ .				
2. While not converged or $j \leq j_{max}$				
3. Update $x^{i+1}$ via [12]				
4. Update $u^{i+1}$ via [10].				
5. Update $v^{i+1}$ via [11].				
6. End while				
Output: $\mathbf{r}^{l} = \mathbf{r}^{j+l}$				

For E subproblem, the corresponding problem is the following

$$E^{l} = \underset{E, E^{T} E = I_{k}}{\operatorname{argmin}} \frac{\rho}{2} \left\| X^{l} - EZ^{l-1} \right\|_{F}^{2} = L(\xi) S(\xi)^{T}$$
[13]

where  $L(\xi)$ ,  $S(\xi)$  are the left and right singular vectors of the matrix  $\xi = \rho X^{\ell} (Z^{\ell-1})^{T}$ , respectively (44).

The Z subproblem is transformed into the following optimization scheme:

$$Z^{l} = \underset{Z}{\operatorname{argmin}} \beta R(Z) + \frac{\rho}{2} \left\| X^{l} - E^{l} Z \right\|_{F}^{2} = \beta R(Z) + \frac{\rho}{2} \left\| Z - \left( E^{l} \right)^{T} X^{l} \right\|_{F}^{2} \qquad [14]$$

In this paper, the regularization term of Z acts as a denoiser on the eigenimages rather than on the multienergy CT images. We selected BM3D as the denoiser under the flexible PnP framework. The algorithm is summarized in Algorithm 3.

Algorithm 3. The proposed method for MECT reconstruction					
Input: parameters $\rho$ , $\beta$ , $l_{max}$ , projection data <b>b</b> .					
1. Initialization: $x^0 = 0, E^0 = 0, Z^0 = 0, l = 0$ .					
2. While not converged or $l \leq l_{max}$					
3. Update $X'$ via Algorithm 2.					
4. Update $E^{l+l}$ via [13].					
5. Update $Z^{t+1}$ via [14].					
6. Compute $X^{l+1} = E^{l+1}Z^{l+1}$ .					
7. End while					
8. Rearrange vectorized images $X^{l_{max}}$ into a third-order tensor $x^{l_{max}}$ .					
Output: $\mathcal X$					

There are 3 parameters in problem [5] to balance the data fidelity term, L0 quasi-norm, and the subspace representation term. However, finding the theoretically optimal values is a complex problem. Therefore, we empirically selected them according to experiments. The effect of these parameters on the experiments is presented in the Discussion section in detail. In addition, the  $\mathcal{X}$ subproblem contains other parameters  $\eta$  to choose from in practice. Its selection was also guided by empirical study. We modified its value according to  $\tau \sum_{i,i_2} \left[ A^T A \right]_{i_1i_2} / \sum_{j}^{N_p} [\mathbf{u}_s + \mathbf{v}_s]_j$ , where  $[\bullet]_j$  represents the element of matrix or vector, and  $\tau$ is a nonnegative tuning parameter that was set to 5.7 in the implementation after multiple trials.

#### Results

To evaluate the performance of the proposed method, we applied the simulation Moby data, more realistic chest data, and real mouse data to execute the experiments. The multienergy OS-SART (ME-OS-SART) (43), the multienergy BM3D (ME-BM3D; described in Algorithm 1), SISTER (33), WATITF (35), and FONT-SIR (37) methods were considered for comparison. The root-mean-square error (RMSE), structural similarity index (SSIM) (45), and the peak signal-to-noise ratio (PSNR) were employed for quantitative evaluation. In order to verify the effectiveness of the proposed method, material decomposition based on the image-domain was further carried out for the real mouse data.

