



# Research on obtaining pseudo CT images based on stacked generative adversarial network

Hongfei Sun<sup>1</sup>, Zhengda Lu<sup>2,3,4</sup>, Rongbo Fan<sup>1</sup>, Wenjun Xiong<sup>1</sup>, Kai Xie<sup>2,3,4</sup>, Xinye Ni<sup>2,3,4</sup>, Jianhua Yang<sup>1</sup>

<sup>1</sup>School of Automation, Northwestern Polytechnical University, Xi'an, China; <sup>2</sup>Department of Radiotherapy, Second People's Hospital of Changzhou, Nanjing Medical University, Changzhou, China; <sup>3</sup>The Center of Medical Physics, Nanjing Medical University, Changzhou, China; <sup>4</sup>The Key Laboratory of Medical Physics, Changzhou, China

*Correspondence to:* Prof. Xinye Ni. The Affiliated of Changzhou No.2 People's Hospital of Nanjing Medical University, Xinglong street 29#, Changzhou 213000, China. Email: nxy@njmu.edu.cn; Prof. Jianhua Yang. Northwest Institute of technology, No.1 Dongxiang Road, Chang'an District, Xi'an 710000, China. Email: yangjianhua@nwpu.edu.cn.

**Background:** To investigate the feasibility of using a stacked generative adversarial network (sGAN) to synthesize pseudo computed tomography (CT) images based on ultrasound (US) images.

**Methods:** The pre-radiotherapy US and CT images of 75 patients with cervical cancer were selected for the training set of pseudo-image synthesis. In the first stage, labeled US images were used as the first conditional GAN input to obtain low-resolution pseudo CT images, and in the second stage, a super-resolution reconstruction GAN was used. The pseudo CT image obtained in the first stage was used as an input, following which a high-resolution pseudo CT image with clear texture and accurate grayscale information was obtained. Five cross validation tests were performed to verify our model. The mean absolute error (MAE) was used to compare each pseudo CT with the same patient's real CT image. Also, another 10 cases of patients with cervical cancer, before radiotherapy, were selected for testing, and the pseudo CT image obtained using the neural style transfer (NSF) and CycleGAN methods were compared with that obtained using the sGAN method proposed in this study. Finally, the dosimetric accuracy of pseudo CT images was verified by phantom experiments.

**Results:** The MAE metric values between the pseudo CT obtained based on sGAN, and the real CT in five-fold cross validation are  $66.82 \pm 1.59$  HU,  $66.36 \pm 1.85$  HU,  $67.26 \pm 2.37$  HU,  $66.34 \pm 1.75$  HU, and  $67.22 \pm 1.30$  HU, respectively. The results of the metrics, namely, normalized mutual information (NMI), structural similarity index (SSIM), and peak signal-to-noise ratio (PSNR), between the pseudo CT images obtained using the sGAN method and the ground truth CT (CTgt) images were compared with those of the other two methods via the paired t-test, and the differences were statistically significant. The dice similarity coefficient (DSC) measurement results showed that the pseudo CT images obtained using the sGAN method were more similar to the CTgt images of organs at risk. The dosimetric phantom experiments also showed that the dose distribution between the pseudo CT images synthesized by the new method was similar to that of the CTgt images.

**Conclusions:** Compared with NSF and CycleGAN methods, the sGAN method can obtain more accurate pseudo CT images, thereby providing a new method for image guidance in radiotherapy for cervical cancer.

**Keywords:** Image synthesis; pseudo computed tomography (CT); generative adversarial networks (GANs)

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## Introduction

As one of the most common gynecological tumors, cervical cancer seriously endangers women's health and lives (1,2). The current treatment methods include surgery or a combination of radiotherapy and chemotherapy, of which radiotherapy is suitable for the treatment of various cancer stages, and its therapeutic effect has been confirmed. Radiotherapy is becoming increasingly accurate due to the gradual advancement of precision techniques from two-dimensional (2D) traditional to image-guided radiotherapy.

Image guided devices used in the medical linear accelerator for the radiotherapy of cervical cancer include an electronic portal imaging device (EPID), cone beam CT (CBCT), and ultrasound (US). EPID is a two-dimensional image guidance device with the advantages of fast scanning speed and convenient operation, but the resolution of soft tissue is low, and its MV level energy increases radiation exposure (3,4). CBCT image guidance mainly uses rigid or affine registration between the CT image obtained in the simulation stage and the CBCT image obtained in the treatment stage based on bony landmarks or gray image information to verify positioning between the fractional treatment. However, it too has the disadvantage of the low resolution of soft tissue and radiation, and the artifacts caused by the radiation hardening effect and electron scattering reduce the image quality after image reconstruction (5-7). Compared with EPID- and CBCT-based image-guided devices, US-based image-guided devices offer the advantages of portability, non-radiation, and real-time operation, while effectively locating the position of the applicator (8) and have a good effect in the application of cervical cancer radiotherapy (9). Presently, the US can only assist CBCT images or independently carry out positioning verification before radiotherapy and cannot formulate and modify radiotherapy plans directly on US images. Therefore, in this study, we introduced a pseudo CT image synthesis technology based on US images to solve the problems mentioned above.

The conventional methods for obtaining pseudo CT images based on US images are mainly divided into two categories, the deformation-field registration method, and the image-synthesis method. The deformation field is obtained via registration between the US images scanned in the simulation stage, and those scanned in the treatment stage, and it is applied to the CT images scanned in the simulation stage to obtain the virtual CT image (10-12). However, the deformation field obtained using this method

is discontinuous, resulting in the inaccurate connection of tissues and organs at the critical points of different regions of interest (ROIs). Although this problem can be solved through smooth filter processing, it reduces the image definition, yet the deformation-field method's limitation can be overcome via image synthesis. The image-synthesis method involves the use of machine-learning or deep-learning algorithms to extract the image features of CT and other modal images, pair the features of the same region, consider the matching results as the training set, add the images of other modes in the test phase, and predict the corresponding pseudo CT images. Presently, scholars mostly use magnetic resonance imaging (MRI) and positron emission tomography (PET) images to synthesize pseudo CT images, and existing research on the synthesis of pseudo CT images based on US images is not profound (13-15).

Owing to the increased prevalence of deep learning, Gatys *et al.* proposed the neural style transfer (NST) method based on the convolutional neural network (CNN) and has been gradually used in image synthesis. The working principle of the method is to define the image-content-loss function and style-loss function. Simultaneously, both the content abstract-feature and style abstract-feature of two kinds of modal images are extracted using the deep-learning network model. Subsequently, one of the modal images is used as the reference image, and the other is reconstructed via iterative optimization (16). This method utilizes the advantage of CNNs to extract high-level features of images, artificially separates image style and content, and performs iterative optimization. Following Johnson *et al.* proposed the image method named fast NSF, wherein the forward convolution neural network replaced back propagation to expedite the optimization of the model to achieve real-time image-style transfer (17). Although the fast NSF method can stylize images in real time using GPU, owing to obvious differences among the styles of different modal images, a separate model must be trained for each style in advance, causing many manual operations to suffer from significant limitations. However, because the NSF method takes the pixel of the image as input, it judges the loss of each pixel one by one in the pixel space then averages the total loss of all the pixels to obtain blurred synthetic images. A method based on the generative adversarial network (GAN) model initially proposed by Goodfellow *et al.* has been developed for medical-image synthesis to achieve satisfactory results (18-21). This method utilizes the idea of confrontation to learn the generative model, automatically defines the potential loss function, and learns

the original real sample set's data distribution so that the sample distribution generated using the generator can approach the real-number sample distribution and possesses satisfactory generalization ability. As the training mode is antagonistic, the demand for training samples for the model is considerably reduced (22). The methods of synthesizing medical images based on GAN are mainly divided into supervised and unsupervised methods. The former method is based on the GAN model that contains conditional information. By learning the correspondence between the source images and target images, the mapping method of GAN through random vector is changed (23). Ben-cohen *et al.* established a model to synthesize PET images obtained by abdominal CT using the conditional GAN (cGAN) that contained the full convolutional network (FCN). The experimental results showed that the model could detect malignant tumors in the liver region and that it could replace the conventional PET-CT scan as the evaluation image for estimating the efficacy of drug treatment (24).

