

An automated and multiparametric algorithm for objective analysis of meibography images

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Background: Meibography is a non-contact imaging technique used by ophthalmologists and eye care practitioners to acquire information on the characteristics of meibomian glands. One of its most important applications is to assist in the evaluation and diagnosis of meibomian gland dysfunction (MGD). As the artificial qualitative analysis of meibography images can lead to low repeatability and efficiency, automated and quantitative evaluation would greatly benefit the image analysis process. Moreover, since the morphology and function of meibomian glands varies at different stages of MGD, multiparametric analysis offering more comprehensive information could help in discovering subtle changes to glands during MGD progression. Therefore, an automated and multiparametric objective analysis of meibography images is urgently needed.

Methods: An algorithm was developed to perform multiparametric analysis of meibography images with fully automatic and repeatable segmentation based on image contrast enhancement and noise reduction. The full architecture can be divided into three steps: (I) segmentation of the tarsal conjunctiva area as the region of interest (ROI); (II) segmentation and identification of glands within the ROI; and (III) quantitative multiparametric analysis including a newly defined gland diameter deformation index (*DI*), gland tortuosity index (*TI*), and gland signal index (*SI*). To evaluate the performance of this automated algorithm, the similarity index (*k*) and the segmentation error including the false-positive rate (r_p) and the false-negative rate (r_N) were calculated between the manually defined ground truth and the automatic segmentations of both the ROI and meibomian glands of 15 typical meibography images.

Results: The results of the performance evaluation between the manually defined ground truth and automatic segmentations were as follows: for ROI segmentation, the similarity index (k)=0.94±0.02, the false-positive rate (r_p)=6.02%±2.41%, and the false-negative rate (r_n)=6.43%±1.98%; for meibomian gland segmentation, the similarity index (k)=0.87±0.01, the false-positive rate (r_p)=4.35%±1.50%, and the-false negative rate (r_n)=18.61%±1.54%. The algorithm was successfully applied to process typical meibography images acquired from subjects of different meibomian gland health statuses, by providing the gland area ratio (*GA*), the gland length (*L*), gland width (*D*), gland diameter deformation index (*DI*), gland tortuosity index (*TI*), and gland signal index (*SI*).

Conclusions: A fully automated algorithm was developed which demonstrated high similarity with moderate segmentation errors for meibography image segmentation compared with the manual approach, offering multiple parameters to quantify the morphology and function of meibomian glands for the objective evaluation of meibography images.

Keywords: Meibography image; automated processing; multiparametric evaluation; objective analysis

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Introduction

Meibomian glands play an essential role in maintaining ocular surface health and integrity by secreting various lipid components, forming a lipid layer, and preventing excessive tear evaporation (1). Functional disorders of the meibomian glands, known as meibomian gland dysfunction (MGD), are increasingly recognized as a high incidence disease (2-5). MGD is commonly characterized by terminal duct obstruction and/or abnormal glandular secretion, often leading to ocular surface epithelium damage, chronic blepharitis, and dry eye disease, which severely degrade quality of life (6). The reported prevalence of MGD varies widely from 3.6% to 69.3% (7,8), which is largely due to the lack of effective and unified diagnostic criteria (8). Evaluation of the changes to meibomian glands is important for the diagnosis and management of MGD in clinical practice.

Besides traditional clinical evaluation methods that combine clinical manifests for MGD diagnosis (9), imaging techniques such as meibography (10-13), optical coherence tomography (14,15), and *in vivo* confocal microscopy (16,17) have also been used to image meibomian glands. Meiobiography is a non-contact imaging technique that uses infrared illumination which acquires images of the silhouette of glands from entire human eyelids. Using meiobiography images, morphological changes such as dilation, distortion, shortening, and atrophy can be directly observed and assessed visually and qualitatively (6,9,18), which greatly assists ophthalmologists in developing standardized diagnosis and treatment strategies (9-13).

To aid ophthalmologists in conducting quantitative evaluation of meibomian glands with meibography images, research has been conducted to obtain and evaluate the reliability of various detailed scale parameter grading methods (10-13,19-28). The most common of these is the dropout area or meibomian gland area (10-13,19-23). Using Image J or other image editing software, the dropout area or meibomian gland area can be quantitatively calculated; however, this is mostly conducted in a subjective manner, as gland/gland-loss regions are manually selected (10-13,19-21). Thus, these methods are relatively time-consuming and can lead to obvious intra- and interobserver variability (13,24,25), which limit their use in clinical studies where many images need to be analyzed efficiently. There is thus a strong need for the development of objective analyses using automated algorithms; however, only a few automated approaches have been demonstrated (22,23,25-28) due to difficulties in measuring the eyelid area and meibomian gland segmentation with meibography images.