According to the reconstruction model, there are 3 parameters associated with inter- and intrachannel regularized terms, which are used to balance the fidelity terms. For different datasets (i.e., simulation Moby data, preclinical chest data, and real mouse data), the parameters were not completely consistent because their selections were not only related to the scanning geometry but also depended on the data conditions. In addition, the implementation source code of the comparison methods [SISTER (33), WATITF (35), and FONT-SIR (37)] was given by the relevant authors, and their parameters were thus empirically optimized experimental comparisons and data conditions to ensure the fairness of comparison. All the initial images were set to zero for all methods in experiments. The number of the ordered subsets was set to 10 for all methods that used the accelerated technology. In addition, the iterations were set to 100 for the proposed method. The number of similar patches was 16 with size  $8\times8$ , and the search window and stride for patch extraction were 39 and 3, respectively.

#### Numerical simulation tests

We first constructed a simulated Moby phantom with the size of  $256 \times 256$ , and each pixel was 0.15 mm × 0.15 mm. To perform multienergy CT reconstruction, the X-ray energy was divided into 8 bins: [16-22), [22-25), [25-28), [28-31), [31-34), [34-37), [37-41) and [41-50) keV. The scanning distances from the source to the object and detector were 132 and 180 mm, respectively. The number of detector units was 512, and the size of each was 0.1 mm. The projection views were set to 80 and 160, and evenly distributed in a 360° range through the circular trajectory. Considering the noise caused by physical effects, such as scattering, stacking, or charge sharing, combined with the law of large numbers and the central limit theorem, random noise was added to the projected data as follows:

$$P_s = P_s + n_\sigma \max(P_s) \cdot n_s$$
  

$$n_s \sim N(0,1), \quad s = 1, 2, \dots, S$$
[15]

where  $P_s$ ,  $\tilde{P}_s$  are the clean and noisy single-energy projection, respectively.  $n_s$  generates a random noise with standard normal distribution, and  $n_\sigma$  is the strength parameter which is set to 4/255 here<sup>1</sup>. To clearly show the structure of Moby data, the reconstructed images of all methods were orientated horizontally and presented as 30×215 pixels.

*Figures 2,3* show the reconstructed results of the fourth, sixth, and eighth channels between different methods under 160 and 80 projection views, where columns (A) to (G) represent the images of references, ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. The extracted ROIs denoted by the yellow dashed square in *Figure 2* (A<sub>1</sub>) and *Figure 3* (A<sub>1</sub>) were magnified below the corresponding reconstructed images. As shown in *Figures 2,3*, imaging results via ME-OS-SART had the lowest image quality due to its lack of ability to denoise, leading to difficulties in identifying the detailed structures. The ME-BM3D method greatly improved

<sup>&</sup>lt;sup>1</sup> Due to the complexity of the noise mechanism in the imaging process, we chose the random noise method to simulate the noise in lowdose projections. It was further found that the level of random noise was approximated to  $1.4 \times 10^3$  photons in Poisson noise.



**Figure 2** Simulated Moby data reconstruction results of different methods under 160 projection views when  $n_{\sigma}$ =4/255. Columns (A) to (G) represent the images of reference, ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method. The first 2 rows represent the fourth energy bin and its corresponding ROIs, the middle 2 rows represent the sixth energy bin and its corresponding ROIs, and the bottom 2 rows represent the eighth energy bin and its corresponding ROIs. The display windows of 3 energy bins are [0.01 0.1], [0.01 0.07], [0.01 0.06] mm<sup>-1</sup>, respectively. The second column indicates the SART results of the low-dose data, which gives a sense of the intensity of the noise. ME-OS-SART, multienergy ordered subset–based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; ROI, region of interest; SART, simultaneous algebraic reconstruction technique.

image quality but was limited to preserving image details and fine structures. WATITF, FONT-SIR, and SISTER methods obtained better image quality than the above methods in suppressing noise and preserving structure. However, as pointed out by the orange arrows in the ROIs of *Figures 2,3* ( $G_3$ ), some missing details were observed. The proposed method generated high-quality images with subtle detail preservation compared with SISTER and better noise suppression compared with the methods mentioned above. In addition, to verify the robustness of the proposed method against different noises, another set of high-noise experiments is further given. *Figure 4* shows the relevant results that the proposed method had a better ability of structure preservation with areas indicated by orange arrows. Compared with other methods, the proposed method maintained the advantages of noise suppression and edge preservation, as indicated by orange arrows, when the noise level was higher.