The latter is based on a coupled GAN model, which searches for the nonlinear mapping relationship between the two image domains or the nonlinear mapping relationship from different image domains to the same shared potential intermediate domain. The weight sharing, image reconstruction, and cyclic consistency constraints are used to replace the constraints on the synthesized images' contents, thereby limiting the learning range of the generator. Owing to the lack of explicit supervision information in the training process, this method can be used to synthesize unpaired source images and target images. Usually, the DualGAN or CycleGAN models are used in this process (25-28). Wolterink *et al.* used the CycleGAN model to train unpaired brain CT and MRI data by using a pair of mirror-symmetric GANs to establish a mapping relationship between the two modal images' data. The results showed that the pseudo CT images synthesized using the model were similar to real brain CT images in terms of anatomical structure (29). Also, Wang *et al.* added a deform convolutional network layer to the classical CycleGAN generator. They normalized the mutual information loss to the entire circulation network's loss function, thereby proving that the improved CycleGAN could be used for the mutual synthesis of the brain or abdominal MRI images and CT images with inconsistent imaging range (30). However, in CycleGAN-based image synthesis, the mapping difficulty between the two modal images is not consistent; therefore, it is difficult to completely reverse the entire cyclic network, which complicates the total objective function's

optimization. On this basis, the synthesis model between the two modal images also requires more time for training.

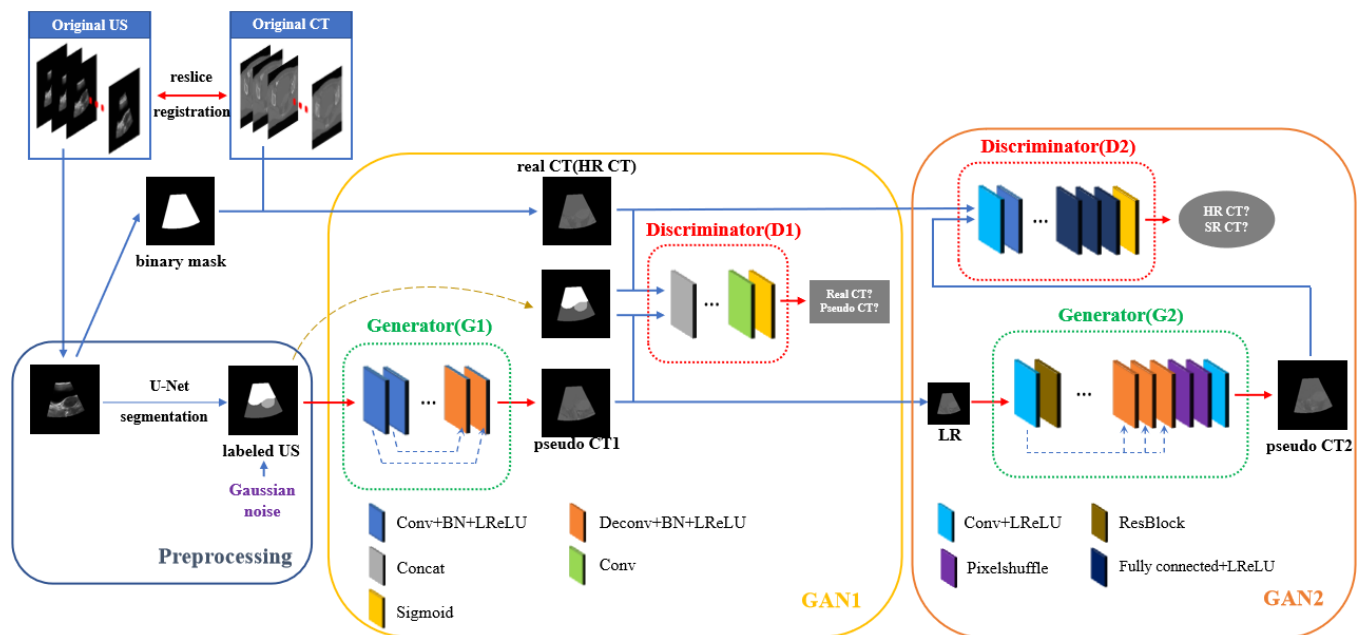
A single GAN cannot effectively process tasks, so we used Zhang *et al.*'s idea to synthesize high-resolution pseudo images based on stacked generative adversarial network (sGAN), and used multiple GANs to independently solve different tasks in the image-synthesis process (31). In this study, the synthetic process of pseudo CT was divided into two stages. In the first stage, labeled US images were input to the improved cGAN, and the corresponding mapping relationship with the CT image was established. This meant that both the main texture information and grayscale information of the target images were obtained, and low-resolution (LR) blurred pseudo CT images were synthesized. In the second stage, the LR blurred pseudo CT images obtained in the first stage were taken as the input of the super-resolution GAN (SRGAN). Also, ResNet and FCN were used to correct the results of the first stage obtaining pseudo CT images with clear texture and accurate grayscale information.

## Methods

To the best of our knowledge, this is the first application of GANs to synthesize US and CT images. We adopted cGAN in the supervised mode for image synthesis. A considerable advantage to this method is that by simultaneously conducting both procedures, the patient does not have to be moved. This means the relative position of the abdominal organs, including organs at risk (OARs), remains the same, reducing image guidance error and satisfying conditions for pairing training sets in image synthesis. In this study, the labeled US images obtained using the U-Net segmentation method were used as the input of cGAN. Also, pseudo CT images were synthesized using the generator of the encoder-decoder model that was based on both residual networks (ResNet) and the discriminator of FCN. Subsequently, the improved SRGAN was used further to enhance the imaging quality of the pseudo CT images, and the 3D pseudo CT images were synthesized using a reconstruction algorithm. The flow chart of the synthesis of pseudo CT images is depicted in *Figure 1*.

### *Data acquisition and image preprocessing*

The image data selected in the experiment were all 3D volume data of preoperative cervical cancer patients under Volumetric Modulated Arc Therapy (VMAT), of which

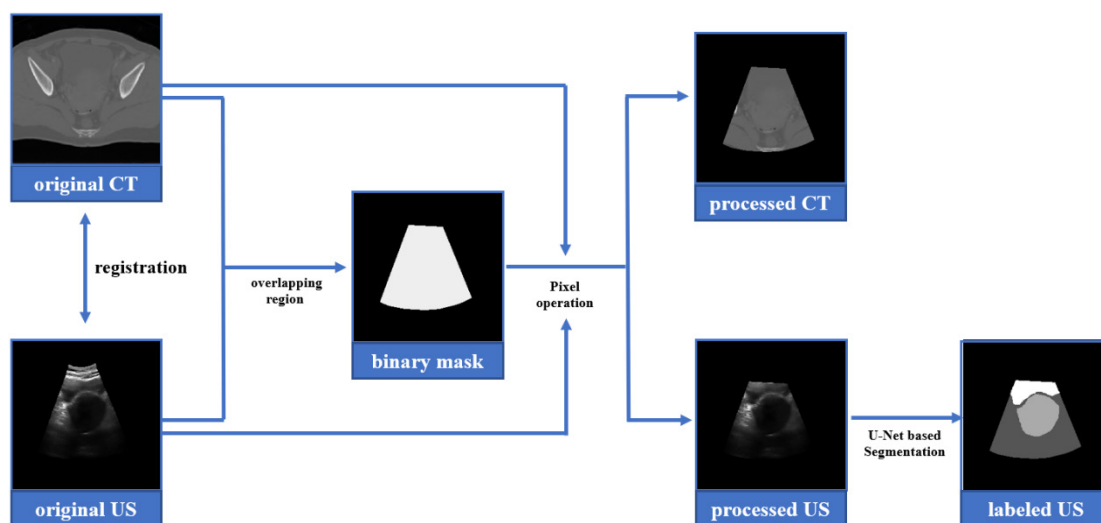


**Figure 1** Flow chart of pseudo CT image synthesis based on sGAN. GAN1 is the conditional GAN, which is used for the coarse synthesis of pseudo CT images. GAN2 is a super-resolution GAN, which is used to improve the resolution of pseudo CT images. sGAN, stacked generative adversarial network.

75 cases were used for model training and 10 used for model testing. The US and CT images obtained were collected during the patients' normal treatment, and informed consent was obtained from all individual participants. The ethics association approved the study of the Second People's Hospital of Changzhou, Nanjing Medical University (2017-002-01). The CT images were obtained by Optima CT520 produced by the GE Corporation (United States). The scanning conditions were as follows: tube voltage 120 kv, tube current 220 mA, image size  $512 \times 512 \times (196-239)$ , voxel spacing  $0.97653 \times 0.97653 \times 1 \text{ mm}^3$ . The CT images of 85 patients were scanned with the Clarity Ultrasound device produced by the Elekta Corporation (Sweden). The scanning conditions were as follows: C5-2/60 US probe, center frequency 3.5 MHz, image size  $400 \times 400 \times (220-295)$ , and voxel spacing  $1 \times 1 \times 1 \text{ mm}^3$ . Each patient was required to empty their bladder then 300 mL of water was delivered through a catheter to ensure the bladder was full before scanning. Before collecting US data, technicians calibrated the indoor laser lamp coordinate system and US probe with a calibration phantom. The 3D US probe has an infrared light refraction device similar to the shape of Octopus which reflects infrared light through eight different points and is received by the infrared device

above the scanning bed. The position of the probe, which represents the position of the scanned single frame image, is calculated according to its infrared receiving frequency. The 3D US is then reconstructed by interpolation based on each frame image's position by clarity system image. These calibrations ensure that the coordinate position of each 3D US voxel collected by the system is known relative to the indoor laser light coordinate system. When collecting patients' US data, the US probe is installed on the self-developed ultrasonic robotic arm, which can avoid the pressing error caused by manual data acquisition.