Meibomian gland dropout mostly occurs in the advanced stage of MGD, and comparison of the histologic sections of normal and obstructed human glands has revealed that obstruction of the orifice in MGD can result in dilation of the gland acinus and central duct, increased gland tortuosity, damage to secretory meibocytes, and eventually the atrophy of glands (29,30). Therefore, in addition to area ratio parameters, there is a need to develop other quantitative parameters that can detect detailed morphological changes to meibomian glands which can potentially be used for MGD diagnosis and severity assessment (9). To date, only a handful of studies have reported the analysis of gland length, width, or regularity in meibography images (12,13,25-28), of which some are subjectively characterized in manual fashion (12,13). A multi-parametric objective analysis would offer doctors comprehensive information in MGD diagnosis and evaluation, especially in discovering subtle changes in preclinical and early-stage cases and monitoring MGD progression.

In this study, we developed an objective meibography image-analyzing algorithm that is capable of automatically performing segmentation of the evelid area with each single meibomian gland and providing multiple quantitative parameters for gland evaluation. Along with traditional parameters, such as the meibomian gland area ratio, gland length, and gland width, our algorithm introduces new morphological parameters including a gland diameter deformation index and gland tortuosity index. This address concerns in quantifying local gland diameter variation and the degree of curved and winding glands resulting from gland terminal duct obstruction, which mostly exists in the intermediate stages of MGD progression (13,16,25,29,30). Moreover, since changes in the secretion, consistency, and colour of meibum inside meibomian glands (12,29,31) could alter the signal intensity of glands in meibography images, we developed a new parameter, the gland signal index, to quantify the gland signal level, which can potentially be used to evaluate meibum secretion activity. Performance of the automated algorithm was evaluated by analyzing the similarity index and segmentation error between manual and automatic segmentations. We demonstrated the feasibility of our algorithm in processing typical meibograhy images, compared the acquired gland parameters of different images, and selected representative meibomian glands.

Methods

The development of this automated and multiparametric algorithm was based on Labview (Released 2016, National Instruments Corporation, USA) with NI vision Development Module 2016 on a PC running Windows 10. Images processed in this article were acquired using commercialized meibography Keratograph 5M (Oculus, Germany). The meibography acquired red-green-blue (RGB) infrared images and frames of the everted evelid area with a 1,088×512 pixel resolution. Acquired images were converted to grayscale, and then exported and saved as bitmaps for analysis with our customized software. The algorithm provides fully automatic and repeatable analysis in three steps: (I) segmentation of the tarsal conjunctiva area as the region of interest (ROI), (II) segmentation and identification of meibomian glands within the ROI, and (III) quantitative multiparametric analysis.

ROI segmentation

Figure 1 shows a flow map of the processing steps of the algorithm for ROI segmentation with a sample meibography image (Figure 1, I_G). In brief, automatic extraction of the ROI is performed by removing the unwanted signals outside the tarsal conjunctiva area and to fit the boundary of the ROI region. For this, the original grayscale meibography image (Figure 1, I_G) is firstly processed with a Prewitt operator to select the unwanted regions with eyelashes and highlight areas that typically appear around the eyelash roots and eyelid margin with large light reflections. The processed image is binarized and dilated to generate a mask image (Figure 1, I_M), which is then subtracted from the original grayscale image (*Figure 1*, I_G), resulting in the image in *Figure 1*, I_{GM} . The resulting image then undergoes median filtering with a circular structural element having a 3-pixel diameter to remove random noises. To enhance the image contrast and

visibility of the glands, the Convolution-Highlight Details operator is applied to the image with a structural element size of 25×25 pixels. Gland edges and image details are further sharpened and outlined by a Laplacian filter with a structural element size of 29×29 pixels, as shown in image Figure 1, I_{HD} . The processed image is then binarized and binary inversed to highlight the surrounding background of the glands on the tarsal conjunctiva area (*Figure 1*, I_{BI}). As the former subtracted regions are inversed to be positive, the mask image is subtracted again from the binary-inversed image Figure 1, IBI, resulting in image Figure 1, IBIM. To eliminate image speckles and small artifacts, the image in Figure 1, I_{BIM} was eroded by a structural element 5×5 pixels in size, which also shatters connected small irregularities. All signal blocks with a size smaller than 190 pixels and which are empirically found, are then cleared to remove small irregularities that do not belong to the everted evelid. The image is then dilated back by a structural element 5×5 pixels in size, and a border rejecting operator is applied to remove large irregularities connected with the image borders (Figure 1, I_{RSO}).