The quantitative assessments of RMSE, PSNR, SSIM, and computational time under 160 views are listed in *Table 2*. Due to the lack of space, we have only listed the quantitative results of 4 channels between different methods. These results show that the indices of the eighth channel are better than those of the other 3 channels. Compared with other methods, the proposed method achieved the best values in each channel in the RMSE, PSNR, and SSIM indices.



**Figure 3** Simulated Moby data reconstruction results of different methods under 80 projection views when  $n_{\sigma}$ =4/255. Columns (A) to (G) represent the images of reference, ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method. The first 2 rows represent the fourth energy bin and its corresponding ROIs, the middle 2 rows represent the sixth energy bin and its corresponding ROIs, and the bottom 2 rows represent the eighth energy bin and its corresponding ROIs. The display windows of 3 energy bins are [0.01 0.1], [0.01 0.07], [0.01 0.06] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy ordered subset-based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity–based tensor with enhanced sparsity reconstruction; ROI, region of interest.

Specifically, taking the eighth channel as an example, the proposed method reduced RMSE by 65.91%, 28.48%, 42.31%, 42.31%, and 16.67%, compared with those for the ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, and SISTER methods, respectively. The SSIM and PSNR were as high as 0.9974 and 56.2138 dB for the proposed method, respectively, which were also higher than those of the other methods. Compared with ME-BM3D, WATITF, FONT-SIR, and SISTER, and SISTER, the proposed method had a lower computational cost per iteration, and its calculation time was 90.25%, 42.04%, 23.07%, and 16.42% of the other 4 block-matching-based methods, respectively. The reason the approaches of ME-BM3D, WATITF, FONT-

SIR, and SISTER are more time-consuming is that the extraction of similar image patches from all channels of MECT, while the proposed method only clusters these patches in the channels of eigenimages. Both WATITF and our proposed method have 3 priors in the model, but the increase of priors does not imply a corresponding increase in the complexity of our algorithm. The former constructs low-rank cube-based tensors of all channels, and the latter extracts similar patches after dimensionality reduction. By cascading the global and local priors, the global noise can be suppressed and the main structures can be further strengthened, reducing the computational time and avoiding the balance between global and nonlocal priors.



**Figure 4** Simulated Moby data reconstruction results of different methods under 160 projection views when  $n_{\sigma}$ =20/255. Columns (A) to (G) represent the images of reference, ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method. The first 2 rows represent the fourth energy bin and its corresponding ROIs, the middle 2 rows represent the sixth energy bin and its corresponding ROIs, and the bottom 2 rows represent the eighth energy bin and its corresponding ROIs. The display windows of 3 energy bins are [0.01 0.1], [0.01 0.07], [0.01 0.06] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy ordered subset-based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; ROI, region of interest.

The partial line profiles and their enlarged ROIs, drawn from the 120th pixel to the 140th pixel along with the white dashed line in *Figure 3* (A<sub>1</sub>), are further plotted in *Figure 5*. The proposed method generated more accurate line profiles than did the other methods. As marked by the green arrows, the complex structure of the image is prone to fluctuations of line profiles in the vertical direction, which means that the proposed method is more sensitive to the changes in detail structures.