A US device is different from a CT device in terms of its scanning conditions and imaging principles. The original US and CT images required preprocessing before they could be used for pseudo image synthesis. While the advantage of US imaging is that it can satisfactorily distinguish the contour and relative position of OARs, the image noise is high, and it does not form a linear correction with the grayscale information of the CT image. This means it cannot be directly used in the synthesis of pseudo CT images and the region of the US image must be divided on the basis of semantic information. In addition, we performed affine registration between the original 3D US images and CT images to ensure their sizes and



**Figure 2** Acquisition of labeled US images.

resolutions were consistent. The size of the processed US and CT image data sets was  $256 \times 256 \times 100$ , and the voxel resolution was  $1 \times 1 \times 1 \text{ mm}^3$ . Subsequently, we created labeled US images using the semantic information as the input of cGAN. The labeled US images refer to the results obtained by labeling different OARs in the original US images based on the image segmentation method. Each labeled region's grayscale value is a certain number, but the values are different among different labeled regions. The image quality of the original US images was low, and the grayscale information in the images could not form a linear correlation with tissue density. Therefore, we referred to the method of Isola *et al.* (32), which sees the original US images replaced by the labeled US images with Gaussian noise as the input of the sGAN model. The labeled US images retain the edge information of tissues and organs and have relative position information between different OARs. There were four acquisition steps in the labeling of US images. In the first step, the ImageJ software was used to reslice the 2D slices of the 3D US and CT images after registration to ensure that the 2D slices of the two modal images within the registration range were aligned one by one. The 3D volume data was then divided into 100 2D layers. In the second step, binary masks were made, and the 2D US and CT images of the same slice were multiplied by pixels to obtain the overlapping region. The pixel value of the overlapping region was set to 1, while the remaining region was the background, whose pixel value was set to 0. The third step saw the binary masks obtained in the second

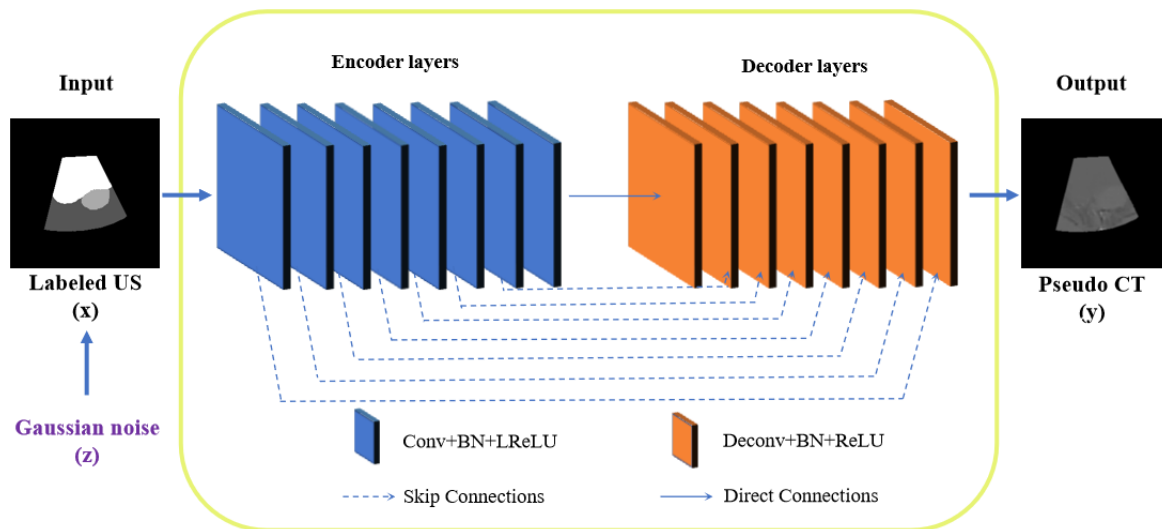
step, respectively processed with the original US and CT images for pixel calculation. The redundant pixels in the original images were then removed to ensure that the two modalities' imaging regions were the same. Using the U-Net method, the US images were segmented into multi-target regions to obtain labeled US images in the fourth step. Also, to reduce the bladder region's deformation due to US probe compression, we connected the upper two vertices of the bladder region in the US images to compensate for the partial absence of the region from the images. The flow chart of the acquisition of the labeled US images is depicted in *Figure 2*.

### ***Supervised deep conditional convolutional adversarial network***

CNN with ResNet has been proven to perform satisfactorily in a variety of image-processing tasks (33–35). Through identity shortcut connection, the network's output is expressed as a linear superposition between the input and a nonlinear transformation thereof. Notably, the most significant difference between ResNet and direct-connected CNN is that the former provides some protection to information integrity because it can directly transmit it from input to output along with the shortcut. This makes the target of model learning more concise and solves the problem of gradient disappearance in the training process (36).

The generator is an improved U-Net to which a residual connection has been added. This means each deconvolution





**Figure 3** The generator of cGAN. cGAN, conditional generative adversarial network.

layer's input is the linear superposition between the previous layer's output and the output of the symmetric convolutional layer, effectively doubling the feature maps (37). This method retains the image feature information at different resolutions, ensuring the encoder's feature information can be continuously re-remembered during the decoder operation and that the synthesized pseudo images can retain the feature information of the original input images to the greatest extent. Also,  $z$  is the input of random Gaussian noise distribution. The parameters of the network model after training have been determined. If the inputs are the labeled US images without adding noise, the output results of pseudo CT images will be unchanged, making them different from the real CT images. The structure of the generator with residual connections is depicted in *Figure 3*.

The input of the network is the labeled US images. The nodes from each network layer in each encoder part to the next include the convolution layer, batch-normalization (BN) layer, and LReLU activation layer. Also, each node to the next in the decoder part includes the deconvolution layer, BN layer, and ReLU activation layer. The network layers of both the encoder and decoder are symmetrically distributed, and the loss function of the generator includes content loss and counter loss. The mean square error (MSE) loss function can be used to train the network to obtain a high peak signal-to-noise ratio (PSNR), so the calculation of the MSE is determined by the MSE ( $L_{MSE}$ ) between the pseudo CT images [ $G(x, z)$ ] synthesized using the US images ( $x$ ) and ground truth CT (CTgt) images ( $y$ ), where  $z$

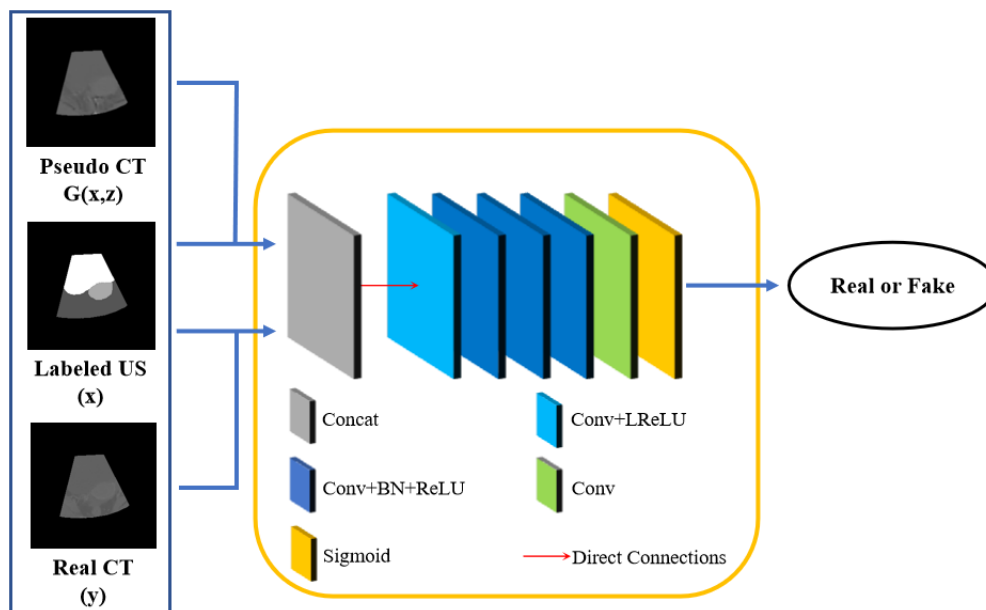
is the noise. Calculation of the PSNR uses the binary cross entropy ( $L_{BCE}$ ) as the loss where  $\alpha$  is the LBCE loss term's weight coefficient in the loss function. In following the experimental results of Isola *et al.*, we set this to 0.5 (32). The loss function of the generator is given as follows:

