

Automatic evaluation of endometrial receptivity in three-dimensional transvaginal ultrasound images based on 3D U-Net segmentation

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Background: Endometrial thickness is an essential factor affecting female fertility. Clinically, ultrasound imaging is the first choice for the examination of uterine and endometrial-related diseases. However, the boundary of some endometrial is challenging to distinguish due to the effects of image resolution and noise. In addition, the irregular shape of the endometrium makes it more difficult for doctors to measure its thickness. Through the automatic segmentation and extraction of the endometrium, the maximum thickness of the endometrium can be measured automatically and accurately. This provides a quantitative index for doctors to use diagnostically.

Methods: In this study, 85 cases of three-dimensional transvaginal ultrasound (3D TVUS) images were collected retrospectively, including 75 cases of endometrial adhesion and 10 cases of non-adhesion. Firstly, the ultrasound images were filtered by block-matching and 3D filtering and speckle reducing anisotropic diffusion (SRAD). These two kinds of filtered images were combined with the original image to construct a three-channel image. Then, the augmented images were sent to 3D U-Net to realize endometrium segmentation. The performance of the segmentation models was evaluated using the Dice similarity coefficient (DSC), Jaccard, sensitivity, and 95th percentile Hausdorff distance (HD95). Finally, the medial axis transform was used to extract the endometrial centerline, based on which the endometrial thickness could be automatically measured.

Results: The endometrium segmentation method proposed in this paper achieved 90.83% in Dice, 83.35% in Jaccard, 90.85% in sensitivity, and 12.75 mm in HD95 in the testing set. Taking the doctor's manual measurement as the gold standard, 94.20% of the automatic endometrial thickness measurements based on the segmentation results were within the allowable error range of clinical diagnosis.

Conclusions: This paper presents an automatic endometrium segmentation and thickness measurement method for 3D TVUS images. The experimental results show that this method has high segmentation accuracy to recognize endometrial adhesion images. Furthermore, the thickness measurement based on the

4096

segmentation results has high reliability and repeatability, and the accuracy can meet clinical diagnosis needs.

Keywords: Three-dimensional transvaginal ultrasound images (3D TVUS images); endometrium segmentation; thickness measurement; deep learning

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Introduction

The endometrium, including the superior inner cortex and mucosa, is essential for fertility and reproductive health. Clinically, endometrial thickness is essential for diagnosing endometrial-related diseases (1-6). In addition, endometrial receptivity reflects the receptivity of the endometrium to embryos, which is often evaluated by endometrial thickness in the clinic (7-9). If the endometrium is too thin, it is not conducive to embryonic implantation and development.

Ultrasound imaging and magnetic resonance imaging (MRI) are the main ways to diagnose uterine and endometrial-related diseases (10-12) To date, threedimensional (3D) ultrasound has been widely used in clinical medicine to provide continuous anatomical images for diagnosis. A 3D ultrasound can enable doctors to observe the endometrium's shape, echo, and thickness more intuitively, and it is of great value in diagnosing uterine diseases (13-16). Furthermore, 3D ultrasound imaging facilitates obtainment of the complete information of the uterus and endometrium in real-time from three different angles—the coronal plane, sagittal plane, and transverse plane.

In ultrasound-based endometrial disease screening, the quantitative evaluation result of endometrial diseases is generally achieved by measuring the thickness of the endometrium. In clinical medicine, the acceptable error range of endometrial thickness measurement is $\pm 2 \text{ mm}$ (17,18). However, manual measurement of endometrial thickness is based on personal experience in clinical diagnosis, and subjective factors may affect the measurement position. Furthermore, some endometrial boundaries are challenging to identify because of the resolution and noise of the image. In addition, the irregular shape of the endometrium increases the difficulty of manual measurement by doctors. Therefore, the current diagnostic methods may have issues such as low accuracy and poor repeatability of the endometrium measurement results.

So far, the research on endometrial segmentation in

ultrasound images has achieved some valuable results. Yang *et al.* (19) proposed an endometrium segmentation algorithm in uterus contraction, using a recursive model and multi-threshold technology to extract the uterus in motion and automatically segment the endometrium to provide evaluation indexes for the treatment of infertility. Thampi *et al.* (20) used the level set method to segment the endometrium in two-dimensional (2D) ultrasound images of endometrial cancer. The algorithm first performed speckle reducing anisotropic diffusion (SRAD) filtering on the image, then selected the initial contour and realized the segmentation of the region of interest (ROI) using the level set. However, the segmentation result of this method will depend on the seed point selection of the level set.