#### Preclinical dataset study

The study was conducted in accordance with the

Declaration of Helsinki (as revised in 2013). A public preclinical chest dataset was further chosen to evaluate the performance of the proposed subspace for more realistic medical application scenarios. The data were processed by doctors and contained less noise than did the actual dataset. The tube voltage was 120 kV, and the energy bins were set to [72–80), [78–86), [84–92), [90–98), [96–104), [102–110), [108–116) and [114–120) keV. The size of reconstructed images was  $512 \times 512$ , with each pixel 0.921 mm × 0.921 mm. The number of detector bins was 1024, and the size was 0.69 mm. The distances of the source to the object and the detector were 1,000 and 1,500 mm, respectively. Furthermore, the noise level  $n_{\sigma}$  was set to

Mothodo		Chapped 2	Channel 4	Chappel 6	Chappel 8				
weinous	Index	Ghanner 2	Ghannel 4	Charmero					
ME-OS-SART	RMSE	0.0141	0.0081	0.0061	0.0044				
	PSNR	37.0362	41.7938	44.3267	47.1280				
	SSIM	0.8556	0.9365	0.9587	0.9750				
	Time	5.34 seconds (for	5.34 seconds (for 1 step iteration)						
ME-BM3D	RMSE	0.0068	0.0043	0.0035	0.0029				
	PSNR	43.4139	47.4269	49.1147	50.8172				
	SSIM	0.9798	0.9882	0.9897	0.9911				
	Time	7.69 seconds (for	7.69 seconds (for 1 step iteration)						
WATITF	RMSE	0.0082	0.0046	0.0034	0.0026				
	PSNR	41.7495	46.7385	49.3562	51.7662				
	SSIM	0.9817	0.9889	0.9911	0.9931				
	Time	16.51 seconds (fo	16.51 seconds (for 1 step iteration)						
FONT-SIR	RMSE	0.0074	0.0043	0.0035	0.0026				
	PSNR	42.6170	47.3813	49.2002	51.8192				
	SSIM	0.9815	0.9892	0.9909	0.9929				
	Time	30.08 seconds (fo	30.08 seconds (for 1 step iteration)						
SISTER	RMSE	0.0039	0.0022	0.0019	0.0018				
	PSNR	48.1268	53.1683	54.3427	55.1248				
	SSIM	0.9918	0.9961	0.9966	0.9967				
	Time	42.27 seconds (fo	42.27 seconds (for 1 step iteration)						
Proposed	RMSE	0.0036	0.0020	0.0019	0.0015				
	PSNR	48.8537	54.0383	54.4660	56.2138				

Τ

ME-OS-SART, multienergy ordered subset-based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourthorder nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; RMSE, root-means-square error; PSNR, peak signal-to-noise ratio; SSIM, structural similarity index.

0.9968

6.94 seconds (for 1 step iteration)

0.0382 in this data. To further verify the effectiveness of the proposed method in MECT reconstruction, we conducted experiments on preclinical data with 160 and 80 projection views. Reconstruction results of the SART method, based on 720 noise-free projection views, were taken as the reference of MECT for the subsequent evaluation. Similar to the simulated experiments, we show the 3 energy channels of the reconstructed images at 15×475 pixels horizontally. An ROI [denoted in Figure 6 (A<sub>1</sub>), labeled I] in the tissue of the chest was magnified to assess the

0.9929

SSIM

Time

structure preservation across the different algorithms, while another ROI [also denoted in *Figure 6* ( $A_1$ ), labeled II] was chosen to make a quantitative evaluation of the mean value of attenuation coefficients and standard deviation (STD), which was calculated as follows:

0.9974

0.9969

$$STD = \sqrt{\frac{1}{N_{roi}} \sum_{r=1}^{N_{roi}} (x_r - \overline{x})^2}$$
[16]

where  $x_r$  denotes the value of r-th pixel, and  $\overline{x}$  is the precomputed mean value of all  $N_{roi}$  image pixels of the



**Figure 5** Line profiles of 8 channels between different methods under 80 projection views. Rows from top to bottom represent the results of 8 channels. ME-OS-SART, multienergy ordered subset-based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourthorder nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction.



**Figure 6** The preclinical dataset reconstruction results of different methods under 160 views. Columns (A) to (F) represent the methods of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the energy bins [90–98) keV, [102–110) keV, and [114–120) keV, and the display windows are [0.01 0.11], [0.01 0.07], [0.01 0.05] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy-ordered subsets based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity–based tensor with enhanced sparsity reconstruction.

selected ROI.