$$L_{G_1} = L_{MSE}(G(x, z), y) + \alpha L_{BCE}(1, D(x, G(x, z))) \quad [1]$$

This study also used a Markov discriminator, an FCN that comprises five convolutional layers and one Sigmoid activation layer. The input passes through one node, including the convolution and LReLU activation layers, then through three nodes, including the convolution, BN, and ReLU activation layers, and the output is finally obtained through the convolution layer and fully connected layer. The discriminator's output size is a probability matrix with the dimensions of  $30 \times 30 \times 1 \text{ mm}^3$ . The result of averaging the matrix is the final output of the discriminator. This architecture can make the model retain more image details during training. The network structure of the discriminator is depicted in *Figure 4*.

To calculate the loss function, the discriminator includes two inputs and two corresponding outputs. It takes as one input the labeled US image ( $x$ ) and pseudo CT image [ $G(x, z)$ ] generated using the generator to obtain the output  $\{D[x, G(x, z)]\}$  and takes as another output the labeled US image ( $x$ ) and CTgt images ( $y$ ) to obtain the output  $\{D(x, y)\}$ . The loss function of the discriminator is given as follows:

$$L_{D_1} = L_{BCE}(1, D(x, y)) + L_{BCE}(0, D(x, G(x, z))) \quad [2]$$



**Figure 4** The discriminator of cGAN. cGAN, conditional generative adversarial network.

### Super-resolution reconstruction of pseudo CT images

LR CT images are converted into high-resolution ones via certain algorithms, and the resulting images are super-resolution CT images. Super-resolution CT images have high pixel density and detailed information. As the resolution of the pseudo CT images obtained using cGAN was not high, their texture information was blurred, so we used the SRGAN to obtain more abundant texture information of the pseudo CT images.

The generated network contained five residual blocks, and each contained two convolution layers with a kernel size of  $3 \times 3$ . Each convolution layer was connected to a BN layer and PReLU activation layer. Subsequently, four deconvolution layers were connected, and each contained deconvolution, BN, and ReLU activation operations. The second to fourth deconvolution layers' inputs were the linear superposition of the output of the previous layer and output of the first deconvolution layer. Subsequently, two Pixelshuffle layers and one deconvolution layer were connected, and the Pixelshuffle layer improved the image resolution via sub-pixel operation. The feature maps of  $r^2$  channels were obtained via convolution, then high-resolution pseudo CT images were obtained via periodic screening, wherein  $r$  was the upscaling factor, i.e., the expansion rate of the images (38). The network structure of the generator is depicted in *Figure 5*.

The loss function of the SRGAN generator also includes content loss and adversarial loss. The content loss is the MSE ( $L_{MSE}$ ) between the super-resolution pseudo CT image  $[G(a)]$  synthesized using the LR pseudo CT image and CTgt image (b). The adversarial loss is the binary cross entropy ( $L_{BCE}$ ) between probability 1, and probability  $D[G(a)]$  that  $G(a)$  is identified as a real image (39) and  $\beta$  is the weight coefficient of  $L_{BCE}$  loss term in the loss function. This is an empirical value, which we also set to 0.5. The loss function of the generator is given as follows:

$$L_{G_2} = L_{MSE}(G(a), b) + \beta L_{BCE}(1, D(G(a))) \quad [3]$$

The discriminator is a CNN with 10 convolution layers, three fully connected layers, and one sigmoid activation layer. The convolution layer includes convolution, BN, and LReLU activation operations. The first two fully connected layers use LReLU as the activation function, and the third fully connected layer uses the Sigmoid activation function to obtain the judgment result of the discriminator. For a convolutional layer, the size of the convolutional kernel is  $3 \times 3$ ; the number of convolutional kernels is 32, 32, 64, 128, 128, 256, 512, and 512; the step size is 1, 2, 1, 2, 1, 2, 1, 2, and 2, and the Padding is SAME. The output obtained after convolution is reconstructed into a 1D tensor and taken as the fully connected layer's input. Also, the number of nodes in all three fully connected layers is 1024, 512, and 1, respectively. The structure of the discriminator is depicted

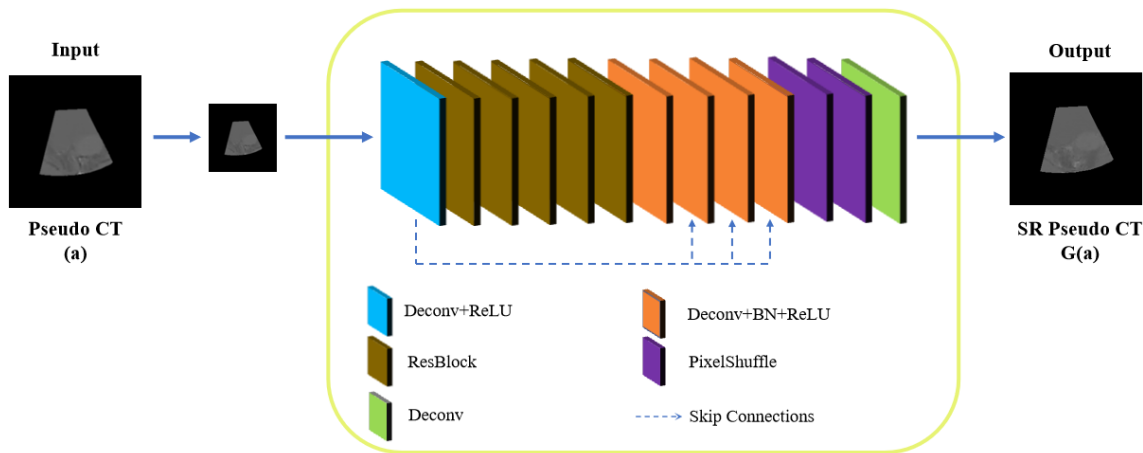


Figure 5 The generator of SRGAN. SRGAN, super-resolution generative adversarial network.

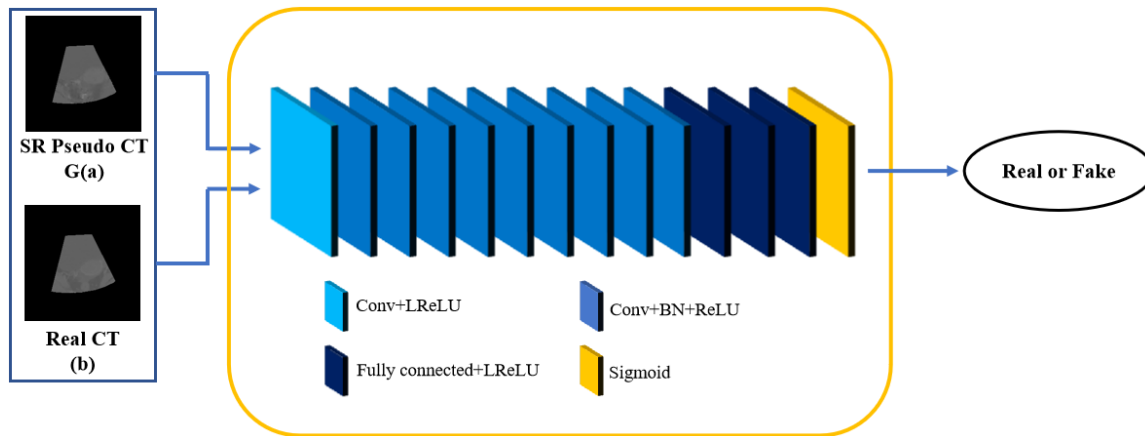


Figure 6 The discriminator of SRGAN. SRGAN, super-resolution generative adversarial network.

in Figure 6. This discriminator also includes two inputs and two outputs. It takes as one input the  $G(a)$  of the super-resolution pseudo CT image generated using the generator to obtain the output  $D[G(a)]$ , and takes  $b$  (CTgt image) as another input to obtain the output  $D(b)$ . The loss function of the discriminator is given as follows:

$$L_{D_2} = L_{BCE}(1, D(b)) + L_{BCE}(0, D(G(a))) \quad [4]$$

**Technical details**

All networks are optimized with the Adam optimizer, where cGAN is trained from scratch with a learning rate of  $10^{-6}$  with a batch size of 1. SRGAN is trained from scratch with a learning rate of  $10^{-4}$ , and the batch size is also 1. The two GAN networks' epochs are both 100, and the code is

implemented using the TensorFlow library. We performed experiments on a personal computer equipped with a GPU (Nvidia GeForce RTX 2080Ti) and a CPU (Intel Core i9-9900K).