As most information on the tarsal conjunctiva area is kept, a gradient out operator with a circular structural element 8 pixels in diameter is employed to connect the signal blocks followed by a convex hull operator that uses a Graham scan algorithm to fit a closing shape of the tarsal conjunctiva area (Figure 1, I_{CH}). To remove the remaining surrounding lumps, the image is then eroded, withholding only the largest block, and then dilated back, resulting in a single block fitting the eyelid region (*Figure 1*, I_{CF}). To define the final ROI, the image, as represented by *Figure 1*, I_{CE} is converted into grayscale, and the contour of the final block is used to fit the final boundaries of the ROI. For the upper boundary, longitudinal top-down scans are performed to find the first signal rising points, which are then connected and fitted by a second degree, one-dimensional B-spline of the centripetal parameter (blue line in *Figure 1*, I_{CF}). For the lower boundary, the optimal fitting with a second degree, one-dimensional B-spline is performed to the line connecting the first signal rising points of the bottomup longitudinal scans in the image (green line in Figure 1, I_{CF}). The final ROI is acquired with the closing area formed by the fitted upper and lower boundaries (Figure 1, I_{ROI}). The original meibography image with the ROI boundary (red line in Figure 1, I_{GCF}), within which the gland segmentation and quantitative analysis would be performed, is also shown in *Figure 1*, I_{GCF} .



Figure 1 Flow map showing the algorithm steps for ROI segmentation.

Segmentation and identification of glands within the ROI

The main steps of the algorithm for meibomian gland segmentation are shown in Figure 2. The original grayscale meibography image (Figure 2, I_G) is first sequentially processed by a median filter, a Convolution-Highlight Details operator, and a Laplacian filter, as mentioned above in the description of the ROI segmentation process. This dampens the random noises and highlight the glands' visibility (*Figure 2*, I_{GHD}). The resulting image is then multiplied by the binary mask of the ROI and binarized (Figure 2, I_{GE}). To remove the remaining image speckles and smooth the shape of the glands, the binarized image is convoluted by a median filter with a circular structural element 5 pixels in diameter. As the ROI segmentation is usually overestimated resulting in some detected objects belonging to the edge of the everted eyelid, an orientation operator is applied to remove those objects with a main angle lower than 45° or higher than 135°. This is determined empirically, as the eyelid edges are typically horizontal while glands mostly have a vertical orientation. The image containing all the detected signals from the glands for gland area ratio analysis is shown as *Figure 2*, I_{GL}.

Since the small meibomian glands on the nasal and temporal sides are mostly irregular, usually out of focus, and unevenly illuminated during meibography imaging, these segmented glands are usually broken into pieces (Figure 2, I_{GL}). Thus, to perform further quantitative analysis of each single gland, these broken glands are excluded by eliminating objects containing fewer than 1,400 pixels, as shown in Figure 2, I_{MG} . While in some cases segmented glands can be connected (highlighted in green and yellow in *Figure 2*, I_{MG}), affecting the subsequent analysis, the connected glands are detected by calculating the number of horizontal segments, N_h, and vertical segments, N_v, of the single objects in Figure 2, I_{MG} and extracting those with $N_h > 350$ or $N_v > 200$ (Figure 2, I_{CG}). The extracted connected glands images (*Figure 2*, I_{CG}) are then sent to the gland fragmentation algorithm.