The reconstructed images and their corresponding enlarged ROIs for 160 projection views obtained by ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method are shown in Figure 6, where columns (A) to (F) represent the different approaches, and rows 1 to 3 represent the fourth, the sixth and the eighth channels, respectively. Furthermore, the difference images and the ROIs [denoted in *Figure 6*  $(A_1)$ ] are also shown in Figure 7. Figure 6 and Figure 7  $(A_1)$ - $(A_3)$  show obvious noises in the reconstructions of ME-OS-SART, whereas other methods in *Figure 6* and *Figure 7* ( $B_1$ )–( $E_3$ ) show noise suppression. However, the zoomed-in ROIs show that the ME-BM3D, WATITF, FONT-SIR, and SISTER methods still failed to recover tissue details and edges. Compared with other methods, the proposed method was superior in fine structure preservation and noise suppression. In addition, the results of 80 views, shown in Figure 8 and Figure 9, also demonstrate that the proposed method had the ability to reconstruct high-quality images compared with other methods.

Table 3 lists the quantitative evaluation of different methods under 80 projection views, where the mean value was measured to assess the accuracy of the results, while the STD value evaluated the noise suppression ability of different methods. The STD values of the proposed method, as pointed in superscript asterisk, were close to those for reference images compared with other methods in each energy channel, indicating that the proposed method is superior in suppressing noises. The proposed method had a similar mean value with other methods, indicating the accuracy of reconstruction results.

#### Real mouse data study

A mouse was scanned through a MARS micro spectral CT system (28,31), which included a micro X-ray source and a flat panel PCD. The study was approved by the Ethics Committee of PLA Strategic Support Force Information Engineering University and was conducted in compliance with the laboratory animal guideline for ethical review of animal welfare. The distances between the source to object and the PCD were 158 and 255 mm, respectively. The length of PCD was 56.32 mm and included 512 pixels, resulting in a field of view with a diameter of 34.69 mm. Gold nanoparticles (GNPs) were injected into the mouse as the contrast agent. Due to the PCD only consisting of 2 energy bins, multiple scans were performed to obtain 13 channels for 371 views with an increasing radiation dose. We extracted the projections for the central slice to reconstruct each channel image with the size of 512×512 in this experiment. We chose 360 and 180 projection views



**Figure 7** The preclinical dataset difference images of different methods under 160 views. Columns (A) to (F) represent the methods of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the energy bins [90–98) keV, [102–110) keV, and [114–120) keV, respectively. The display windows are [–0.15 0.15], [–0.1 0.1], [–0.06 0.06] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy-ordered subsets based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity–based tensor with enhanced sparsity reconstruction.



**Figure 8** The preclinical dataset reconstruction results of different methods under 80 views. Columns (A) to (F) represent the methods of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the energy bins [90–98) keV, [102–110) keV, and [114–120) keV, and the display windows are [0.01 0.11], [0.01 0.07], [0.01 0.05] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy-ordered subsets based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction.



**Figure 9** The preclinical dataset difference images of different methods under 80 views. Columns (A) to (F) represent the methods of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the energy bins [90–98) keV, [102–110) keV, and [114–120) keV, respectively. The display windows are [–0.15 0.15], [–0.1 0.1], [–0.06 0.06] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy-ordered subsets based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity–based tensor with enhanced sparsity reconstruction.