**Evaluation**

To verify the model's performance, a five-fold cross-validation technique was used in the training and testing steps. The 75 cases were randomly divided into five groups, and four groups (including 60 cases) were selected for each experiment to test the trained model. After training, the model was applied to the CBCT images of the remaining 15 subjects to generate pseudo CT. To verify the accuracy of the pseudo CT images obtained based on the improved



sGAN, pseudo CT synthesized based on the NSF and CycleGAN methods were selected as control experiments, and the CTgt was the actual CT image.

The accuracy of the HU value of pseudo CT and real CT of each subject is evaluated by calculating the mean absolute error (MAE) of voxels in the pelvic region:

$$MAE(CT_{re}, CT_{ps}) = \frac{1}{N} \sum_{i=1}^N |CT_{re}(i) - CT_{ps}(i)| \quad [5]$$

where N is the total number of voxels in the CT pelvic region.  $CT_{re}$  is a real image scanned by a CT machine, and  $CT_{ps}$  is the pseudo CT obtained by different methods. The smaller the MAE value, the closer the pseudo CT images' HU value to the real CT images.

To test the results of 10 cervical cancer patients in the testing phase, the accuracy of the image-synthesis algorithm was evaluated using the following three quantitative metrics: NMI (40), SSIM (41), and PSNR (42).

The first metric is NMI, which is used to evaluate the similarity between CTgt images and pseudo CT images, and was obtained using different methods. The function expression is as follows:

$$NMI(CT_{gt}, CT_{ps}) = \frac{2I(CT_{gt}, CT_{ps})}{H(CT_{gt}) + H(CT_{ps})} \quad [6]$$

$$I(CT_{gt}, CT_{ps}) = H(CT_{gt}) - H(CT_{gt} | CT_{ps}) \\ = H(CT_{ps}) - H(CT_{ps} | CT_{gt}) \quad [7]$$

where  $I(CT_{gt}, CT_{ps})$  denotes the mutual information value between the pseudo CT and CTgt images, and  $H(CT_{gt})$  and  $H(CT_{ps})$  denote the information entropy. The closer the NMI metric value is to 1, the better the registration result.

The second metric is SSIM, and its mathematical definition is as follows:

$$SSIM = \frac{(2\mu_{I_g} \mu_{I_p} + C_1)(2\sigma_{I_g I_p} + C_2)}{(\mu_{I_g}^2 + \mu_{I_p}^2 + C_1)(\sigma_{I_g}^2 + \sigma_{I_p}^2)} \quad [8]$$

$$C_1 = (k_1 L)^2, \quad C_2 = (k_2 L)^2$$

where  $\mu_{I_g}$  and  $\mu_{I_p}$  denote the mean grayscale values of the CTgt image and pseudo CT image, respectively;  $\sigma_{I_g}$  and  $\sigma_{I_p}$  denote the variances of the grayscale value of the CTgt and pseudo CT images, respectively;  $\sigma_{I_g I_p}$  denotes the covariance;  $C_1$  and  $C_2$  denote constants to maintain stability; L denotes the dynamic range of the CT image grayscale; and  $k_1=0.01$  and  $k_2=0.03$ . The SSIM value lies in the range

of [0, 1], and the closer the SSIM value is to 1, the greater the similarity between the two images.

The mathematical definition of the PSNR measurement method is as follows:

$$PSNR = 20 \log_{10} \left( \frac{MAX_I}{\sqrt{\frac{1}{XYZ} \sum_{x=0}^{X-1} \sum_{y=0}^{Y-1} \sum_{z=0}^{Z-1} |I_{gt}(x, y, z) - I_{ps}(x, y, z)|^2}} \right) \quad [9]$$

where  $I_{gt}$  and  $I_{ps}$  denote the CTgt and pseudo CT images, respectively. Also, X, Y, and Z denote the size of the image, and  $MAX_I$  denotes the maximum grayscale value of the CT images. The lower the MAE value and higher the PSNR value, the more similar the synthetic pseudo CT image is to the CTgt image. The calculation of the three measurements mentioned above methods is related to the grayscale of CT images, and the grayscale range of the CT images is unified into the range of [0, 4,000] (43).

The DSC was used to evaluate bladder and uterine regions' segmentation accuracy in the pseudo CT images (44). In this study, the distinct curve guided FCN proposed was used to segment the OARs in the pelvic region of the pseudo and real CT images (45). Calculating the volume overlap of bladder and uterus between CT images, the accurate segmentation results should have a high organ volume overlap rate. Notably, DSC is given as follows:

$$DSC = \frac{2|L_{CT_{gt}} \cap L_{CT_{ps}}|}{|L_{CT_{gt}}| + |L_{CT_{ps}}|} \quad [10]$$

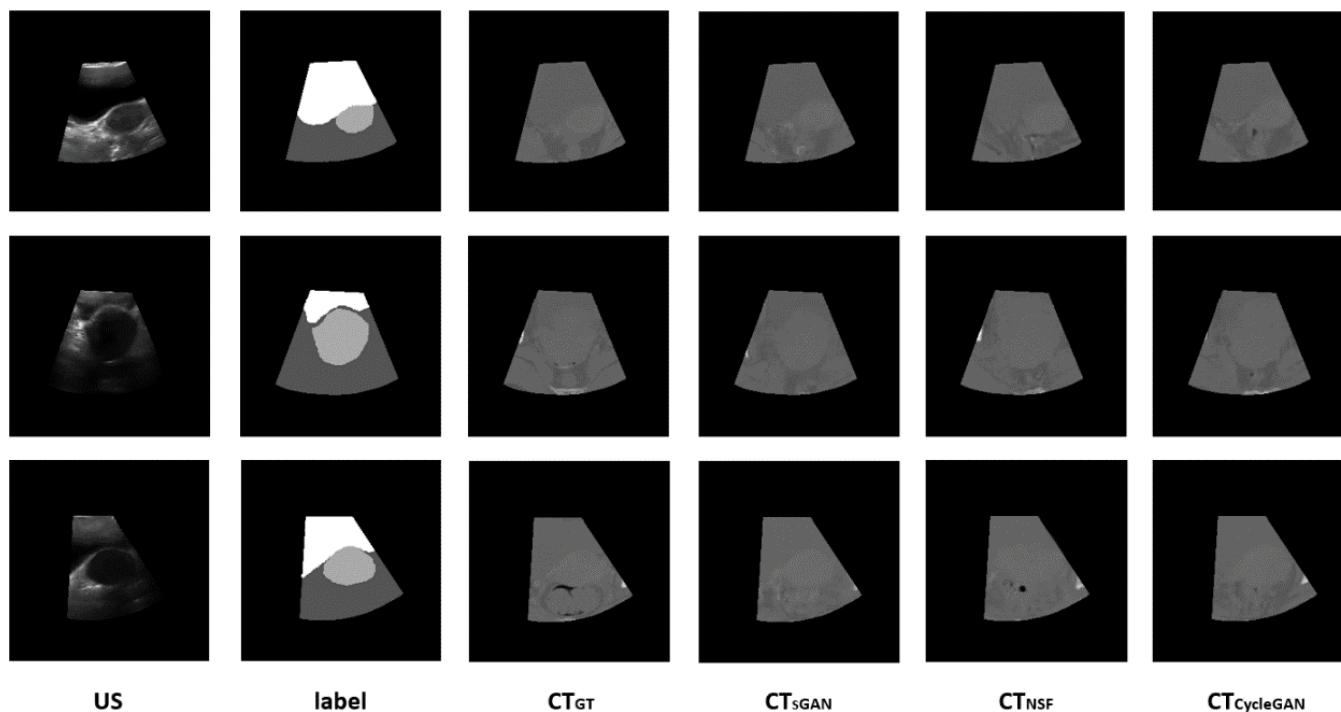
where  $L_{CT_{gt}}$  and  $L_{CT_{ps}}$  denote the bladder or uterus's binary segmentation results in the CTgt and pseudo CT images, respectively, which were obtained using the method proposed in this study. The closer the DSC value is to 1, the higher is the similarity between the bladder and uterine regions in the pseudo CT image and the CTgt image.