In recent years, a convolutional neural network (CNN) has been widely applied to the processing and analysis of medical images and has shown excellent performance in medical image segmentation (21-23). The U-Net network is a typical CNN model for medical image segmentation. With the development of technology, researchers began to extend 2D convolution to 3D convolution to introduce the spatial information of data (24). The 3D U-Net was first developed for 3D medical image segmentation and achieved good research results (25). Chen et al. (26) proposed a 3D U-Net network based on the channel attention for multi-modal brain tumor segmentation. Mourya et al. (27) proposed the cascaded 3D U-Net to realize automatic segmentation of the liver and tumor in computed tomography (CT) images, and its Dice for liver segmentation reached 95%.

The CNN was also applied to endometrial segmentation. Hu *et al.* (28) used the visual geometry group (VGG) network to realize automatic endometrium segmentation in 2D ultrasound images and calculated the maximum endometrial thickness perpendicular to the central axis, which was extracted through the medial axis transformation (MAT) (29,30). Singhal *et al.* (31) proposed an endometrium segmentation algorithm based on fully



Figure 1 Flow chart of data screening process. 3D, three-dimensional.

convolutional networks (FCN) and level set and realized the automatic measurement of endometrial thickness. The algorithm performed the 2D segmentation and thickness measurement of endometrium through a hybrid variational curve propagation model, namely, the deep learning snake (DLS) segmentation model. Park *et al.* (32) employed the critical point discriminator to train the endometrium segmentation network to learn the shape distribution of the endometrium. As a result, the problem of edge blur and uneven texture of 2D ultrasound images was solved by adversarial learning that could realize the endometrium's automatic segmentation.

The above endometrium segmentation studies were all based on the sagittal plane of 2D ultrasound images. Although 3D images were used by Singhal *et al.* (31), the network segmentation training was still carried out for 2D images slice by slice. However, compared with 2D, 3D ultrasound provides complete structural information. Furthermore, the accuracy of endometrium segmentation determines the accuracy of endometrial thickness measurements. Therefore, based on 3D ultrasound images, this paper presents an automatic endometrium segmentation using a 3D U-Net (33). Then, the method obtains the measurement of endometrium thickness. We present the following article in accordance with the STARD reporting checklist (available at https://qims.amegroups. com/article/view/10.21037/qims-21-1155/rc).

Methods

Materials

Constrained by the time of the data collection and retention in the ultrasound instruments, we performed staged data collection to obtain sufficient data. In each stage of data collection, all ultrasound images were selected. Therefore, a total of 113 three-dimensional transvaginal ultrasound (3D TVUS) images from October 2019 to May 2021 (October-December 2019, March-May 2020, October-December, and March-May 2021) were collected retrospectively in this study. The ages of all patients ranged from 29 to 41. For the acquired data, we excluded patient data that were duplicated within one month, poor quality images, and images with indistinguishable endometrial areas. After data screening, 85 cases were selected for this study, including 75 cases with endometrial adhesion and 10 cases without endometrial adhesion. The data selection process is shown in Figure 1. The images were collected by Voluson E8 three-dimensional ultrasonic equipment and the transducer RIC5-9-D (center frequency 6.6 MHZ, bandwidth 5 MHZ-9MHZ; GE Healthcare, Chicago, IL, USA). The slice spacing of the image data was between 0.22 and 0.31 mm, and the resolution was between 0.2933 and 4.413 pixels per mm. The three-section images of the endometrium with or without adhesion are shown in Figure 2, the coronal section of the endometrium in Figure 2A, the transverse section in



Figure 2 Images of the endometrium. The first row shows normal endometrium, the second shows the endometrium with adhesion, and the red line shows the endometrial boundary in each section. (A) Coronal section images; (B) transverse section images; and (C) sagittal section images.

Figure 2B, and the sagittal section in *Figure 2C*. The first row is normal endometrium, the second is the endometrium with adhesion, and the red line shows the endometrial boundary in each section.

The study was conducted in accordance with the Declaration of Helsinki (as revised in 2013). The study was approved by the Institutional Review Board of Shengjing Hospital of China Medical University, and individual consent for this retrospective analysis was waived.