Methods	Metric	Channel 1	Channel 2	Channel 3	Channel 4	Channel 5	Channel 6	Channel 7	Channel 8
Reference	Mean value	0.4070	0.1952	0.1319	0.0970	0.0764	0.0610	0.0506	0.0394
	STD	0.3895	0.1781	0.1148	0.0766	0.0527	0.0390	0.03	0.0205
ME-OS-SART	Mean value	0.4049	0.1955	0.1324	0.0972	0.0769	0.0611	0.0507	0.0395
	STD	0.2596	0.1193	0.0764	0.0510	0.0343	0.0258	0.0204	0.0145
ME-BM3D	Mean value	0.4032	0.1953	0.1322	0.0972	0.0767	0.0611	0.0506	0.0394
	STD	0.3613	0.1664	0.1049	0.0694	0.0466	0.0343	0.0264	0.0177
WATITF	Mean value	0.4053	0.1949	0.1318	0.0967	0.0763	0.0609	0.0504	0.0393
	STD	0.3161	0.1453	0.0942	0.0630	0.0441	0.0330	0.0258	0.0182
FONT-SIR	Mean value	0.3966	0.1938	0.1311	0.0970	0.0776	0.0614	0.0509	0.0406
	STD	0.2948	0.1401	0.0908	0.0610	0.0422	0.0310	0.0244	0.0187
SISTER	Mean value	0.4029	0.1952	0.1319	0.0971	0.0766	0.0610	0.0506	0.0394
	STD	0.3315	0.1532	0.0982	0.0652	0.0446	0.0331	0.0257	0.0175
Proposed	Mean value	0.4051	0.1950	0.1316	0.0967	0.0765	0.0611	0.0506	0.0396
	STD	0.3757*	0.1730*	0.1118*	0.0746*	0.0511*	0.0384*	0.0301*	0.0219*

Table 3 Means and STDs of different methods for the preclinical dataset under 80 views

\*, the indices that close to reference values. ME-OS-SART, multienergy ordered subset-based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; STD, standard deviation.



**Figure 10** The real mouse reconstruction results of different methods under 360 views. Columns (A) to (F) represent the images of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the 1st, 7th, 13th energy bins, respectively. The display windows are [0 0.08], [0 0.07], [0 0.07] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy ordered subsetbased simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction.

evenly distributed in 371 ranges to verify the proposed method in low-dose spectral CT reconstruction.

Figure 10 shows the reconstruction results of 3 representative energy bins (1st, 7th, 13th) via different methods under 360 views. The first column denotes the images reconstructed by ME-OS-SART with severe noises, but it is difficult to distinguish some soft tissue details. Columns (B) to (E) represent the reconstructions of ME-BM3D, WATITF, FONT-SIR and SISTER, and it seems that a lot noise has been suppressed. However, in the magnified regions, denoted by yellow dashed lines in *Figure 10* (A<sub>1</sub>), the 2 ROIs reconstructed by ME-BM3D, WATITF, FONT-SIR and SISTER indicate a lower ability to preserve bone structures compared with the proposed method. *Figure 11* is the reconstructions of the different methods under 180 views and shows similar results.

Furthermore, the basis for material decomposition depends on the reconstructed image quality: the better the image quality, the easier the task of postprocessing material decomposition. The first 3 rows in *Figure 12* and *Figure 13* show the 3 decomposed basis materials: bone, soft tissue, and GNP. The last row includes the colored image,

with red, green, and blue representing the 3 materials mentioned above. The decomposition results also show the effectiveness of the proposed method, and the proposed method could provide continuous triangle areas (denoted by red box) of GNP contrast agent with clear image edges. In addition, the bone material decomposed by the proposed method had a more complete and distinct shape, and the probability of misclassifying into GNP was lower than that of the other comparison methods.

#### **Discussion**

This section describes some important factors that influenced the implementation of the proposed algorithm in detail, including the dimensions of subspace, the selection of parameters, and the effectiveness of eigenimages denoising.