To verify the accuracy of the pseudo-CT image based on US image synthesis in dose calculation, this study conducted a phantom experiment and selected real scanned CT images as the ground truth images for dosimetry verification. Medical physicists define and outline the planning target volume (PTV) and organs at risk (OARs) on CTgt images and copy them to the pseudo CT images synthesized based on different deep learning methods. The VMAT radiotherapy plan was made on the CTgt images, and the Monte Carlo algorithm calculated a dose of 4,500 cGy/25 F. After the optimized plan met the clinical requirements, the plan was copied to different pseudo CT images. To compare the difference between pseudo CT and CTgt images in the radiotherapy plan, the 4,500 cGy prescription dose with

**Table 1** The MAE metric results computed between real CT image and different pseudo CT images for five-fold cross validation

	Fold1	Fold2	Fold3	Fold4	Fold5
sGAN (HU)	66.82±1.59	66.36±1.85	67.26±2.37	66.34±1.75	67.22±1.30
NSF (HU)	77.11±2.99	77.21±2.30	75.33±4.30	75.87±3.56	76.87±2.04
CycleGAN (HU)	65.61±2.48	64.58±2.79	66.24±4.28	67.05±4.31	65.53±2.44

sGAN, stacked generative adversarial network; NSF, neural style transfer.



**Figure 7** Pseudo CT image results based on three different image-synthesis methods. CTgt, the ground truth CT; CTsGAN, pseudo CT image obtained using sGAN; CTNSF, pseudo CT image obtained using neural style transfer; CTCycleGAN, pseudo CT image obtained using CycleGAN.

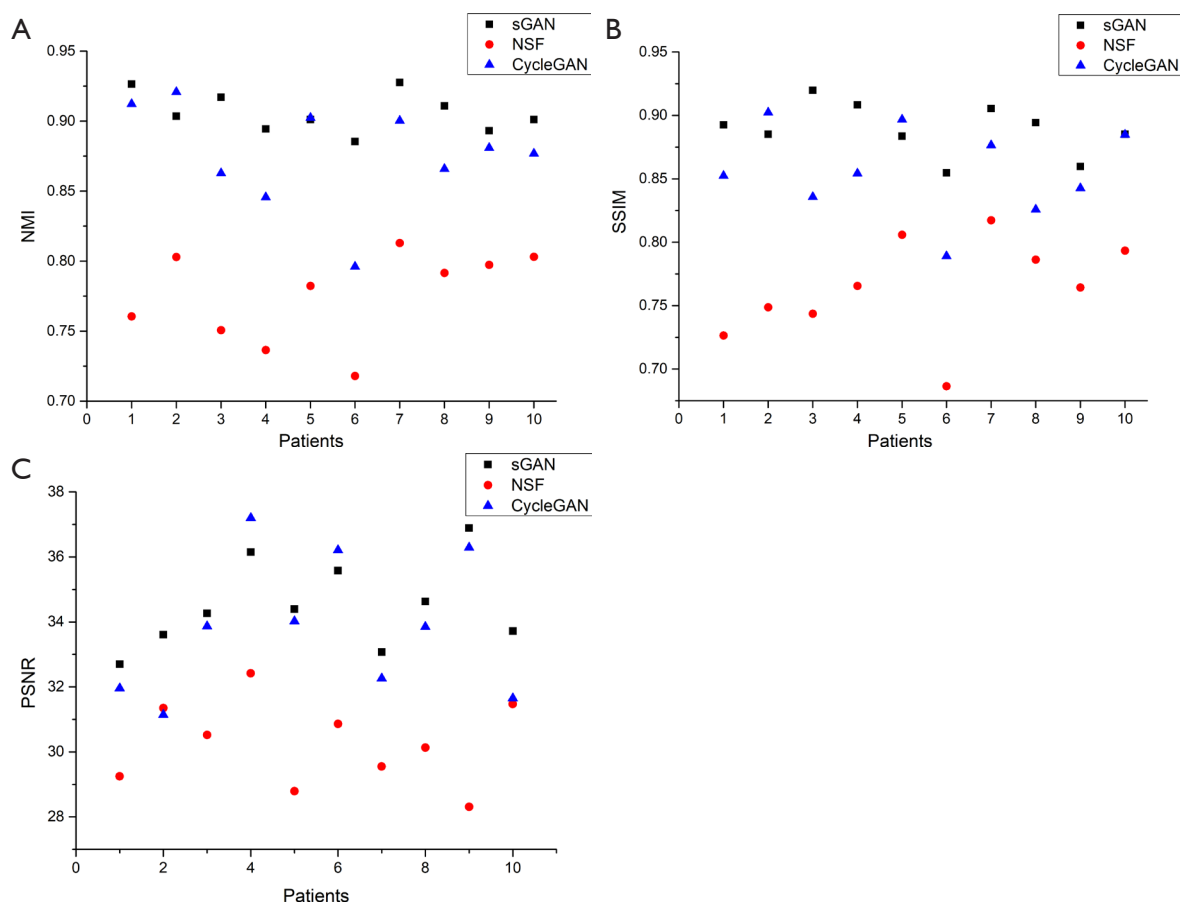
95% PTV was used as the plan's passing criterion. The doses in PTV and OARs of cervical cancer patients, which were obtained based on pseudo CT and CTgt images under the same optimization conditions of VMAT treatment in the Monaco planning system, were compared. Dosimetry evaluation indexes mainly include dose volume histogram (DVH), maximum dose (Dmax), average dose (Dmean), and minimum dose (Dmin).

## Results

Table 1 shows the MAE measurement results between the real CT images and the pseudo CT images synthesized by

different methods. Compared with NSF's method, sGAN has a lower MAE value, which indicates that the pseudo CT image synthesized by SGAN is closer to the real CT image. Compared with CycleGAN, SGAN does not have obvious advantages, although on the premise of ensuring image quality, the SGAN method has more stable training results than the CycleGAN method and is also universal for training volume data.

Figure 7 depicts the pseudo CT image obtained using three different image-synthesis methods. Although the NSF-based method can roughly obtain pseudo CT images, it blurs the edge information between different tissues and organs, resulting in the mismatching of CT values

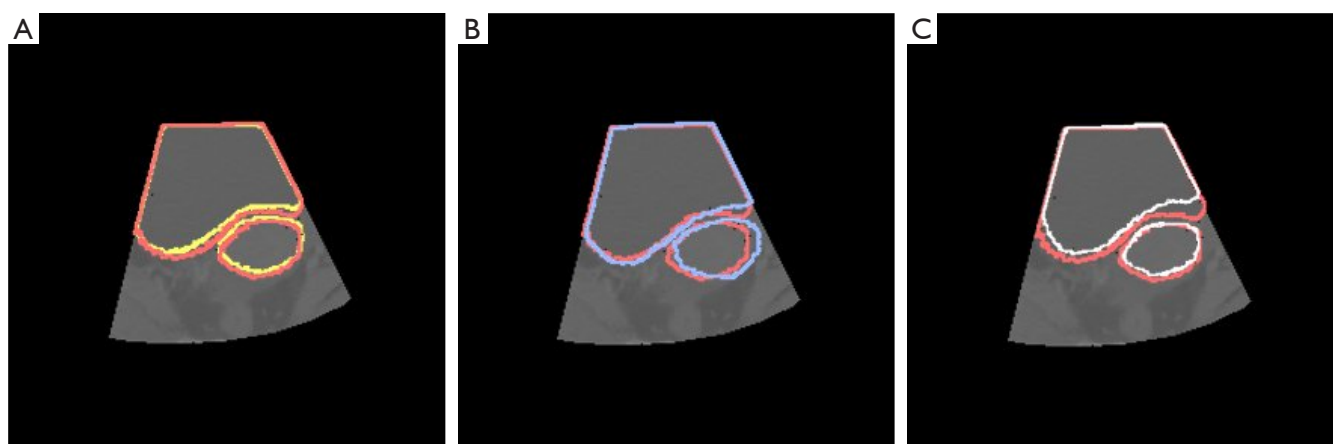


**Figure 8** Measurement results of pseudo CT images and CTgt images using three different image-synthesis algorithms. (A) measurement results based on NMI; (B) measurement results based on SSIM; (C) measurement results based on PSNR. NMI, normalized mutual information; SSIM, structural similarity index; PSNR, peak signal-to-noise ratio.

in different imaging regions. Compared with the NST method, the pseudo CT images obtained using CycleGAN are more accurate; however, the resulting images are not stable because of the difference between the two modal images to be synthesized. If the difference is considerable, the synthesized image data is poor; otherwise, the result is satisfactory. The sGAN method proposed in this study ensures that each organ's relative position in the image remains unchanged and provides accurate organ contour and grayscale information. Also, the result of image synthesis is relatively stable, indicating a more favorable outcome compared with the other methods. The NMI, SSIM, and PSNR measurement results for the pseudo CT images synthesized using three different image-synthesis methods, and CTgt images are depicted in *Figure 8*. According to the comparison results, the CTgt and pseudo CT images obtained using the method proposed in this

study are significantly different from those obtained using the other two methods ( $t_{\text{NMI}(\text{sGAN-NSF})} = 13.594$ ,  $t_{\text{NMI}(\text{sGAN-CycleGAN})} = 3.053$ ,  $t_{\text{SSIM}(\text{sGAN-NSF})} = 10.621$ ,  $t_{\text{SSIM}(\text{sGAN-CycleGAN})} = 2.914$ ,  $t_{\text{PSNR}(\text{sGAN-NSF})} = 8.999$ ,  $t_{\text{PSNR}(\text{sGAN-CycleGAN})} = 2.530$ , and  $P < 0.05$ ).