Study methods

This paper used 3D U-Net to segment endometrium from 3D ultrasound images. Two experienced doctors manually annotated the endometrium on the coronal section by ITK-SNAP (http://www.itksnap.org/pmwiki/pmwiki.php) and measured the endometrial thickness as the gold standard for evaluation. In the case of disagreement, another more senior clinical physician was asked to analyze and confirm the final annotation results. The overall research method is shown

in *Figure 3*. The 3D U-Net uses 3D convolution instead of 2D (34). With a 3D image as input, the structure information between slices of the image could be better extracted in the encoder part of the network, and the ROI could be more accurately located in the decoder part, which realized more accurate segmentation of the endometrium. Then, the endometrial thickness could be automatically measured according to the sagittal endometrium segmentation results, and the receptivity could be evaluated with the thickness.

Image preprocessing

The noise of ultrasound images has a significant influence on model learning. Therefore, we performed image filtering on the original images, including block-matching and 3D filtering (BM3D) and the SRAD (35-37). As a result, the noise of the image was removed, while the edge information was preserved as much as possible. These two kinds of filtered images were combined with the original image to construct a three-channel image. Then, the augmented



Figure 3 Flowchart of the method. The first red column on the right shows the different sections obtained by 3D U-net segmentation and the reconstructed endometrial images, and the second column shows the segmentation results of the sagittal section used for endometrial thickness measurement. Conv, convolution; BN, batch normalization; Relu, rectified linear units; 3D, three-dimensional; U-net, U-shape network.

images were sent to 3D U-Net to realize endometrium segmentation. The image process after two filtering processes are shown in *Figure 4*, the original image in *Figure 4A*, the image after SRAD filtering in *Figure 4B*, and the image after BM3D noise removal in *Figure 4C*.

To achieve a better performance during deep learning model training, we chose two methods for data augmentation. One was to augment the training data by rotating, scaling, translating, and mirroring. The other method was to randomly extract patches from the ROI of the data to increase the training samples (38,39). By trying different patch sizes in training, we finally determined to extract ten patches with the size of 96×96×32 for each case as the input of network training. When testing, the same size patches were extracted by sliding windows, and there are 50% overlapping areas between patches. When synthesizing the results, the mean value of the overlapping areas was calculated, and then the prediction results were back to 224×224×32 images.

3D U-Net segmentation

We used a 3D U-Net to segment the endometrium. Since most of the research on endometrium segmentation has been carried out on 2D ultrasound images, we conducted a comparative experiment of 2D U-Net and 3D U-Net segmentation. Among the 85 cases of data, 15 cases (13 with adhesion and 2 without) were randomly selected as the testing set, and the other 70 cases were used as the training set. All experiments in this paper were carried out on NVIDIA GTX 1080 graphics card (NVIDIA, Santa Clara, CA, USA).

In the 3D U-Net segmentation experiment, the image



Figure 4 Image filtering. (A) Original image; (B) image filtered by BM3D; and (C) image filtered by SRAD. BM3D, block-matching and 3D filtering; SRAD, speckle reducing anisotropic diffusion.

size sent into the network training was $224\times224\times32$. When training, the Adam optimizer was used for optimization with momentum parameters of beta1 =0.9, beta2 =0.999, and epsilon =1e-8 (40). The initial learning rate was 10^{-3} . During the training period, the learning rate decayed according to Eq. [1]. The batch size was 1 due to graphics processing unit (GPU) limitations, epochs were 800, and the Dice loss was used as the loss function. Sigmoid was selected as the activation function, and a threshold of 0.5 was used to obtain the final segmentation mask from the output of the 3D U-Net. In the experiment, the original data (OD) set, the augmented OD set, and the augmented filtered data set were trained, respectively, and the corresponding segmentation model and segmentation results were obtained.

$$lr = initial_{lr} * decay_{rate}^{\frac{global_{step}}{decay_{steps}}}$$
[1]

Where *lr* represents the current learning rate, *initial*_{*lr*} represents the initial learning rate, $decay_{rate}$ represents the decay rate, $global_{step}$ represents the current training round, and $decay_{steps}$ represents the decay period.