#### Effects of the dimensions of subspace

The influence of the dimensions of subspace k on the MECT reconstruction is discussed through the simulated Moby data under 160 projection views. Since the energy

905



**Figure 11** The real mouse reconstruction results of different methods under 180 views. Columns (A) to (F) represent the images of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the 1st, 7th, 13th energy bins, respectively. The display windows are [0 0.08], [0 0.07], [0 0.07] mm<sup>-1</sup>, respectively. ME-OS-SART, multienergy ordered subsetbased simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction.

channel of data is 8, the dimensions of the subspace are set to 2, 3, 4, 5, 6, 7, respectively. As shown in Figure 14A, although the quantitative results of different numbers of subspace's dimensions were similar, the RMSE curve was at the lowest position when k=3. Furthermore, we also explored the computational costs when varying the dimension of subspace, which are shown in Figure 14B. There is no significant consumption of computing time even if the dimension of the subspace is increased. Therefore, we set the dimension of subspace as 3 in our simulation experiments according to the results of RMSE curves and computational costs. Similar to the simulated Moby experiments, the choice of subspace dimensions for preclinical and real data also varied from the corresponding energy windows. Considering the computational time and imaging quality, the number of k could be set as 3, 4 or 5. In practice, we also chose the number 3.

#### Effects of the selection of parameters

There are three parameters in our reconstruction model:

 $\lambda$  is used to balance the intrachannel gradient image sparse prior,  $\beta$  is the regularization coefficient interchannel, and  $\rho$ is the nonnegative penalty parameter. It may be interesting to study the theoretical analysis of the selection of these parameters. However, we usually make the empirical choices based on the data conditions. In this paper, these parameters are within the range of  $10^{-4}$  to  $10^4$ . The RMSE curve changes with different values of  $\beta$  in simulation experiments are shown in *Figure 14C*. When the ground truth was not available for preclinical and real datasets, we also optimized these parameters according to the data conditions and the evaluations of image quality across several people. The selections of  $\lambda$ ,  $\beta$ , and  $\rho$  are listed in *Table 4* for different datasets.

#### Effects of eigenimages Z denoising

 $\beta$  is the regularization parameter of eigenimages Z, which does not directly associate with the original MECT images. In order to verify the effectiveness of the proposed method in eigenimages Z denoising, we chose ME-OS-SART and

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**Figure 12** The real mouse material decomposition results of different methods under 360 views. Columns (A) to (F) represent the images of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the bone, soft tissue, and GNP, respectively. The fourth row images are the corresponding color rendering, where red, green, and blue represent the above basis materials. The display windows are [0 0.5], [0 1], [0 0.5] cm<sup>-1</sup>, respectively. ME-OS-SART, multienergy ordered subset–based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; GNP, gold nanoparticles.

ME-BM3D as comparison methods, where the ME-BM3D method acted on the reconstructed MECT images by ME-OS-SART. The convergence curves of the 3 methods are shown in *Figure 14D*. *Figure 14D* shows that the denoising on eigenimages was more effective than when directly applied to MECT images.

In addition, there is still potential to improve the reconstructed image quality, such as for some detailed structures seem to be lost in the enlarged areas of the proposed method shown in *Figure 2* and *Figure 3*. The appearance of abnormal spikes of channels 6–8 in *Figure 5* also indicates that subtle noise was present in some regions, and so how to balance noise suppression and structure preservation also needs further consideration. Furthermore, the regularized terms of the inter- and intrachannel only considers the sparsity of gradient image and the correlations of multichannel images, and the priors can be further explored via integrating a deep denoising network into the



**Figure 13** The real mouse material decomposition results of different methods under 180 views. Columns (A) to (F) represent the images of ME-OS-SART, ME-BM3D, WATITF, FONT-SIR, SISTER, and the proposed method, respectively. Rows 1 to 3 represent the bone, soft tissue, and GNP, respectively. The fourth row images are the corresponding color rendering, where red, green, and blue represent the above basis materials. The display windows are [0 0.5], [0 1], [0 0.5] cm<sup>-1</sup>, respectively. ME-OS-SART, multienergy ordered subset-based simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; WATITF, weight-adaptive total variation and image-spectral tensor factorization; FONT-SIR, fourth-order nonlocal tensor decomposition model for spectral CT image reconstruction; SISTER, spectral image similarity-based tensor with enhanced sparsity reconstruction; GNP, gold nanoparticles.