The difference between the contour of the OARs in the CTgt image and pseudo CT image is depicted in *Figure 9*. The contour is obtained via the automatic segmentation method of region growth. The yellow region in *Figure 9A* represents the contour of the OARs in the pseudo CT image obtained using sGAN; the blue region in *Figure 9B* represents the contour of the OARs in the pseudo CT image obtained using NSF, and the white region in *Figure 9C* represents the contour of the OARs in the pseudo CT image obtained using CycleGAN. The red region in each of these figures represents the contour of the OARs in the CTgt image, and the closer the red and other-color contour



**Figure 9** Contour differences of OARs between CTgt images and synthetic CT images. (A) Contour differences of OARs between CTgt images and pseudo CT images obtained based on sGAN. (B) Contour differences of OARs between CTgt images and pseudo CT images CT images obtained based on NSF. (C) Contour differences of OARs between CTgt images and pseudo CT images CT images obtained based on CycleGAN. The red curve shows the contour of the OARs in the CTgt images. The yellow curve represents the contour of the OARs in the pseudo CT images obtained using sGAN. The blue curve represents the contour of the OARs in the pseudo CT images obtained using NSF. The white curve represents the contour of the OARs in the pseudo CT images obtained using CycleGAN. OAR, organs at risk; CTgt, ground truth CT; sGAN, stacked generative adversarial network.

**Table 2** DSC measurement results of registration accuracy between ground truth CT images and pseudo CT images synthesized by three different methods

DSC (%)	Patients number									
	1	2	3	4	5	6	7	8	9	10
sGAN	91.7	89.4	91.2	88.7	89.8	87.9	91.0	90.5	89.7	90.4
NSF	82.6	83.8	80.9	78.4	82.2	77.1	84.2	82.7	81.9	79.7
CycleGAN	86.3	90.6	86.1	85.5	90.1	83.6	89.4	88.3	89.7	88.2

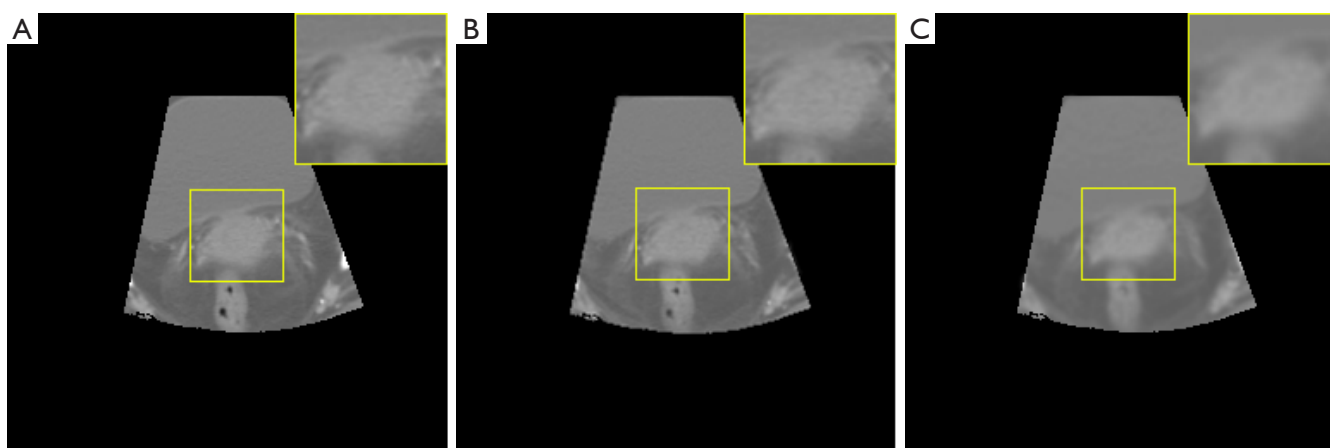
DSC, dice similarity coefficient; sGAN, stacked generative adversarial network; NSF, neural style transfer.

regions are, the more similar the regions are to one another. *Table 2* lists the registration accuracy of the OARs evaluated via DSC values between CTgt and pseudo CT images synthesized using different methods. Compared with the other two methods, the registration results of the OARs between these images obtained using the sGAN method have a higher DSC value.

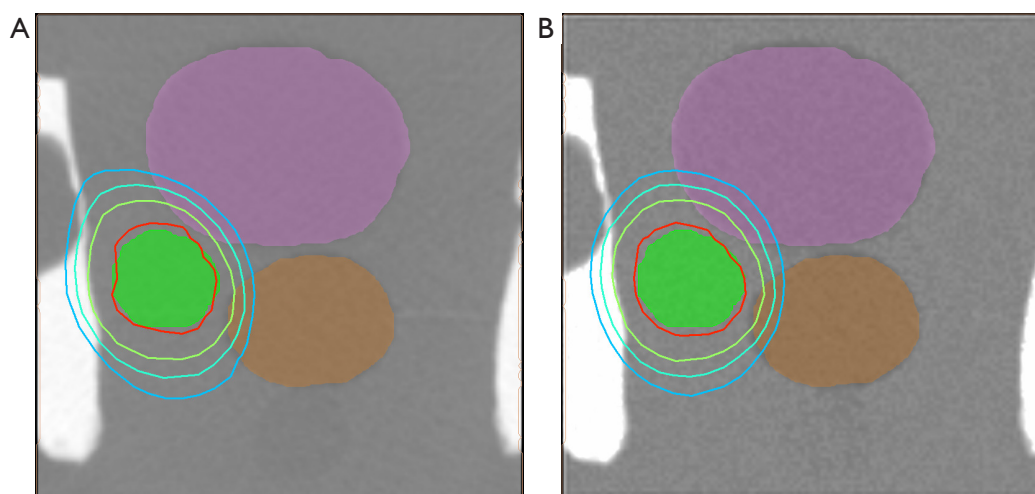
Also, to prove the effectiveness of SGAN in synthesizing pseudo CT images compared with cGAN alone, we compared the pseudo CT image results obtained by sGAN and cGAN separately, and the comparison results are shown in *Figure 10*. *Figure 10A* shows the real CT images; *Figure 10B* shows the pseudo CT images obtained based on sGAN, and *Figure 10C* shows the pseudo CT images obtained based on cGAN. The yellow square is a local

enlarged image. This demonstrates that cGAN alone cannot obtain high-resolution pseudo CT images, and the results need to be input into SRGAN for resolution reconstruction, to obtain a more clear texture and better visual effects.

We used an ultrasound phantom for dosimetry verification. The dose distribution results of real CT and pseudo CT images obtained based on the SGAN method are shown in *Figure 11*, respectively. The green region is PTV, the pink and orange regions are OAR1 and OAR2, respectively, and the brown line is the outer contour. In *Figure 11*, the dose lines around the PTV region are 4,500 cGy, 4,000 cGy, 3,500 cGy, and 3,000 cGy from inside to outside. This shows that the dose distribution of CTgt and pseudo CT obtained based on sGAN is different, and the pseudo CT has a better conformal degree. The



**Figure 10** The comparison results of pseudo CT images were obtained by sGAN and cGAN, respectively. (A) Real CT images. (B) Pseudo CT images obtained based on sGAN. (C) Pseudo CT images obtained based on cGAN. The yellow square is a local enlarged image. sGAN, stacked generative adversarial network; cGAN, conditional generative adversarial network.



**Figure 11** Dose distribution map of PTV based on different CT images. a: Dose distribution map based on real CT images. b: Dose distribution map based on pseudo CT image.