Automatic measurement of the endometrium thickness After obtaining the segmentation results of the endometrium through the 3D U-Net, the automatic measurement of endometrium thickness was conducted. Although the original image in this study was the coronal image, the sagittal image can better reflect the thickness of the endometrium. Therefore, the sagittal endometrium segmentation results were used to measure and evaluate thickness. First, the centerline of the segmented endometrium was extracted through the MAT. Then, the distances perpendicular to the centerline were calculated according to the endometrium contour. Furthermore, the maximum distance was taken as the endometrium thickness in this slice, consistent with the evaluation method in clinical medicine. The results of automatic measurement of endometrium thickness according to MAT is shown in *Figure 5*, the images of different sagittal section images of the endometrium in *Figure 5A*, the corresponding endometrium contour and centerline obtained by MAT in *Figure 5B*, and the corresponding thickness measurements in *Figure 5C*. The code for endometrial segmentation, evaluation, and endometrial thickness measurement can be found on GitHub (https://github.com/wx-hub/package.git).

Evaluation method

The Dice similarity coefficient (DSC), Jaccard, sensitivity, and 95th percentile Hausdorff distance (HD95) were used as the parameters for the segmentation evaluation. The DSC, Jaccard, sensitivity, and HD95 were calculated as follows:

$$DSC = \frac{2TP}{FP + 2TP + FN}$$
[2]

$$Jaccard = \frac{TP}{TP + FP + FN}$$
[3]

$$Sensitivity = \frac{TP}{TP + FN}$$
[4]

$$HD(P_i, G_i) = \max\left(H_{95}(P_i, G_i), H_{95}(G_i, P_i)\right)$$
^[5]

$$H_{95}(P_i, G_i) = 95K_{p \in P_i}^{th} min_{g \in G_i} \|P_i - G_i\|$$
[6]

where *TP*, *FP*, and *FN* represent the number of true positive, false positive, and false negative pixels, and *HD*



Figure 5 Automatic endometrium thickness measurement. The orange line is the endometrial border, the yellow line represents the centerline of the endometrium, the blue line represents the maximum thickness of the endometrium, and the green line shows the thickness of the endometrium at different locations. (A) The different sagittal section images; (B) the corresponding endometrium contour and the centerline obtained by MAT; and (C) the corresponding thickness measurements. MAT, medial axis transformation.

represents the maximum surface distance between the predicted mask map P_i of pixel i and the corresponding ground truth G_i manually marked by the expert. The K_{th} ranking distance was used to suppress outliers.

Results

Endometrium segmentation results

Segmentation of different network

For 2D U-Net, we selected the original coronal image

containing the ROI as the input for network training. According to the case division of the training and testing set, we obtained 2,000 training images and 480 testing images. During the training, an Adam optimizer was used for optimization. The initial learning rate was 10^{-4} , epochs were 500, and the binary cross-entropy was used as the loss function. Different batch sizes were tested, and the final model selected the batch that had the best segmentation results.

The segmentation results of 2D U-Net and 3D U-Net



Figure 6 Endometrium segmentation results of 2D and 3D U-Net. (A) The original image; (B) the label of the endometrium; and (C,D) show the segmentation results of 2D and 3D U-Net, respectively. 2D, two-dimensional; 3D, three-dimensional; U-net, U-shape network.

are shown in *Figure 6*, the original image in *Figure 6A*, the label of endometrium in *Figure 6B*, and the segmentation result of 2D and 3D U-net in *Figure 6C*,6D. *Table 1* shows the evaluation indexes of the two network segmentation models. The segmentation result of 2D U-Net had undersegmentation or over-segmentation, and its DSC was 64.04%, while the segmentation result of 3D U-Net was significantly improved, and its DSC reached 85.80%.

Segmentation of different preprocessing

Based on the 3D U-Net, we evaluated the segmentation

results of the OD, the augmented data (AD) obtained by the traditional augmentation method, the enhanced augmented data (EAD) obtained after image filtering, the patched data (PD) of the original image, and the enhanced patched data (EPD) obtained after image filtering. The final results are shown in *Table 2*. The DSC of the segmentation results obtained from OD and AD were 85.80% and 87.20%, respectively. On EAD, the segmentation result achieved the DSC of 90.83%, which was 5.03% and 3.63% higher than before. In the patch-based 3D U-Net, the segmentation result of the model based on PD was 81.66%, and that

Table 1 Evaluation of U-Net segmentation results

Index	2D U-Net	3D U-Net
DSC (%)	64.04	85.80
Jaccard (%)	50.43	75.33

2D U-net, two-dimensional U-shape network; 3D, threedimensional; DSC, dice similarity coefficient.