MECT reconstruction model, a deep learning has certain advantages in medical image analysis (46-50).

#### Conclusions

In this paper, we propose a method to integrate the global, local, and nonlocal priors for low-dose MECT reconstruction in which the global low-rankness and nonlocal priors are cascaded through subspace decomposition and block-matching frames. Subspace representation is used to map original MECT images to a low-dimensional space, and the eigenimages are denoised by BM3D, which greatly reduces the computational complexity. L0 quasi-norm is further applied to exploit the local spatial sparsity in intrachannel images. Then, the model is iteratively solved by the alternating minimization method. Compared with the state-of-the-art methods, the simulation, preclinical, and real data experiments further



**Figure 14** Some descriptions of the proposed method. (A) RMSE curves of different dimensions of subspace. (B) Computational costs (unit: seconds) for 1 iteration with different dimensions of subspace. (C) RMSE curves with different values of regularization parameter  $\beta$ . (D) Convergence behaviors of 3 methods (ME-OS-SART, ME-BM3D, and the proposed method). ME-OS-SART, multienergy ordered subsetbased simultaneous algebraic reconstruction technique; ME-BM3D, multienergy-based block-matching and 3D filtering; RMSE, rootmeans-square error.

Table 4 The parameter values for 3 datasets

Datasets	λ	β	ρ
Simulation	1.8×10 <sup>-4</sup>	2.9	1.1
Preclinical	1.8×10 <sup>-4</sup>	2.9	1.1
Real mouse	1.8×10 <sup>-6</sup>	10	1.1

verified that the proposed method has the ability to improve the performance of denoising and detail preservation.

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#### Footnote

*Conflicts of Interest:* All authors have completed the ICMJE uniform disclosure form (available at https://qims. amegroups.com/article/view/10.21037/qims-22-647/coif). The authors have no conflicts of interest to declare.

*Ethical Statement:* The authors are accountable for all aspects of the work in ensuring that questions related to the accuracy or integrity of any part of the work are appropriately investigated and resolved. The study was

conducted in accordance with the Declaration of Helsinki (as revised in 2013). The study was approved by the Ethics Committee of PLA Strategic Support Force Information Engineering University, in compliance with the laboratory animal guideline for ethical review of animal welfare.

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#### **Appendix 1**

Here we describe the definitions relating to the global, local and nonlocal mentioned in the Introduction.

#### Local and nonlocal priors

When computing a local prior for a target pixel (denoted in orange and bolded point in *Figure S1*), the related adjacent pixels are considered (marked by black crosses in *Figure S1*) of the target pixel.

When the occasion comes into the nonlocal priors for a target pixel, not only do the adjacent pixels need to be calculated but so do the neighborhood pixels in the search window  $_n$ . The local and nonlocal priors are briefly illustrated in *Figure S1*.

#### Global prior

In fact, there is no general and specific standards or definitions for the descriptions of global priors. Therefore, we attempt to distinguish global and nonlocal priors according to whether the integrity of the data is considered or not. The global priors indicate that the pixels in a space  $R^s$  can be mapped to another space  $R^k$  under some transformation, and the dimensions of the 2 space may not be exactly the same. For instance, the wavelet transform is a typical ascending dimension transform, and the subspace decomposition method adopted in this paper is a dimensional reduction transformation.

According to the above concepts, a few representative MECT reconstruction methods containing different priors are summarized in *Table 1*. The local prior is marked when the regularization term relates to the sparsity of intrachannel. When extracting some pixels from a search window, the nonlocal priors are selected in the case of a channelwise operation. For instance, in the pixel extraction process described in Wu *et al.* (31,35), target pixels of all channels are extracted simultaneously. We therefore believe that they also have global priors from considering the integrity of all channels.



**Figure S1** The illustrations of the local and nonlocal priors is shown in (A) and (B), respectively, where orange and bolded points represent the target (i,j) pixels, and black crosses represent pixels adjacent to (i,j) or in the search window *n*.