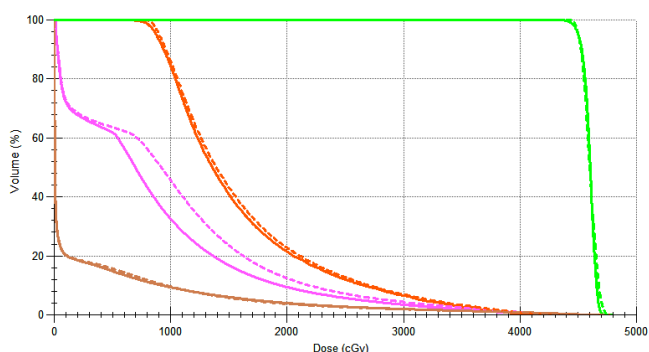
difference is that the relative position between OARs and PTV in the synthesized pseudo CT image is different from that of CTgt. *Figure 12* shows the comparison results of the DVH dose difference of the same OARs and PTV in different CT images. The solid line is CTgt, and the dashed line is the pseudo CT obtained based on sGAN. This shows that with the exception of OAR1, the remaining dose lines in the DVH chart have relatively small differences, and their specific dose differences are shown in *Table 3*. *Table 3* also lists the Dmax, Dmean, and Dmin values of PTV and OARs under pseudo-CT and CTgt radiotherapy plans. The

difference in most index values between the two CT images is within 50 cGy.

## Discussion

In this study, 3D US and CT images were registered in the image pre-processing stage, and the 2D images were rearranged according to the patient's axial direction. Therefore, in training data, the target was to search for the mapping relationship between continuous 2D images in ultrasound and CT image domains, reducing the problem





**Figure 12** Comparison results of DVH dose difference of the same OARs and PTV in different CT images. DVH, dose volume histogram; OAR, organs at risk; PTV, planning target volume.

**Table 3** Comparison of dose indexes of PTV and OARs in four CT images based on Monte Carlo optimization

Plan name	Metric	PTV	OAR1	OAR2
CTgt	Dmax	4,730.1	4,371.6	4,155.1
	Dmin	4,350.1	9.1	669.3
	Dmean	4,596.5	861.8	1,591.2
CTps	Dmax	4,771.6	4,427.0	4,236.0
	Dmin	4,410.5	10.2	782.8
	Dmean	4,598.7	923.2	1,628.4

PTV, planning target volume; OAR, organs at risk; Dmax, maximum dose; Dmean, mean dose; Dmin, minimum dose; CTgt, ground truth CT; CTps, pseudo CT obtained by sGAN.

of mismatch during training. Also, following the pseudo CT image synthesis task based on sGAN, we use 3D image reconstruction technology to reconstruct a 2D pseudo CT image sequence. The reconstructed 3D volume data were compared with ground truth CT images (real scanning CT), which showed good similarity in anatomy and dosimetry. From the experimental results, it is evident that compared with other methods, sGAN can more effectively synthesize pseudo CT images. Within the same imaging range, the organs' anatomical structure in the pseudo CT image obtained using the sGAN method was more similar to that in the CTgt image. The sGAN method used the image-synthesis network and the image super-resolution reconstruction network and trained these different GAN networks separately, thereby reducing the complexity of the total loss function and obtaining satisfactory training results in the local network. In the cGAN-based image

synthesis, labeled images based on the US images were added to constrain the synthetic region of different organs in the pseudo CT images. Simultaneously, the content of different labels was locally matched with the corresponding region in the target CT image to avoid semantic mismatch. In the SRGAN-based image synthesis, a series of residual blocks and skip connection were added to the generator to reconstruct the LR pseudo CT image and further improve its texture clarity. The pseudo CT images obtained using the sGAN method based on the two networks were similar to the real CT images. Also, the NSF method suffers from semantic-mismatching problems, such as background-texture migration of the style image to the foreground of the target image without maintaining semantic consistency during the transfer process, and no global linear matching relationship exists between US image and CT image (46). Therefore, the pseudo CT images obtained using this method differed from the CTgt images in terms of grayscale information and anatomical structure. Also, CycleGAN achieved satisfactory results in unsupervised image-synthesis tasks. However, for the image synthesis based on the complexity of different textures and anatomical structures, the consistent loss coefficient of the cycle loss used by CycleGAN was invariant. Therefore, although the grayscale information of the pseudo CT synthesized using this method was similar to that of the CTgt, it could not effectively and stably synthesize the pseudo CT image. When OARs are irregular and texture information complex, the pseudo CT image synthesized using this method would be distorted, and the contour of the organs within the imaging range show greater deviation from the real image.

In the cGAN-based image synthesis, the generator's structure was designed as the encoder-decoder mode with residual concatenation. First, the input labeled US image was down-sampled to reduce the image's feature resolution, then the LR image features were learned via feature transformation. Finally, the LR image features were amplified in the spatial dimension via up-sampling, and the image was restored to the input dimension. The mode can compress redundant feature information and effectively extract it. In the decoder part of the generator, the previous layer's output features and those of the image layer of the decoder were spliced as the input of the deconvolution layer, thereby ensuring that the finally generated pseudo CT image integrated more shallow information and provided accurate gradient information. The generated CT image had a high coincidence degree with the corresponding

organ contour in the US image. In terms of discriminators, we used a six-layer full CNN. The labeled US image was connected to the pseudo CT image synthesized using the generator and real CT image, respectively, as two discriminator inputs. The discriminator's output was a matrix of dimension 30×30 pixels, and each element of the matrix corresponding to a receptive field of 70×70 pixels of the original input image. This means the input image was divided into 900 image blocks, each of 70×70 pixels, to identify true and false. The discriminator's output in the traditional GAN comprised the single probability of judging whether the input image was true or false. This method takes the mean value of each element in the matrix as the output of true/false and judges the local region of the input image block-by-block so that the discriminator can accurately judge the input image's details. This improves the final generation quality of the pseudo CT image. Also, in the generator and discriminator, the LReLU activation function was used to avoid highly sparse gradients, and BN was used to normalize the output of the intermediate hidden layer, thereby stabilizing the distribution of input data in each layer of the network and expediting the learning speed of the model (47).

In SRGAN-based image super-resolution reconstruction, the second to sixth layers of the generator used residual blocks. Except for the first ResNet layer, each ResNet layer's input was the sum of the outputs of the first two layers. We also used skip connection to transfer the input layer's shallow information to deeper deconvolution layers in the network to ensure that the gradient information of CT images could be effectively transmitted with the deepening of the number of network layers. This enhanced the robustness of SRGAN and avoided the gradient-diffusion phenomenon in the back-propagation process. The VGG19 network structure was adopted in the discrimination network, and a BN layer was added to expedite the training. Also, the max-pooling layer in the network was removed to avoid the feature-information loss. In taking the pseudo CT images obtained using cGAN as the input of SRGAN, their resolution can be improved, and after the SRGAN-based reconstruction, the texture information of the pseudo CT image became more significant and is more similar to the CTgt image.

The supervised-mode-based sGAN also has limitations. Because this method requires paired data sets in pseudo CT image synthesis, mismatched CT-US image pairs may fail synthetic images. Also, inaccurate label production in the preprocessing would affect the subsequent image-

synthesis results. In subsequent experiments, we will use the improved CycleGAN network to establish the nonlinear mapping relationship between US and CT images and carry out the pseudo CT image synthesis task. By adjusting the network parameters and loss function, we want to make the CycleGAN network training stable. Also, the image-synthesis model used in this study is based on 2D resliced image data. Compared with 3D image synthesis, the training time is longer and spatial information is ignored. Since this study is a preliminary one on applying the deep-learning method in the US- and CT-image synthesis, in the following experiments, we will use more patient data and introduce the GAN based on 3D convolution kernel further to improve the accuracy of pseudo CT image synthesis. We will also evaluate the application of pseudo CT images of real patients in radiotherapy from the perspective of dosimetry.

## Conclusions

We proposed a novel method to perform the step-by-step synthesis of pseudo CT images based on sGAN. In this method, LR pseudo CT images were synthesized using labeled US images as the input to cGAN. Subsequently, the pseudo CT images' resolution was further improved via SRGAN, and images with more significant texture information were obtained. The experimental results showed that the pseudo CT images obtained using the proposed method had high similarity with CTgt images and had a satisfactory radiotherapy application potential.

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## Footnote

*Conflicts of Interest:* All authors have completed the ICMJE

uniform disclosure form (available at <http://dx.doi.org/10.21037/qims-20-1019>). The authors have no conflicts of interest to declare.

*Ethical Statement:* The Medical Ethics Committee of the Second People's Hospital of Changzhou, Nanjing Medical University approved the study (2017-002-01), and informed consent was obtained from all individual patients.

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