 Table 2 Segmentation evaluation of 3D U-Net on the different pre-processing datasets

Index	OD	AD	EAD	PD	EPD
DSC (%)	85.80	87.20	90.83	81.66	84.30
Jaccard (%)	75.33	78.20	83.35	70.00	73.30
Sensitivity (%)	83.71	85.05	90.85	75.39	79.89
HD95 (mm)	18.01	14.77	12.75	23.75	22.40

3D U-Net, three-dimensional U-shape network; OD, original data; AD, augmented data; EAD, enhanced augmented data; PD, patched data; EPD, enhanced patched data; DSC, dice similarity coefficient; HD95, 95th percentile Hausdorff distance.

based on EPD was 84.30%, with an increase of 2.64%. Overall, image filtering and the 3-channel integration with the enhanced images significantly improved the segmentation results. Compared with the patch-based method, the traditional augmentation method achieved better segmentation performance, and the DSC improved by 6.53%.

The segmentation results from different training datasets are shown in *Figure* 7, the original images in *Figure* 7*A*, the label of the endometrium in *Figure* 7*B*, the segmentation results training from OD, AD and EAD in *Figure* 7*C*, 7*D*,7*E*, the segmentation results trained from PD and EPD in *Figure* 7*F*,7*G*. The segmentation model training from EAD achieved the best endometrium segmentation result.

Endometrium thickness measurements

In this study, the endometrium thickness measurements were performed on the sagittal images of 15 cases in the testing set based on the segmentation results from EAD



Figure 7 Endometrium segmentation results of 3D U-Net from the different training datasets. (A) The original images; (B) the labels of the endometrium; (C-E) the segmentation results training from OD, AD, and EAD respectively; and (F,G) the segmentation results training from PD and EPD. 3D U-Net, three-dimensional U-shape network; OD, the origin data; AD, the augmented data; EAD, the enhanced augmented data; PD, the patched data; EPD, the enhanced patched data.

 Table 3 Endometrium thickness measurement evaluation

Index	MAE (mm)	RMSE (mm)	STD (mm)	<±2 mm (%)
Proposed method	0.75	1.07	0.80	94.20

MAE, mean absolute error; RMSE, root mean square error; STD, standard deviation.



Figure 8 Endometrium thickness measurement results. The orange line is the endometrial border, the yellow line represents the centerline of the endometrium, and the blue line represents the maximum thickness of the endometrium.

training model. At the same time, two experienced doctors were asked to manually measure the endometrium thickness of these 15 cases, which was regarded as the gold standard for evaluation. Mean absolute error (MAE), root mean square error (RMSE), and standard deviation (STD) were selected to evaluate the measurement error. The results are shown in *Table 3*. The calculation formulae of MAE, RMSE, and STD are as follows:

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y_i - \hat{y_i}|$$
[7]

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \widehat{y_i})^2}$$
[8]

$$STD = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \overline{y})^2}$$
[9]

where $\hat{y_i}$ and y_i represent the true value and predicted value, and \overline{y} represents the mean value of y_i .

The allowable measurement error range of endometrium thickness in clinical medicine is ± 2 mm. The experimental results show that 94.20% of the measurement results were within the error range based on the measurement method proposed in this paper. *Figure 8* shows the measurement results of the endometrium thickness based on 3D

U-Net segmentation, in which the red region shows the segmentation result of the endometrium, the orange line is the contour of the endometrium, the yellow line is the centerline of the endometrium, and the green line shows the maximum thickness of the endometrium.

Discussion

Most of the existing endometrium segmentation studies were conducted on 2D images, including using traditional image segmentation methods and deep learning methods. In this study, the segmentation results obtained by 2D U-Net were unsatisfactory, although the images were preprocessed and augmented. In contrast, the segmentation accuracy improved when using the 3D U-Net, and the DSC reached 90.83%, which is 26.79% higher than that of the 2D U-Net. The reason for the improvement is that the signal-to-noise ratio of the ultrasound image is relatively poor, and the morphology of the endometrium is irregular. In addition, 2D segmentation ignores the information between the image slices, so 3D segmentation results are significantly better than those of 2D segmentation. Finally, we compared the proposed method with the existing endometrium segmentation methods, as shown in Table 4.