As shown in *Figure 3*, the gland fragmentation algorithm is developed to automatically separate connected glands. The extracted connected gland image (*Figure 3*, I_{CG}) is continuously eroded with a structural element size of 1×3 pixels until the detecting objects number, N, exceeds 1 (*Figure 3*, I_{ED}). The eroded image is then binary inversed and skeletonized to generate a skeleton image (*Figure 3*, I_{IS}), which is then subtracted from the connected gland image (*Figure 3*, I_{CG}), resulting in separation of the connected glands (Figure 3, IGS). However, as seen in the zoom-in area of Figure 3, I_{GS}, although separated, the single glands are disrupted by some skeleton branches. Before sending the separated disrupted glands for repair, the number of horizontal segments, N_h, and vertical segments, N_v, of the single objects depicted in Figure 3, IGS are calculated to ascertain whether objects of connected glands still exist. If they do, the eroding process is repeated to obtain further separation, and if not, the separated single disrupted glands (*Figure 3*, I_{SGS}) proceed to the repair process. By applying a gradient out operator with a circular structural element with a 3-pixel diameter followed by a fill hole operator, the disrupted single glands are fixed while being expended out by 1 pixel (*Figure 3*, I_{GO}). A gradient in the operator with a circular structural element 3-pixels in diameter is then applied to form the contours of the single glands (Figure 3, I_{GC}). Gland repair (*Figure 3*, I_{RG}) is achieved by subtracting the gland contours from the expended glands. The final separated glands are shown in *Figure 3*, I_{SG} . By combing the final separated glands and the detected single glands (red glands in Figure 2, I_{MG}), all intact glands are identified and labelled for further quantitative analysis.

Quantitative parameter analysis

Using the segmented ROI and labelled intact meibomian glands, quantitative parameters including the gland area ratio (GA), gland length (L), gland width (W), gland diameter deformation index (DI), gland tortuosity index (TI), and gland signal index (SI) are defined and computed.

The gland area ratio, GA is calculated as follows:

$$GA = \frac{N_{gl}}{N_{ROI}} \times 100\%$$
^[1]

in which N_{gl} is the number of pixels occupied by all detected signals from the glands (*Figure 2*, I_{GL}) and N_{ROI} is the number of pixels occupied by the segmented ROI area (*Figure 1*, I_{ROI}).

Morphological parameter analysis of the length, width, diameter deformation index, and tortuosity index are performed on each segmented and labelled gland (*Figure 2*, I_{LMG}). The single gland length, *L*, is defined as follows:

$$L = R \times l_{MN}$$
^[2]

in which l_{MN} is the length (in pixels) of the gland central line between endpoints M and N (*Figure 4A*), and R is the digital resolution of the meibography. By imaging a diffuse reflectance grid distortion target (#62-949, Edmund Optics),



Figure 2 Flow map showing the algorithm steps for meibomian gland segmentation. The gland fragmentation algorithm is depicted in *Figure 3*.



Figure 3 Flow map of the gland fragmentation algorithm to separate connected glands.

as shown in *Figure 4B*, *R* was calibrated to be 0.03 mm/*pixel* in our case with images captured by OCULUS Keratograph 5*M*. The gland width, *D*, is defined by the averaged width across a single gland:

$$D = R \times \frac{1}{n} \sum_{i=1}^{n} d_i$$
[3]

in which d_i is the width (in pixels) of the gland at every 3-pixel point on the gland central line and is calculated by the pixel length of the perpendicular line of the local

tangent line within the intersection points A, B on the gland edge contour (*Figure 4A*). To address diameter variations such as the uneven dilation and discontinuous atrophy of a gland, which are related to the status of the meibomian gland duct and acinus (37), the gland diameter deformation index, *DI*, is introduced by the following:

$$DI = \sigma_d = \sqrt{\frac{1}{n} \sum_{i=1}^n \left(R \times d_i - D \right)^2}$$
[4]

which is the standard deviation σ_d of the local gland widths





Figure 4 (A) Schematic illustrating the elements for morphological parameter calculation of a single meibomian gland; (B) meibography imaging of a diffuse reflectance grid distortion target for digital resolution calibration of the system.

within a single gland. To quantify the degree of gland curving and hairpin-loop-like winding changes, which mostly result from gland terminal duct obstruction, the gland tortuosity index, *TI* is defined as follows:

$$TI = \frac{l_{MN}}{l_{MN}'} \times \frac{1}{n} \sum_{i=1}^{n} k_i = \frac{l_{MN}}{l_{MN}'} \times \frac{1}{n} \sum_{i=1}^{n} \left| \frac{\Delta \alpha_i}{R \times \Delta s_i} \right|$$
[5]

in which l_{MN} is the length (in pixels) of the gland central line between endpoints M and N, l'_{MN} is the length (in pixels) of the straight line between endpoints M and N, k_i is the local curvature of the gland central line at every 3-pixel point, $\Delta \alpha_i$ is the angularity between tangent lines at point i and i-1, and Δs_i is the arc length (in pixels) between point i and i-1(*Figure 4A*). To obtain an overall evaluation of all the glands detected in the tarsal conjunctiva, the averaged length (\overline{L}) , width (\overline{D}) , diameter deformation index (\overline{DI}) , and tortuosity index (\overline{TI}) of all the detected meibomian glands are computed for each meibography image.

As meibomian gland functional and structural disorders affect meibum secretion activity, different meibum consistency and colour directly alter the reflection of the illumination light, resulting in changes in the signal intensity of glands in meibography images. To quantify the gland signal level in the image, which can potentially be used to evaluate the meibum secretion, the gland signal index is defined as follows:

$$SI = lg \frac{GREY_i}{GREY_0}$$
[6]

in which $GREY_i$ is the averaged image grey value of the segmented intact glands (*Figure 2*, I_{LMG}) in the raw meibography image (*Figure 2*, I_G), and $GREY_o$ is the averaged image grey value of the non-gland area (Inversed area of *Figure 2*, I_{GE}) within the ROI area in the raw image.

Results

To validate the performance of this automated and multiparametric algorithm, 15 meibography images were acquired with OCULUS Keratograph 5M (Oculus, Germany) from subjects of different meibomian gland health status. Images were evaluated and agreed upon by two professional ophthalmologists. Informed consent was obtained from the subjects. The experimental procedures adhered to the tenets of the Declaration of Helsinki [1983] and were approved by the Institutional Review Board of the Zhongshan Ophthalmic Centre, Sun Yat-sen University, China (protocol number: 2019KYPJ110). The ground truth of the ROI and meibomian glands segmentations were defined by the mean manually delineated ROI and glands' boundaries by the two ophthalmologists. The meibography images were also automatically and objectively processed



Figure 5 Illustrations of the contours of the (A) ROI and (B) meibomian glands of a representative meibography image segmented manually (yellow) and automatically (red).

by the algorithm for ROI and glands' segmentation and multiparametric calculation. The manual segmentation of each image took approximately 8 minutes, while the automated processing took approximately 15 seconds.

Segmentation performance validation

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To evaluate the segmentation performance of the algorithm, the similarity index (k) and segmentation error (32-35)were calculated between the manually defined ground truth segmentation and the automatic segmentation of both the ROI and meibomian glands. The similarity index (k), also known as the kappa coefficient, measures the similarity of the two segmentations defined by the ratio of the area of their intersection divided by the area of their union {Eq. [7]}. This ranges from 0 for segmentations that have no overlap to 1 for segmentations that are identical. To determine the segmentation error, we calculated the false-positive rate (r_p) and the false negative rate (r_N) . The false-positive rate (r_P) was depicted as the probability of the non-ROI/non-gland area included in the automatic segmentation results, and vice versa for the false-negative rate (r_N) . The false-positive rate (r_P) and the false-negative rate (r_N) were calculated by dividing the area of the incorrectly segmented non-ROI/non-gland area and ROI/gland area by the manually segmented ROI/ gland area, as shown in Equation 8 and 9 respectively.

$$k(S_{m}, S_{a}) = \frac{2|S_{m} \cap S_{a}|}{|S_{m}| + |S_{a}|}$$
^[7]

$$r_{P} = \frac{|S_{a}| - |S_{m} \cap S_{a}|}{|S_{m}|} \times 100\%$$
[8]

$$r_{N} = \frac{|S_{m}| - |S_{m} \cap S_{a}|}{|S_{m}|} \times 100\%$$
[9]

in which S_m is the manually segmented ROI/gland area and S_a is the automatic segmented ROI/gland area.

Figure 5 illustrates the contours of the segmented ROI (Figure 5A) and meibomian glands (Figure 5B) of a representative meibography image. The contours of the mean manually segmented ROI and meibomian glands are depicted in yellow while the algorithm automatically segmented contours are depicted in red. Table 1 shows the averaged similarity index and segmentation error between the manual and automatic segmentation of the ROI and meibomian glands for the 15 meibography images. For ROI segmentation, the similarity index (k)=0.94±0.02, the false-positive rate (r_p)=6.02%±2.41%, and the false-negative rate (r_p)=6.43%±1.98%. For meibomian gland segmentation, the similarity index (k)=0.87±0.01, the false-positive rate (r_p)=4.35%±1.50%, and the false-negative rate (r_p)=18.61±1.54%.