When using 3D U-Net for endometrium segmentation,

Study	Method	Case number	Image number	Input image size	Dice (%)	Jaccard (%)	Thickness <±2 mm (%)
Hu <i>et al</i> . (28)	2D VGG-based U-Net	91	1,031	192×256	85.30	-	87.50
Singhal et al. (31)	2D deep learned snake	59	330	200×200	-	-	87.00
Park <i>et al</i> . (32)	2D segmentation framework with a discriminator	-	3,372	256×320	82.67	70.46	-
This study	3D U-Net	85	2,480	224×224×32	90.83	83.35	94.20

Table 4 The comparison of endometrium segmentation and thickness measurement

2D VGG-based U-Net, two-dimensional visual geometry group based on U-shape network; 3D U-Net, three-dimensional U-shape network.

we compared the traditional data augmentation and patchbased methods. The experimental results showed that the DSC of the traditional data augmentation method (EAD) was 90.83%, while the patch-based method (EPD) was only 84.30%. The analysis showed that the patch-based augmentation method had an excellent segmentation effect for normal endometrium. However, for endometrium with adhesion, although the extraction of the patches can increase the sample size, the patch only contains local information, which leads to missing or having difficulty distinguishing the local edge and results in incomplete segmentation or over-segmentation.

In addition, we used a 3-fold cross-validation method to verify the optimal model based on EAD as the final uterine image preprocessing method and 3D U-Net as the final uterine segmentation network. First, 18% of data (15 cases) were randomly selected as the test set. Then, the remaining data were randomly divided into three parts of the same number, two of which were used for training and the other for verification. This process was carried out in turn, and then we obtained the optimal model, which was trained with data other than the test set to obtain the final segmentation model. Finally, the segmentation performance of the model was evaluated on the test set, and the results achieved DSC coefficient of 89.1% and STD value of 0.0296. Compared with the previous test results (DSC coefficient of 90.83%, STD value of 0.0325), the Dice coefficient of the optimal model was slightly reduced, but the STD value was improved. The segmentation accuracy of the optimal model was guaranteed, and the stability of the test results were improved.

An essential purpose of endometrium segmentation is to measure the endometrium thickness. Therefore, the segmentation results directly affect the accuracy of the thickness measurement. This study compared the automatic measurement of endometrium thickness based on different segmentation results. The experimental results showed that the accuracy of endometrium thickness measurement was highest used 3D U-Net segmentation training from EAD, 94.20% of the measurement results are within the error range, and only a few data have relatively large thickness measurement errors due to their blurred endometrium boundary and severe endometrial damage. We compared the proposed method with the existing endometrium thickness measurement methods, as shown in *Table 4*.

In this study, the endometrium thickness was calculated on sagittal images, which is consistent with the measurement method of doctors. The method was applied in the clinical process for experimental testing. Next, we will try to measure the thickness of the endometrium based on 3D segmentation results to provide further assistance to physicians. In addition, there were some poor-quality images encountered during the data collection process, which are shown in Figure 9. For these poor-quality images, an experienced doctor also has difficulty providing representative criteria for segmentation. Therefore, the poor-quality images were excluded from the datasets. The segmentation of the poor-quality images will be discussed with doctors subsequently. Moreover, the experimental datasets in this paper were obtained from a single source with limited access to data. In future work, we can obtain more data samples to train and test the model.

Conclusions

This paper presents an automatic endometrium segmentation method based on 3D U-Net and demonstrates an endometrial thickness measurement method. The experimental results show that the segmentation model training from traditional data augmentation and image filtering processing (EAD) achieves the best performance, reaching DSC of 90.83%, which is higher than patch-based 3D U-Net and 2D U-Net. Based on the segmentation results, the MAE and RMSE of the automatic endometrium



Figure 9 Coronal section images of poor-quality images.

thickness measurement were 0.75 and 1.07 mm. A total of 94.20% of the measurement results in the testing dataset were within the allowable error range of clinical medicine. Therefore, the proposed method in this paper can effectively help doctors in their diagnostic decision making.

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Footnote

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Conflicts of Interest: All authors have completed the ICMJE uniform disclosure form (available at https://qims. amegroups.com/article/view/10.21037/qims-21-1155/coif). The authors report that this work was supported by the National Natural Science Foundation of China (NSFC) under grant number 61873257 and the Guizhou Province Science and Technology Project under grant number Qiankehezhicheng [2019] 2794. The authors have no other conflicts of interest to declare.

Ethical Statement: The authors are accountable for all aspects of the work in ensuring that questions related to the accuracy or integrity of any part of the work are appropriately investigated and resolved. The study

was conducted in accordance with the Declaration of Helsinki (as revised in 2013). The study was approved by the Institutional Review Board of Shengjing Hospital of China Medical University, and individual consent for this retrospective analysis was waived.

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4108