Automatic segmentation and multiparametric results

The segmentation results of the five representative meibography images acquired from subjects with different gland health status are shown in Figure 6. Images are displayed from Figure 6A, B, C, D, E based on their stage of MGD progression from healthy to severe as evaluated and agreed upon by the two ophthalmologists. The left column shows the original meibography images with the red curves encompassing the automatically segmented ROIs. The right column shows the segmented and labelled single meibomian glands for further quantitative analysis. The automatic calculated quantitative parameters, including the gland area ratio (GA), and gland signal index (SI), in addition to the averaged gland length (\overline{L}) , width (\overline{D}) , diameter deformation index (\overline{DI}) , and tortuosity index (\overline{TI}) , are shown in Table 2. The preliminary results indicate that as the severity of MGD progressed from healthy to severe stages, the measured GA decreased from 39.84% to 19.34% and the \overline{L} showed a downtrend. Despite this, \overline{D} , \overline{DI} , and \overline{TI} all increased in images of intermediate MGD and

Table 1 Averaged similarity index and segmentation error between the manual segmentation and automatic segmentation of the ROI and meibomian glands

Cogmontotiono	Similarity index (k)	Segmentation error		
Segmentations	Similarity index (k)	False-positive rate, r_P (%)	False-negative rate, r_N (%)	
ROI segmentation	0.94±0.02	6.02±2.41	6.43±1.98	
Glands segmentation	0.87±0.01	4.35±1.50	18.61±1.54	

Data are shown as mean ± standard deviation. ROI, region of interest.



Figure 6 The automatic ROI (left column) and meibomian gland (right column) segmentation results of the five representative meibography images with different health statuses of meibomian glands. The display sequence from (A-E) is based on their stage of MGD progression from healthy to severe.

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Meibography images	GA (%)	\overline{L} (mm)	\overline{D} (mm)	\overline{DI}	\overline{TI}	SI
A	39.84	5.62±1.25	0.35±0.08	0.10±0.04	0.18±0.11	13.91
В	36.73	5.04±1.20	0.42±0.07	0.12±0.03	0.26±0.08	20.27
С	31.57	5.05±1.26	0.42±0.10	0.15±0.07	0.30±0.26	19.53
D	29.20	4.55±1.25	0.42±0.08	0.15±0.04	0.40±0.21	18.15
E	19.34	2.62±0.76	0.32±0.06	0.09±0.04	0.18±0.09	24.97

Table 2 Multiparametric analysis results of the five representative meibography images with different health statuses of meibomian glands

Data are shown as mean ± standard deviation. GA, gland area ratio; L, gland length; D, gland width; Dl, gland diameter deformation index; TI, gland tortuosity index; SI, gland signal index.

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Table 3 Morphological parameters of representative meibomian glands

	Representative glands						
L (mm)	6.55	6.51	6.44	6.15	3.06		
D (mm)	0.35	0.48	0.54	0.58	0.34		
DI	0.07	0.13	0.18	0.25	0.09		
ТІ	0.13	0.31	0.41	1.12	0.20		

L, gland length; D, gland width; DI, gland diameter deformation index; TI, gland tortuosity index.

then declined in severe MGD when serious gland atrophy occurred. SI varied since the secretion, density, and colour of meibum inside the meibomian glands varied across cases.

Comparison of representative glands

To better demonstrate the correspondence of gland morphological parameters to detailed gland characteristics, especially the newly defined DI and TI, we selected several representative glands from the processed meibography images and compared the calculated morphological parameters and their appearance characteristics as shown in Table 3. This showed that the less uniform the gland diameter was along its length, the higher the gland DI was, which is directly related to the uneven dilation and discontinuous atrophy of the meibomian gland duct and acinus (29,30). In addition, the larger the degree of gland curving and winding was, the higher the TI, which reflects the typical macro tortuous appearance of meibomian glands appearing in intermediate MGD (25,29).

Discussion

In this study, we reported a fully automated algorithm

for the objective segmentation and multiparametric quantitative analysis of meibography images. The automatic segmentations showed high similarity with moderate segmentation errors when compared with manual segmentations performed by professional ophthalmologists. The use of traditional parameters, such as the gland area ratio, gland length, and gland width, along with the newly defined parameters, including gland diameter deformation index, gland tortuosity index, and gland signal index, achieved a more comprehensive analysis of meibography images.

Various researchers have conducted quantitative analysis of meibography images with everted evelid area and meibomian gland segmentations. However, most of these studies have implemented subjective methods to manually select the evelid region and/or segmented the gland/glandloss area with commercialized image editing software such as Image J (12,13,24) or self-developed semiautomatic algorithms (21) which usually have relatively low reliability and efficiency (24,25). Furthermore, while some automated methods have been developed, only a few researchers have tested multiparametric automated analysis methods. Arita et al. proposed image enhancement techniques to isolate meibomian glands but only computed the gland area ratio (22). Celik et al. introduced automated meibomian gland segmentation using Gabor wavelet filtering by extracting the orientation, width, length, and the curvature of segmented glands but used a standardized elliptical area for the ROI segmentation without adapting it to the real shape of each meibography image (23). Koh et al. reported an automated method to extract gland morphological features including gland length and width and trained a linear classifier for image classification but used manual selection for analysis of the eyelid region (26). Koprowski et al. described a fully automated approach that differentiated between gland, intergland, and gland drop-out areas to analyze images by gland area ratio together with detailed parameters quantifying the gland branches (27). Llorens-Quintana et al. developed an algorithm capable of segmenting both gland and tarsal conjunctiva areas automatically, and providing the gland area ratio, fitted ellipse for gland length and width analysis, and a newly defined gland irregularity parameter (28). Compared with the aforementioned approaches, our automated multiparametric algorithm identifies the ROI contours and segments meibomian glands based on image contrast enhancement and noise reduction. A subalgorithm has also been implemented to separate connected glands while not affecting their original appearance for

further morphological analysis. In addition to traditional parameters, we proposed a novel method to objectively quantify gland diameter variations, gland tortuosity, and gland signal level, thus offering more comprehensive information which is likely to be advantageous for detecting local and subtle changes of meibomian glands.

The segmentation performance evaluation results indicate that our automatic algorithm produced a relatively high false-negative rate for meibomian gland segmentation compared with the mean manual segmentation. This is because manual segmentation tends to include the gaps between the gland acinus as the gland area, while automatic algorithms are more sensitive to image contrast and can detect and exclude these gap areas. Compared with former studies, the gland area ratio calculated by our algorithm is relatively smaller (12). This is because we excluded the intergland area from calculating the gland area ratio, as our method can precisely distinguish meibomian glands from the intergland area, while most other methods include it. The quality of the meibography images acquired for algorithm processing needs to be guaranteed. Images with low contrast, inhomogeneous illumination, and poor resolution could introduce extra error during ROI and meibomian gland segmentations, affecting the reliability of the final quantitative analysis results. Although our algorithm is currently adapted to the images acquired with the OCULUS Keratograph 5M (Oculus, Germany)-as most of the processing parameters are selected empiricallyit may be adjusted to permit its use with other types of meibograpy instruments.

The algorithm offers more morphological and functional parameters for meibomian glands analysis, and our preliminary results show its potential in detecting subtle variations in meibomian glands. However, large scale clinical studies are needed to comprehensively characterize the relations between these quantitative parameters and the clinical manifestation of meibomian glands in different pathological stages of disease. Moreover, our current algorithm takes into account the analysis of the upper lid only. Since everting the lower evelid is not as easy as the upper eyelid where a larger tarsal plate exists, meibography images of the lower lid are typically unevenly focused and only partially expose the meibomian glands; thus, automatic segmentation of the ROI and meibomian glands in the lower lid remains challenging. Future work will focus on lower lid meibography image analysis since combining the evaluation of both lids offers better clinical diagnostic performance.

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Footnote

Conflicts of Interest: All authors have completed the ICMJE uniform disclosure form (available at http://dx.doi. org/10.21037/qims-20-611). The authors have no conflicts of interest to declare.

Ethical Statement: The experimental procedures adhered to the tenets of the Declaration of Helsinki [1983] and were approved by the Institutional Review Board of Zhongshan Ophthalmic Centre, Sun Yat-sen University, China (protocol number: 2019KYPJ110). Informed consent was obtained from all subjects.

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